

# **Physically-Based Animation and PDEs**

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**Computer Graphics  
CMU 15-462/15-662**

# Last time: Optimization

- **Graphics as optimization**
- **Many complex criteria/constraints**
- **Technique: numerical optimization**
  - **pick initial guess**
  - **ski downhill**
  - **keep fingers crossed!**
- **Today: return to differential equations**
  - **saw ODEs—derivatives in time**
  - **now PDEs—also have derivatives in space**
  - **describe many natural phenomena (water, smoke, cloth, ...)**
  - **recent revolution in CG/visual effects**





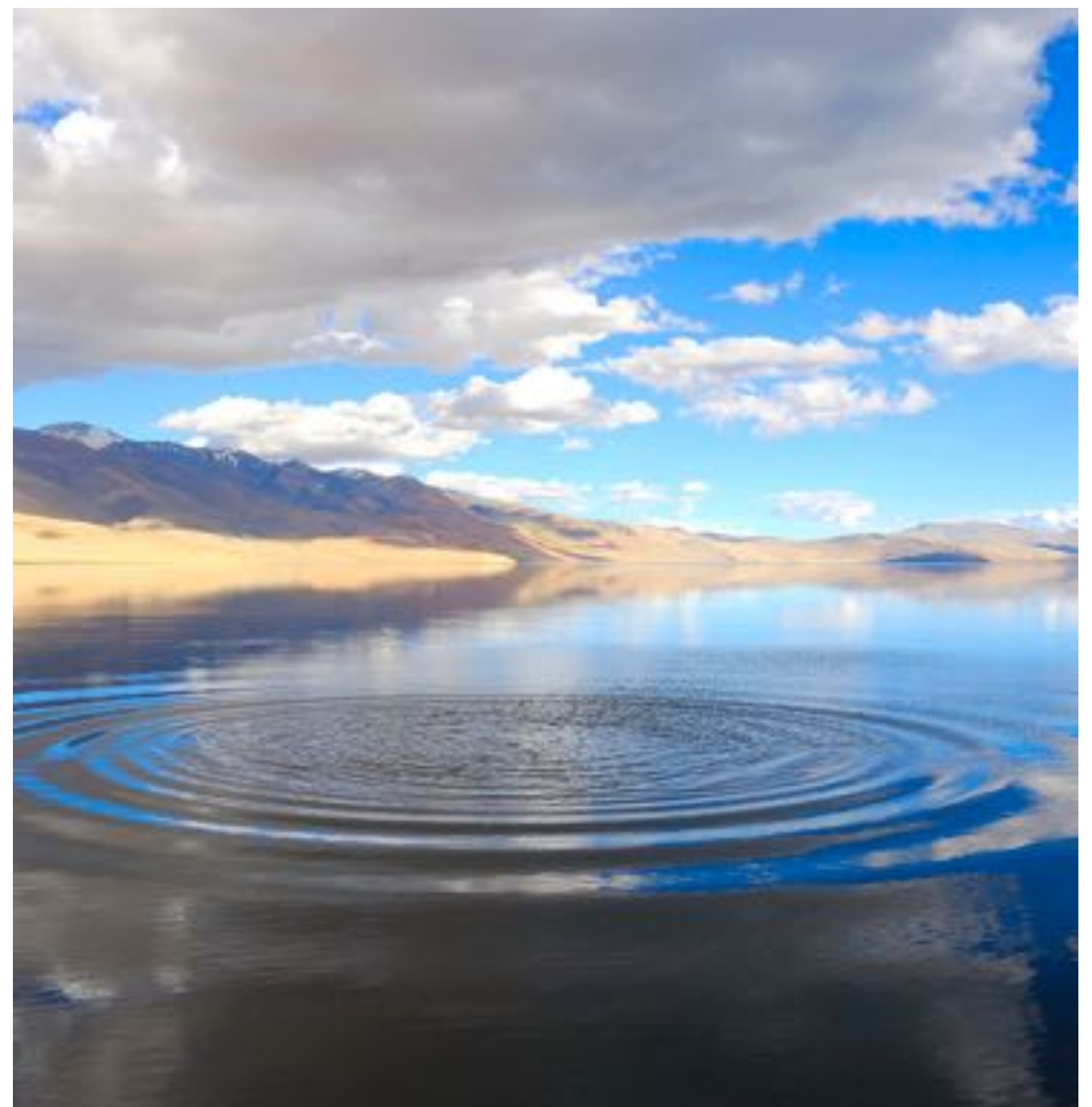
# Partial Differential Equations (PDEs)

- **ODE: Implicitly describe function in terms of its time derivatives**
- **Like any implicit description, have to solve for actual function**
- **PDE: Also include space derivatives in description**

**ODE—rock flies through air**



**PDE—rock lands in pond**



# To make a long story short...

- Solving ODE looks like “add a little velocity each time”

$$q_{k+1} = q_k + \tau f(q)$$

- Solving a PDE looks like “take weighted combination of neighbors to get velocity (...and add a little velocity each time)”

	1	
1	-4	1
	1	

$f(q)$

$$q_{k+1} = q_k + \tau f(q)$$

**...obviously there is a lot more to say here!**

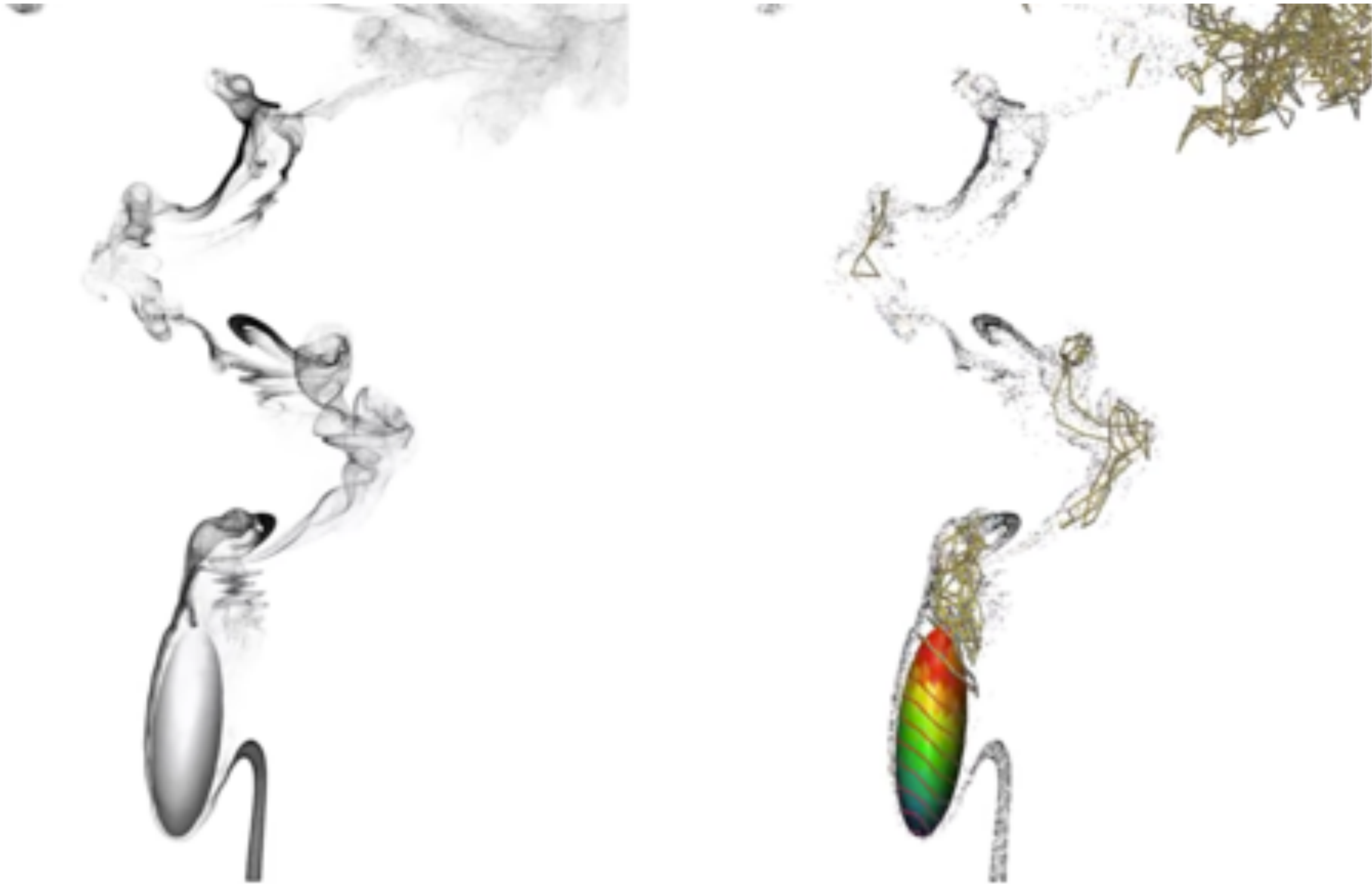
# Liquid Simulation in Graphics



Losasso, F., Shinar, T. Selle, A. and Fedkiw, R., "Multiple Interacting Liquids"



# Smoke Simulation in Graphics



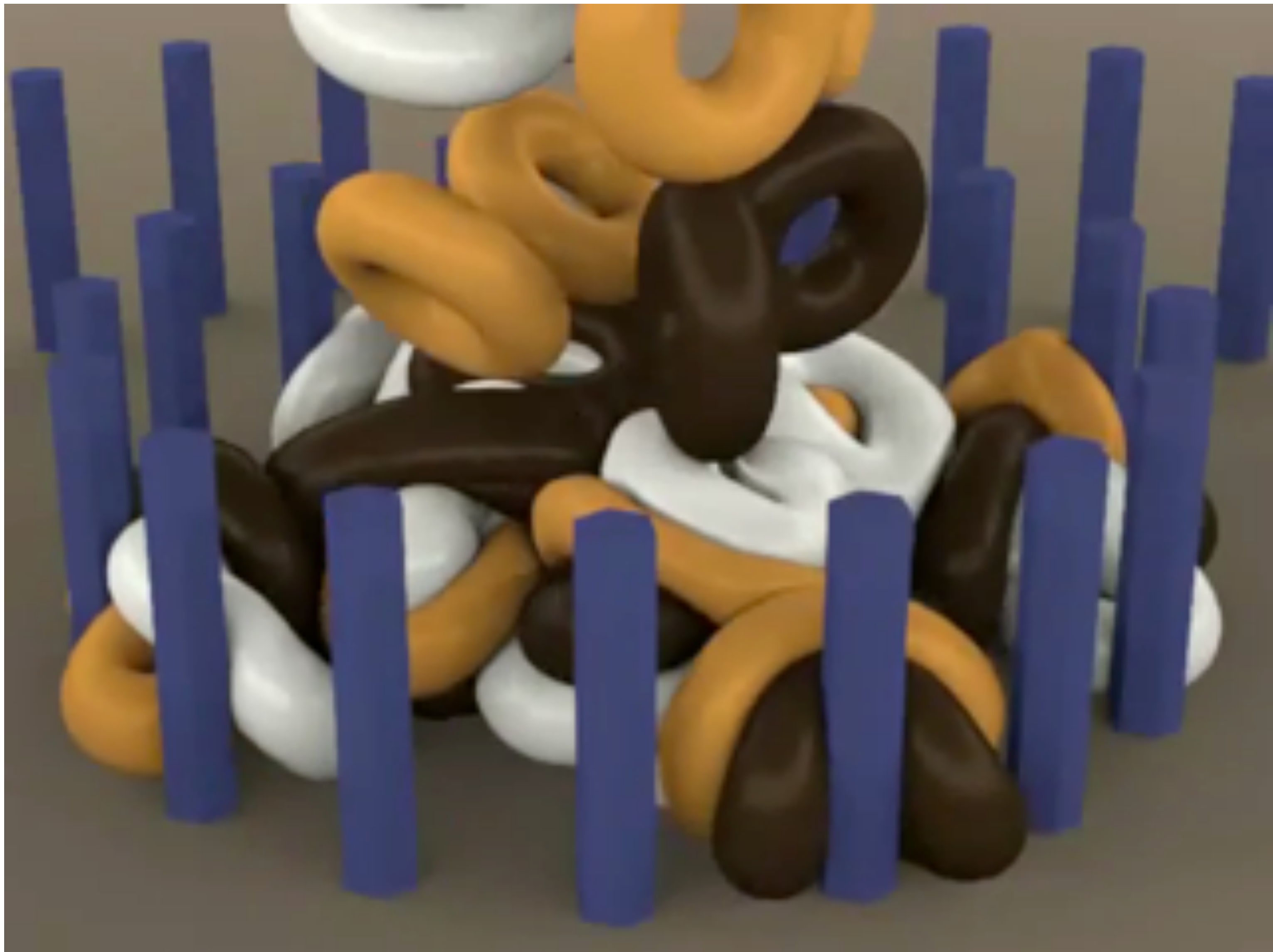
S. Weißmann, U. Pinkall. "Filament-based smoke with vortex shedding and variational reconnection"

# Cloth Simulation in Graphics



**Zhili Chen, Renguo Feng and Huamin Wang, "Modeling friction and air effects between cloth and deformable bodies"**

# Elasticity in Graphics



Irving, G., Schroeder, C. and Fedkiw, R., "Volume Conserving Finite Element Simulation of Deformable Models"

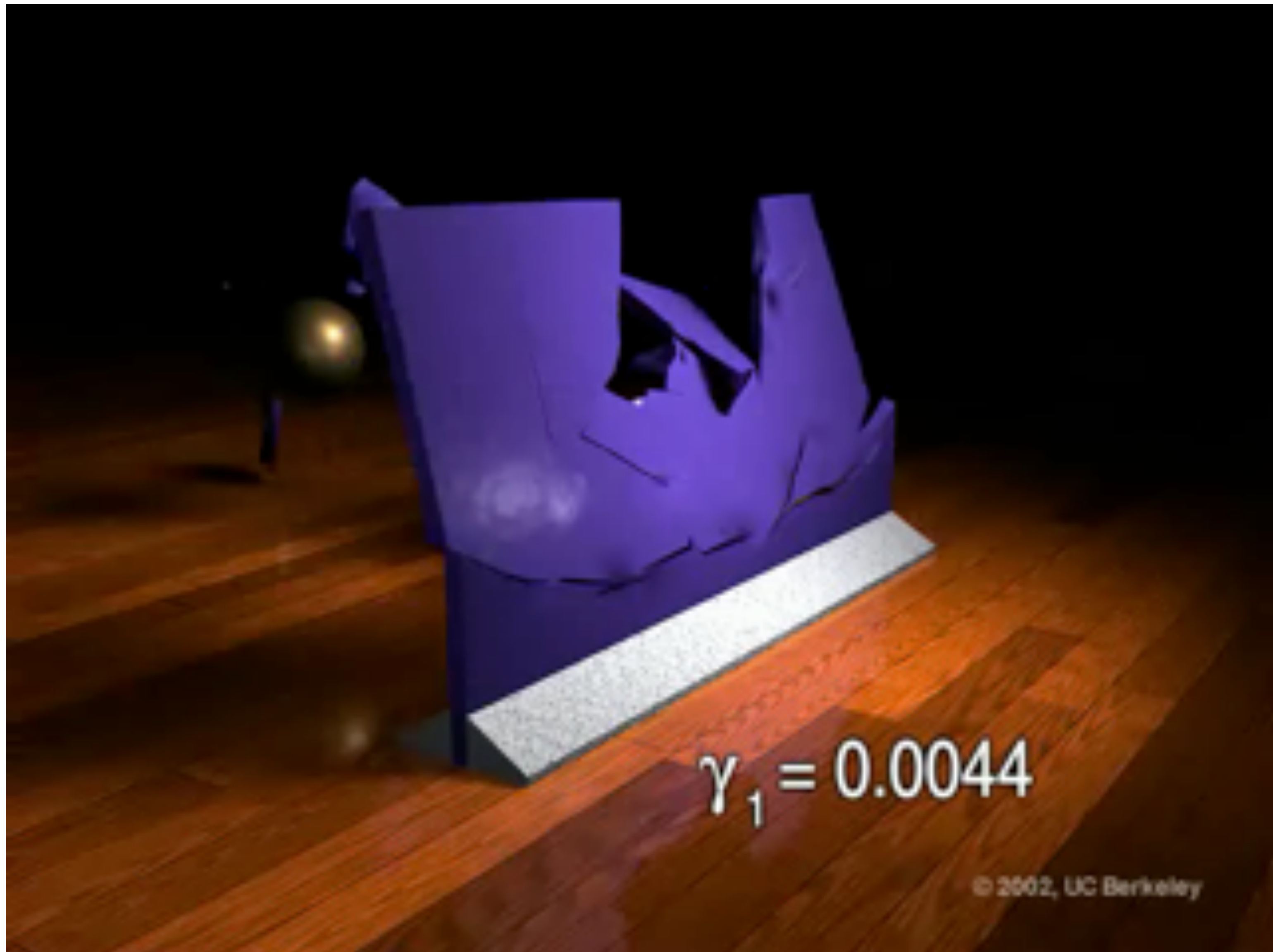


# Hair Simulation in Graphics



**Danny M. Kaufman, Rasmus Tamstorf, Breannan Smith, Jean-Marie Aubry, Eitan Grinspun,  
"Adaptive Nonlinearity for Collisions in Complex Rod Assemblies"**

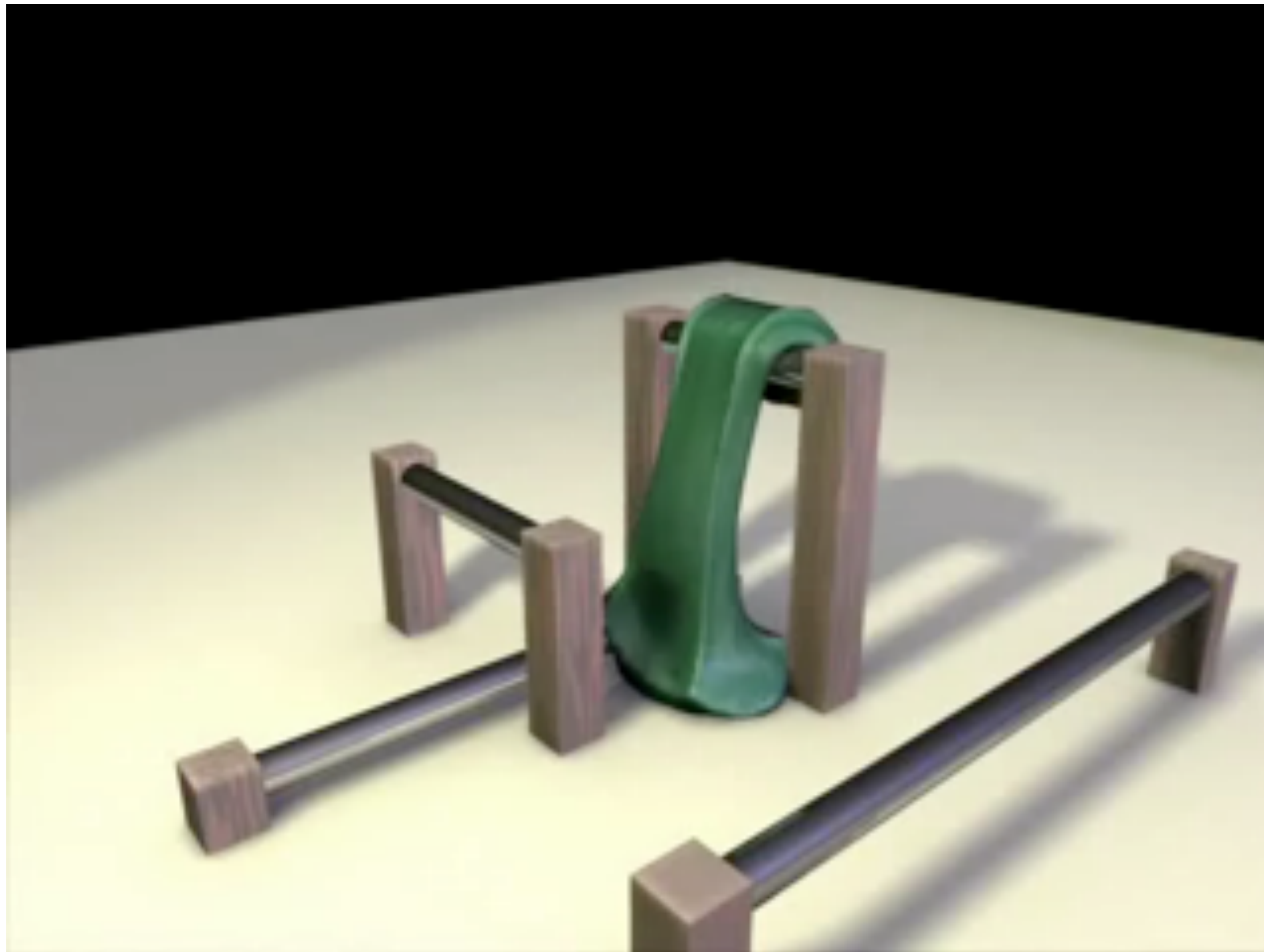
# Fracture in Graphics



James F. O'Brien, Adam Bargteil, Jessica Hodgins, "Graphical Modeling and Animation of Ductile Fracture"



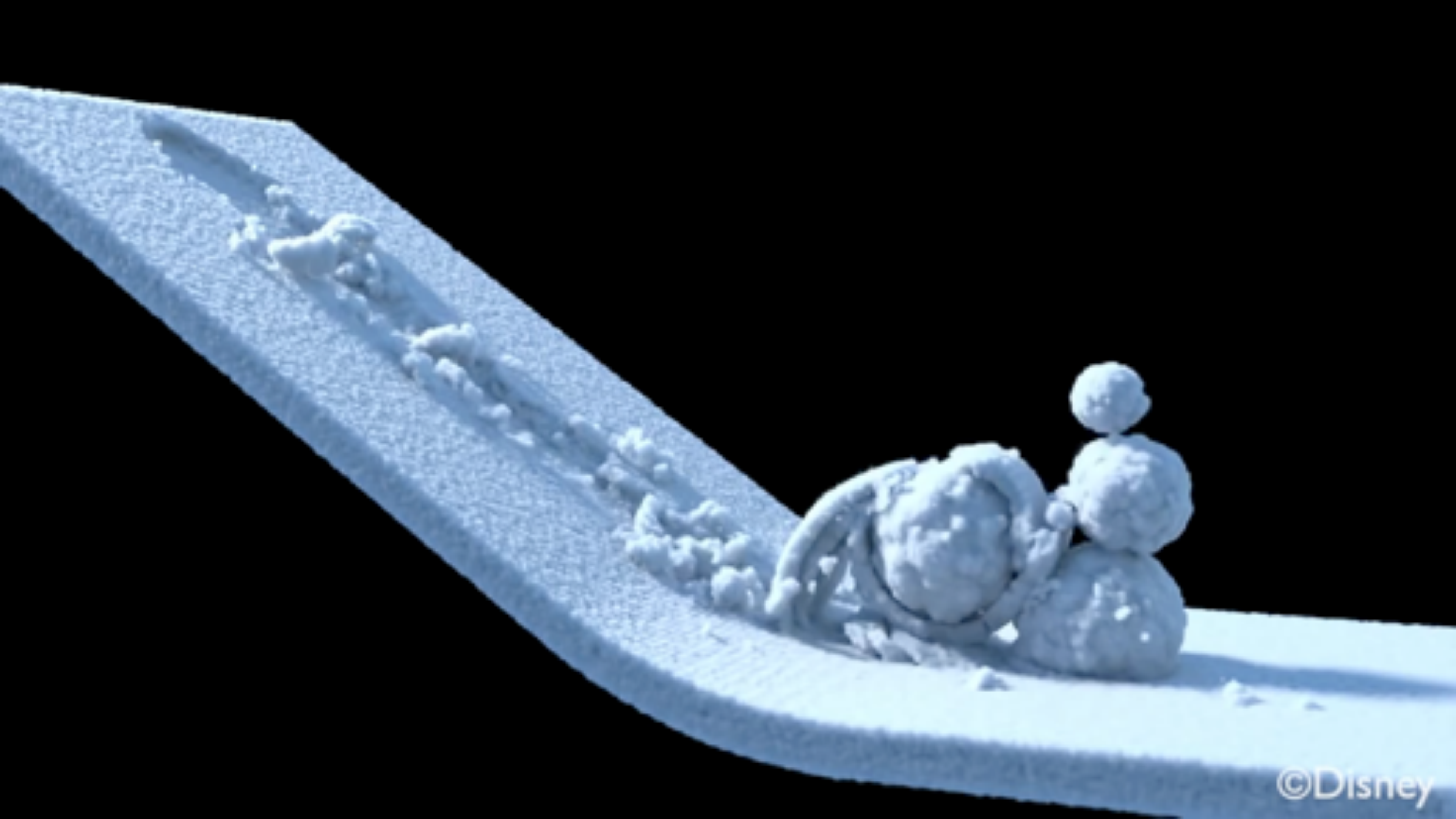
# Viscoelasticity in Graphics



Chris Wojtan, Greg Turk, "Fast Viscoelastic Behavior with Thin Features"



# Snow Simulation in Graphics



Alexey Stomakhin, Craig Schroeder, Lawrence Chai, Joseph Teran, Andrew Selle, "A Material Point Method For Snow Simulation"

# Definition of a PDE

- Want to solve for a function of time and space

$$u(t, x)$$

time      space

- Function given implicitly in terms of derivatives:

$$\dot{u}, \ddot{u}, \frac{d}{dt^3} u, \frac{d}{dt^4} u, \dots$$

any combination of time derivatives

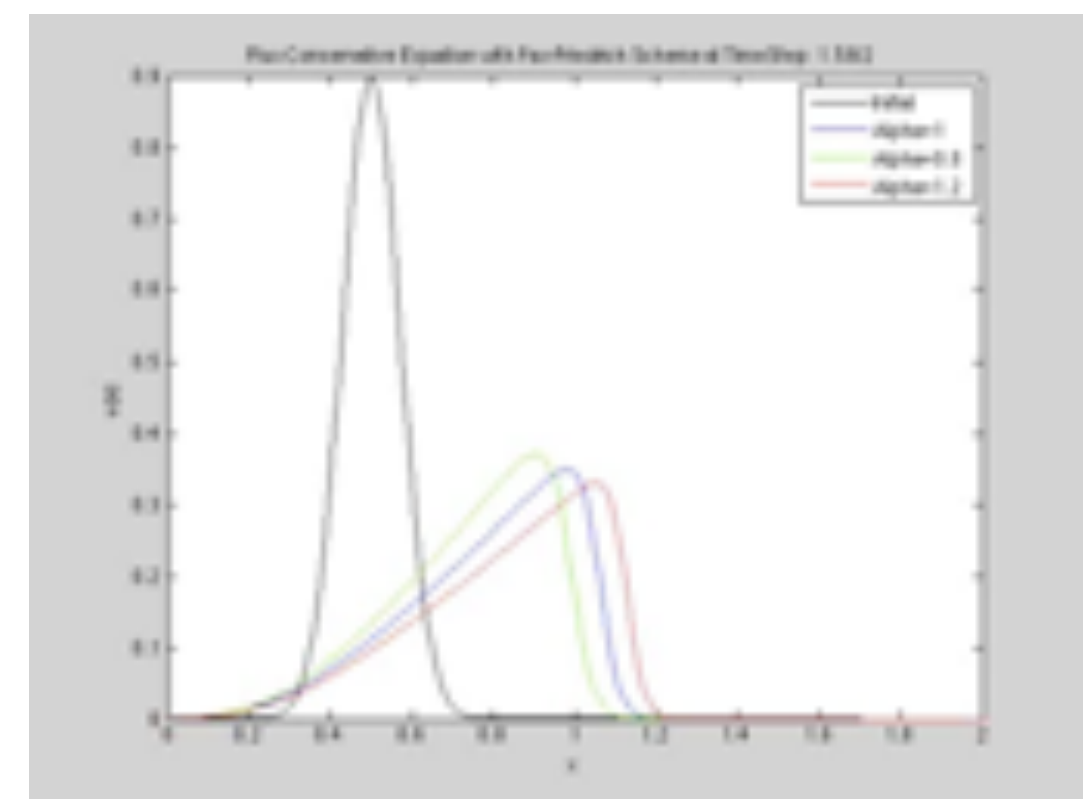
$$\frac{\partial u}{\partial x_1}, \frac{\partial u}{\partial x_2}, \frac{\partial^2 u}{\partial x_1 \partial x_2}, \frac{\partial^m + n u}{\partial x_i^m \partial x_j^n}, \dots$$

plus any combination of space derivatives

- Example:

$$\dot{u} + uu' = au''$$

(Burgers' equation)



# Anatomy of a PDE

- Linear vs. nonlinear: how are derivatives combined?

**nonlinear!**

$$\dot{u} + u u' = a u'' \quad \text{(Burgers' equation)}$$

$$\dot{u} = a u'' \quad \text{(diffusion equation)}$$

- Order: how many derivatives in space & time?

1st order in time 2nd order in space

$$\dot{u} + u u' = a u'' \quad \text{(Burgers' equation)}$$

2nd order in time 2nd order in space

$$\ddot{u} = a u'' \quad \text{(wave equation)}$$

- Nonlinear / higher order  $\Rightarrow$  HARDER TO SOLVE!



# Model Equations

- Fundamental behavior of many important PDEs is well-captured by three model linear equations:

**LAPLACE EQUATION (“ELLIPTIC”)**  $\Delta u = 0$

“Laplacian” (more later!)

“what’s the smoothest function interpolating the given boundary data”

**HEAT EQUATION (“PARABOLIC”)**  $\dot{u} = \Delta u$

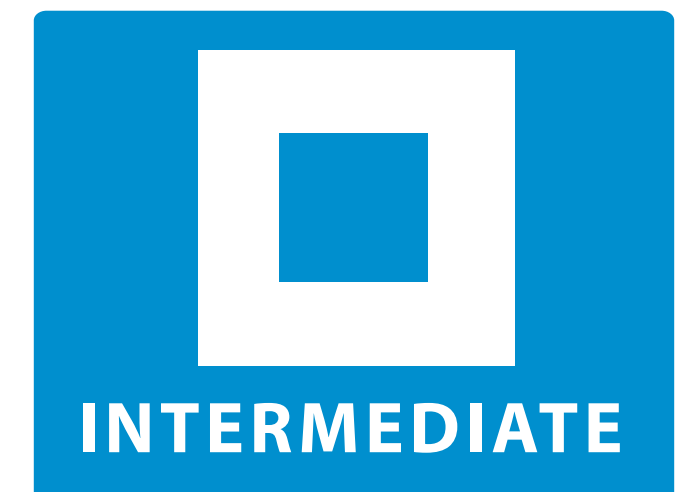
“how does an initial distribution of heat spread out over time?”

**WAVE EQUATION (“HYPERBOLIC”)**  $\ddot{u} = \Delta u$

“if you throw a rock into a pond, how does the wavefront evolve over time?”

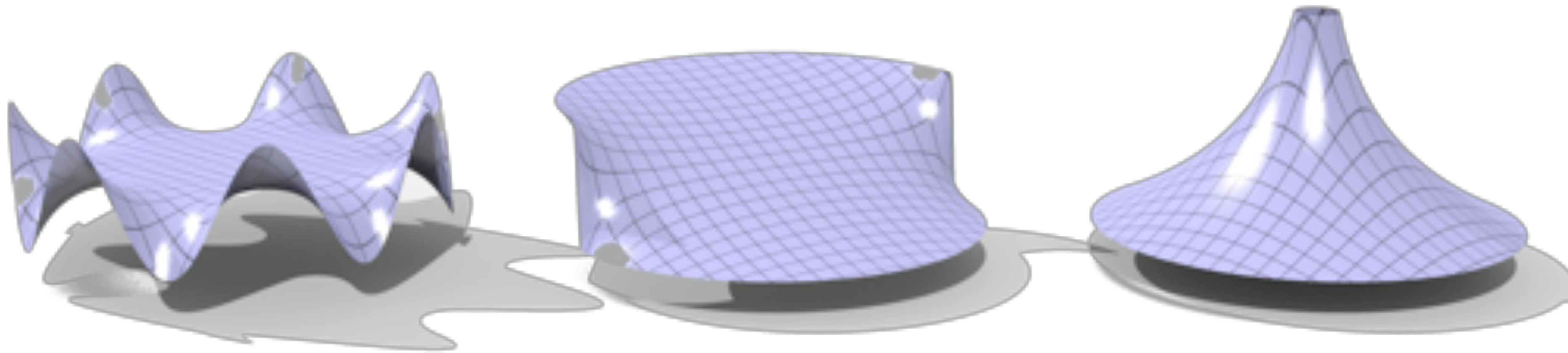
[ NONLINEAR + HYPERBOLIC + HIGH-ORDER ]

Solve numerically?



# Elliptic PDEs / Laplace Equation

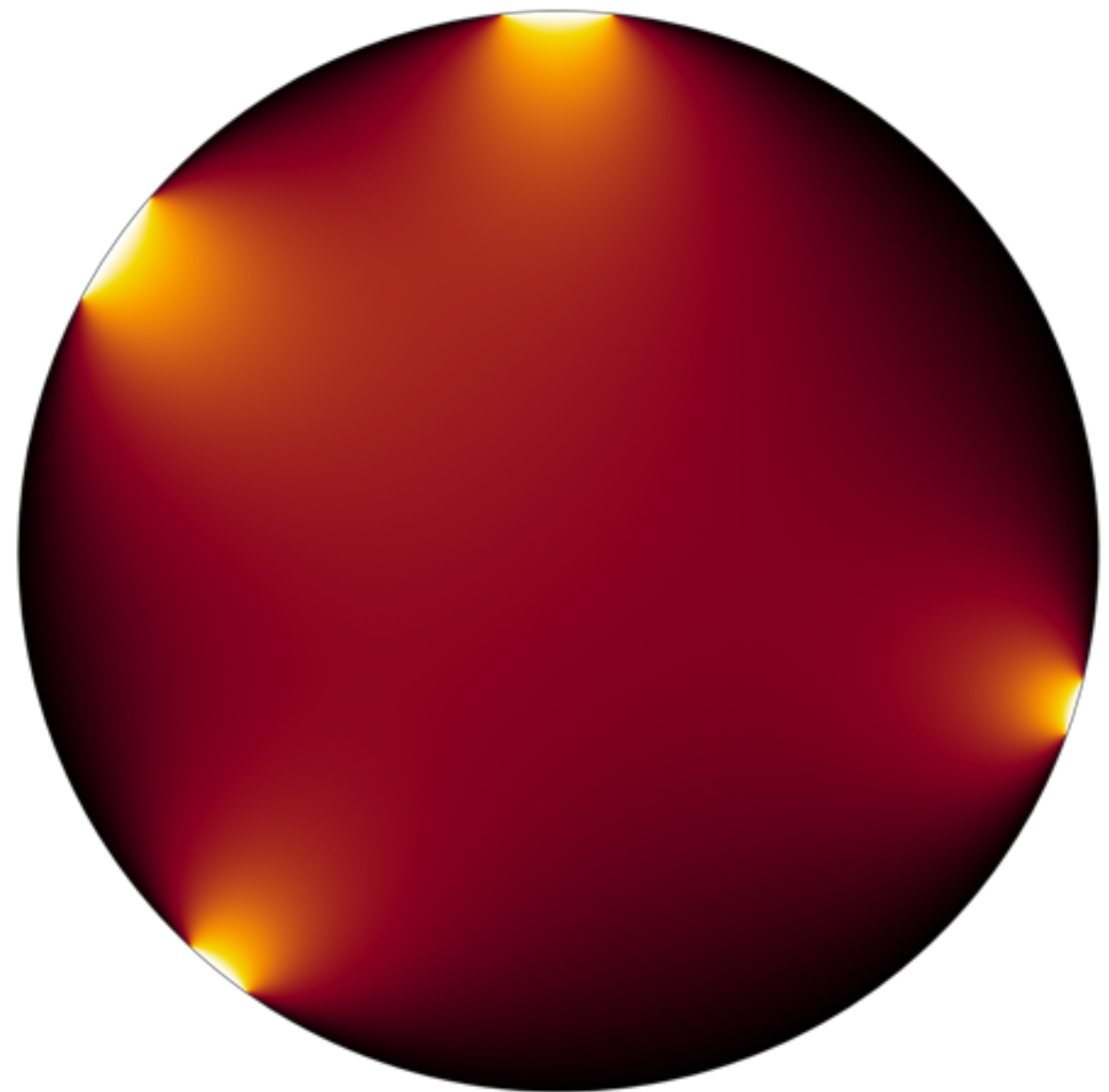
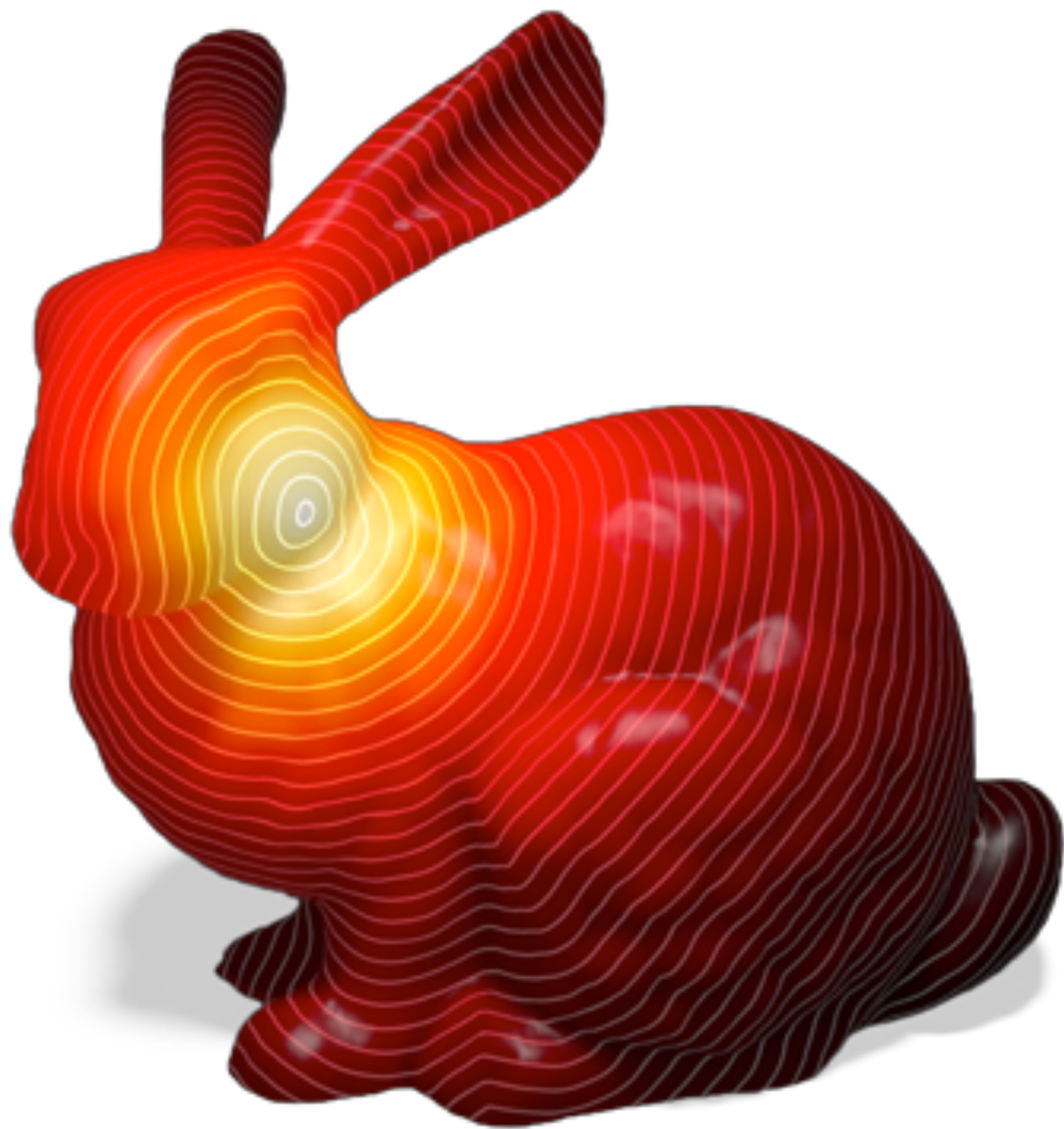
- **“What’s the smoothest function interpolating the given boundary data?”**



- **Conceptually: each value is at the average of its “neighbors”**
- **Roughly speaking, why is it easier to solve?**
- **Very robust to errors: just keep averaging with neighbors!**

# Parabolic PDEs / Heat Equation

- “How does an initial distribution of heat spread out over time?”



- After a long time, solution is same as Laplace equation!
- Models damping / viscosity in many physical systems



# Hyperbolic PDEs / Wave Equation

- **“If you throw a rock into a pond, how does the wavefront evolve over time?”**



- **Errors made at the beginning will persist for a long time! (hard)**

**How did we do that?**

# Numerical Solution of PDEs—Overview

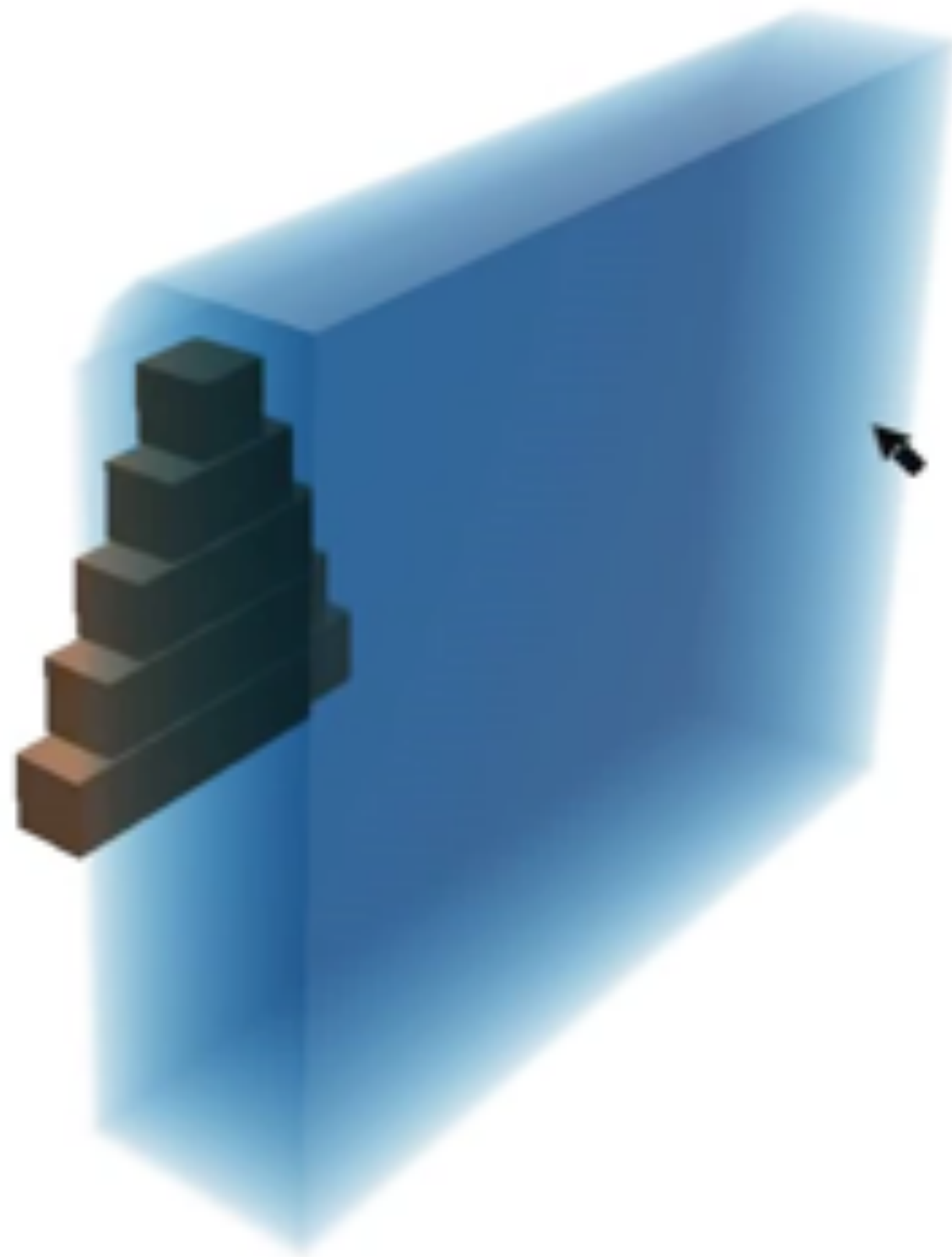
- Like ODEs, many interesting PDEs are difficult/impossible to solve analytically—especially if we want to incorporate data (e.g., user interaction)
- Must instead use numerical integration
- Basic strategy:
  - pick a time discretization (forward Euler, backward Euler...)
  - pick a spatial discretization (TODAY)
  - as with ODEs, run a time-stepping algorithm
- Historically, very expensive—only for “hero shots” in movies
- Computers are ever faster...
- More & more use of PDEs in games, interactive tools, ...



# Real Time PDE-Based Simulation (Fire)



# Real Time PDE-Based Simulation (Water)

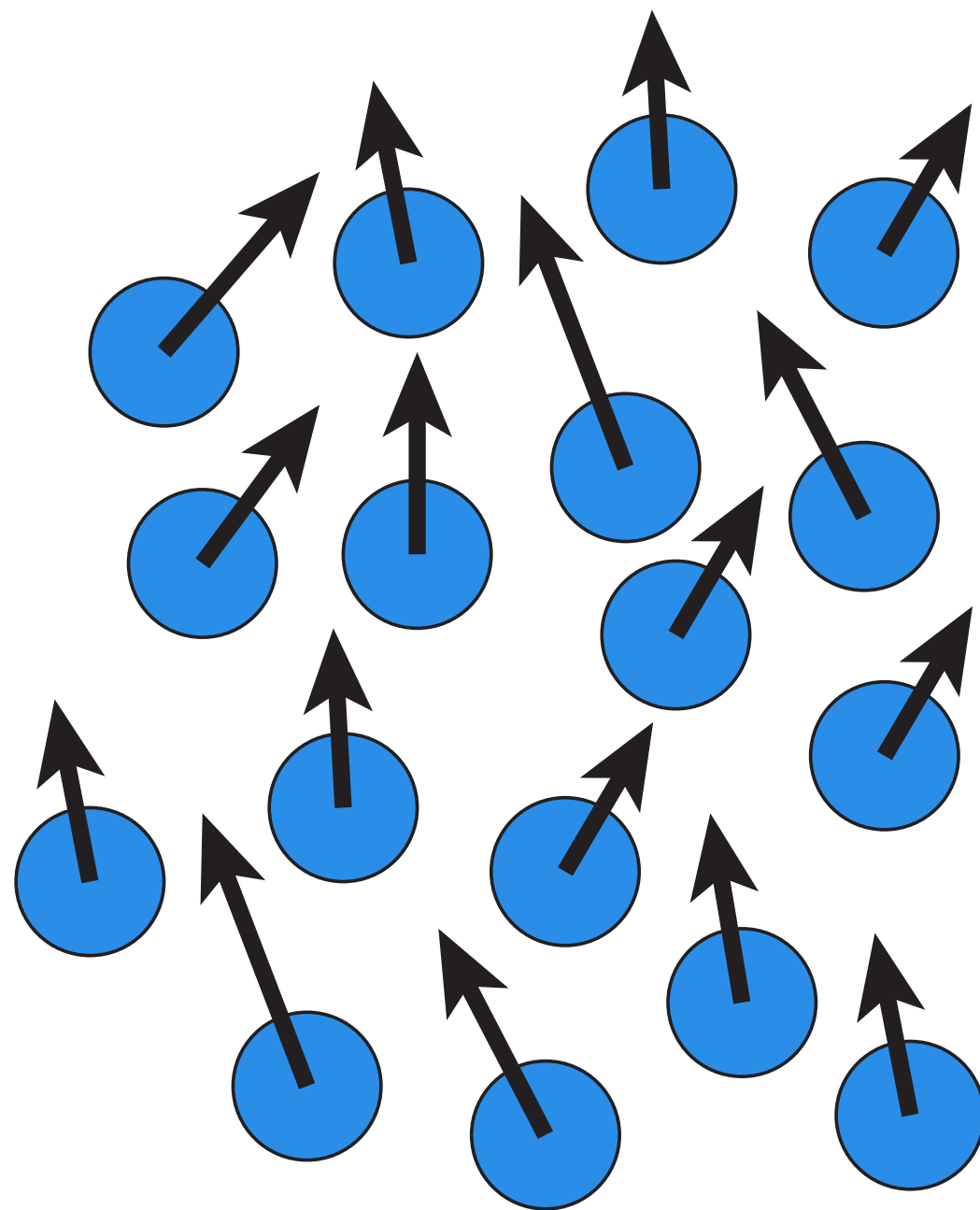


Nuttapong Chentanez, Matthias Müller, "Real-time Eulerian water simulation using a restricted tall cell grid"

# Lagrangian vs. Eulerian

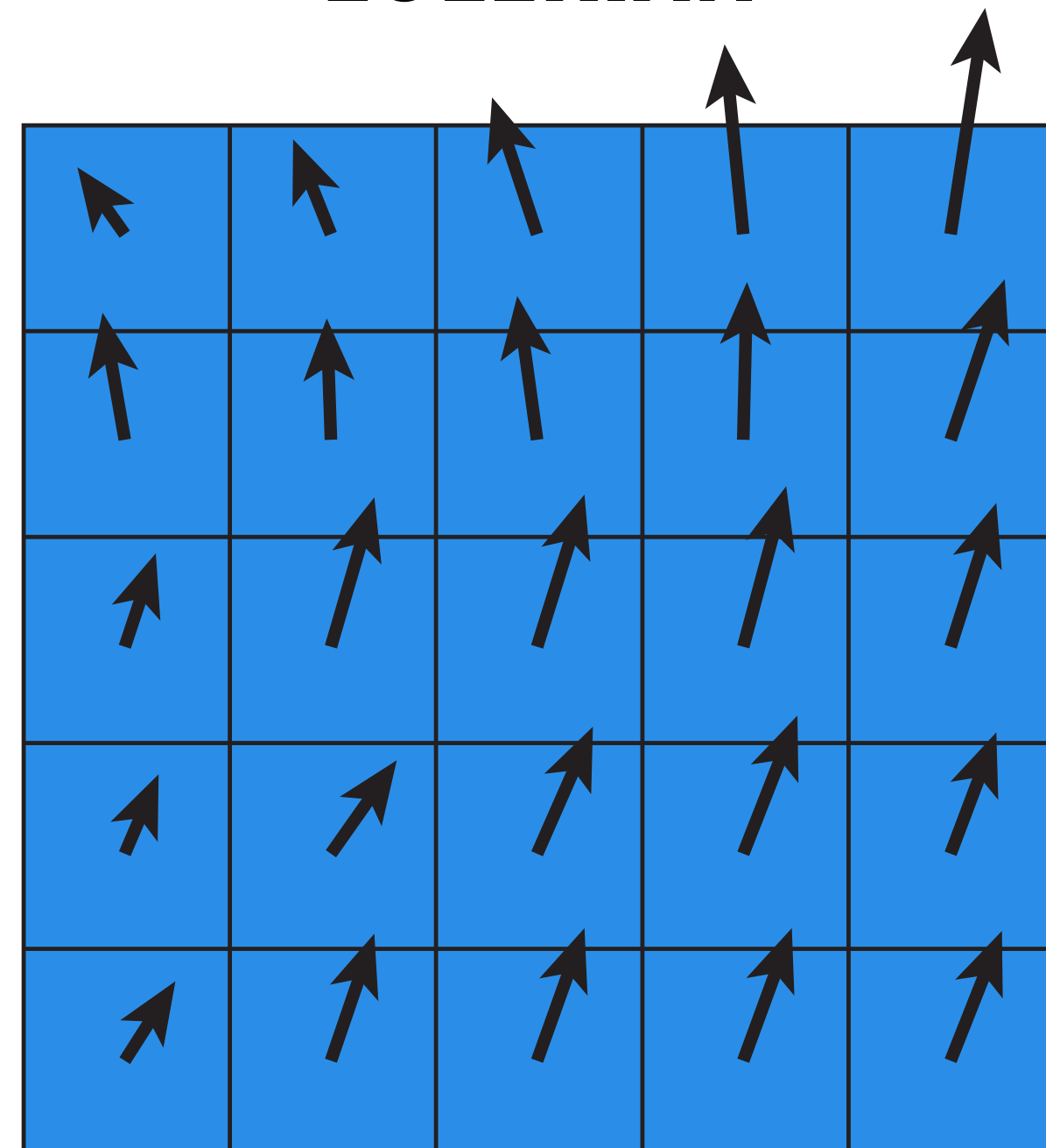
- Two basic ways to discretize space: Lagrangian & Eulerian
- E.g., suppose we want to encode the motion of a fluid

## LAGRANGIAN



**track position & velocity  
of moving particles**

## EULERIAN



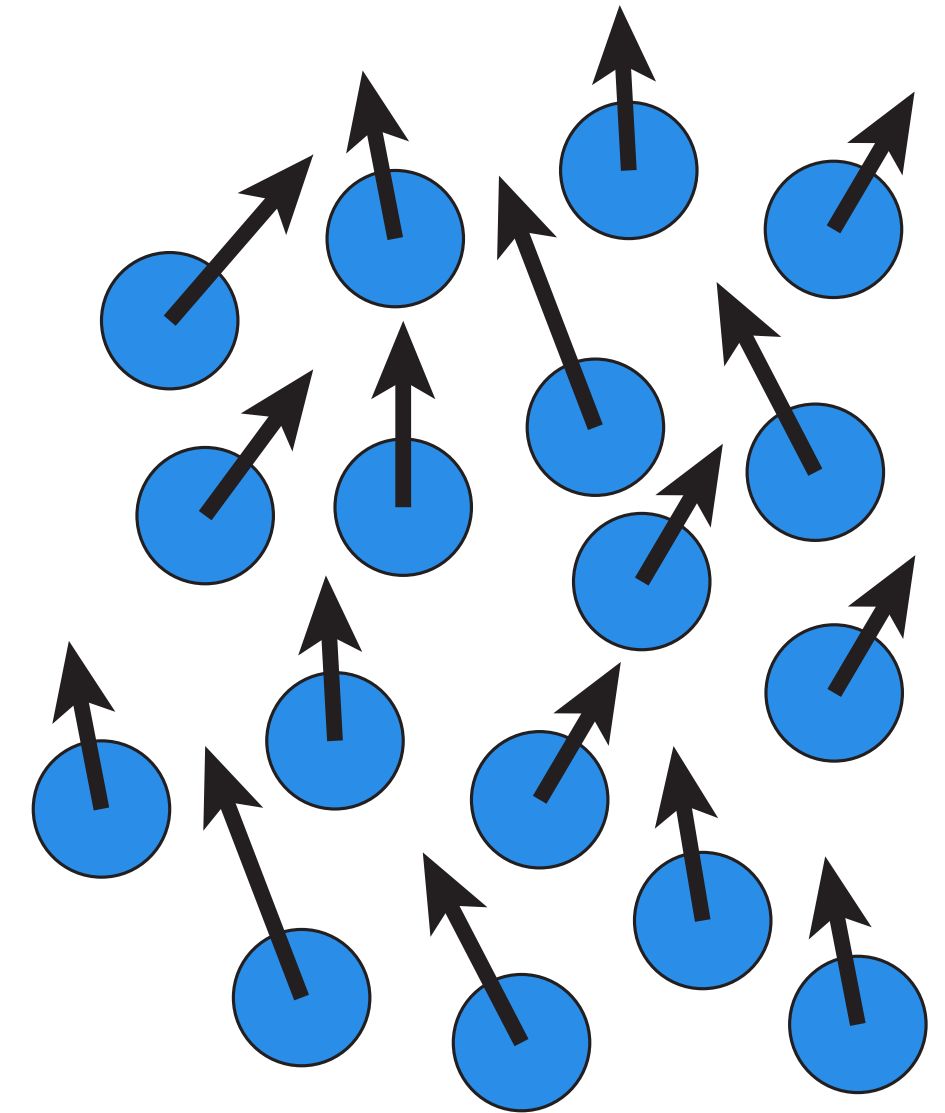
**track velocity (or flux)  
at fixed grid locations**



# Lagrangian vs. Eulerian—Trade-Offs

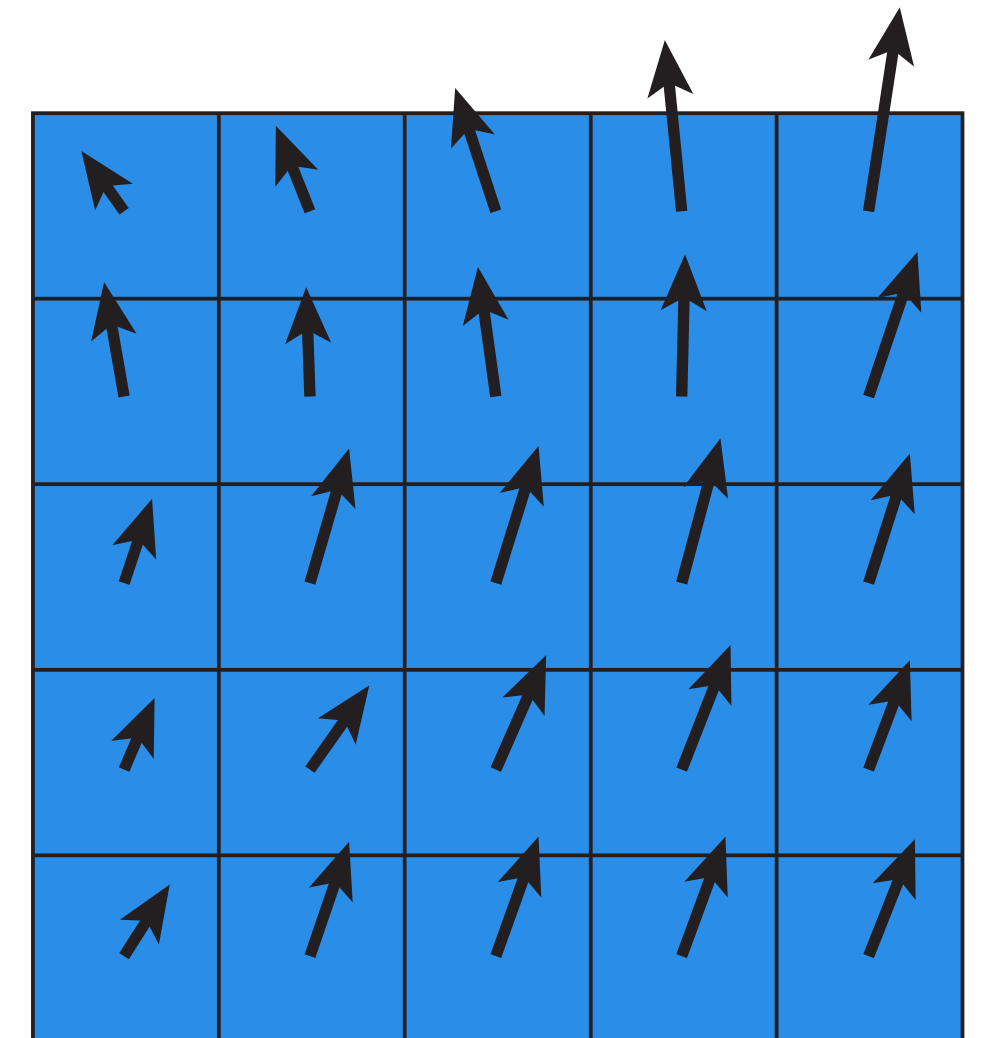
## ■ Lagrangian

- **conceptually easy (like polygon soup!)**
- **resolution/domain not limited by grid**
- **good particle distribution can be tough**
- **finding neighbors can be expensive**



## ■ Eulerian

- **fast, regular computation**
- **easy to represent, e.g., smooth surfaces**
- **simulation “trapped” in grid**
- **grid causes “numerical diffusion” (blur)**
- **need to understand PDEs (but you will!)**



# Mixing Lagrangian & Eulerian

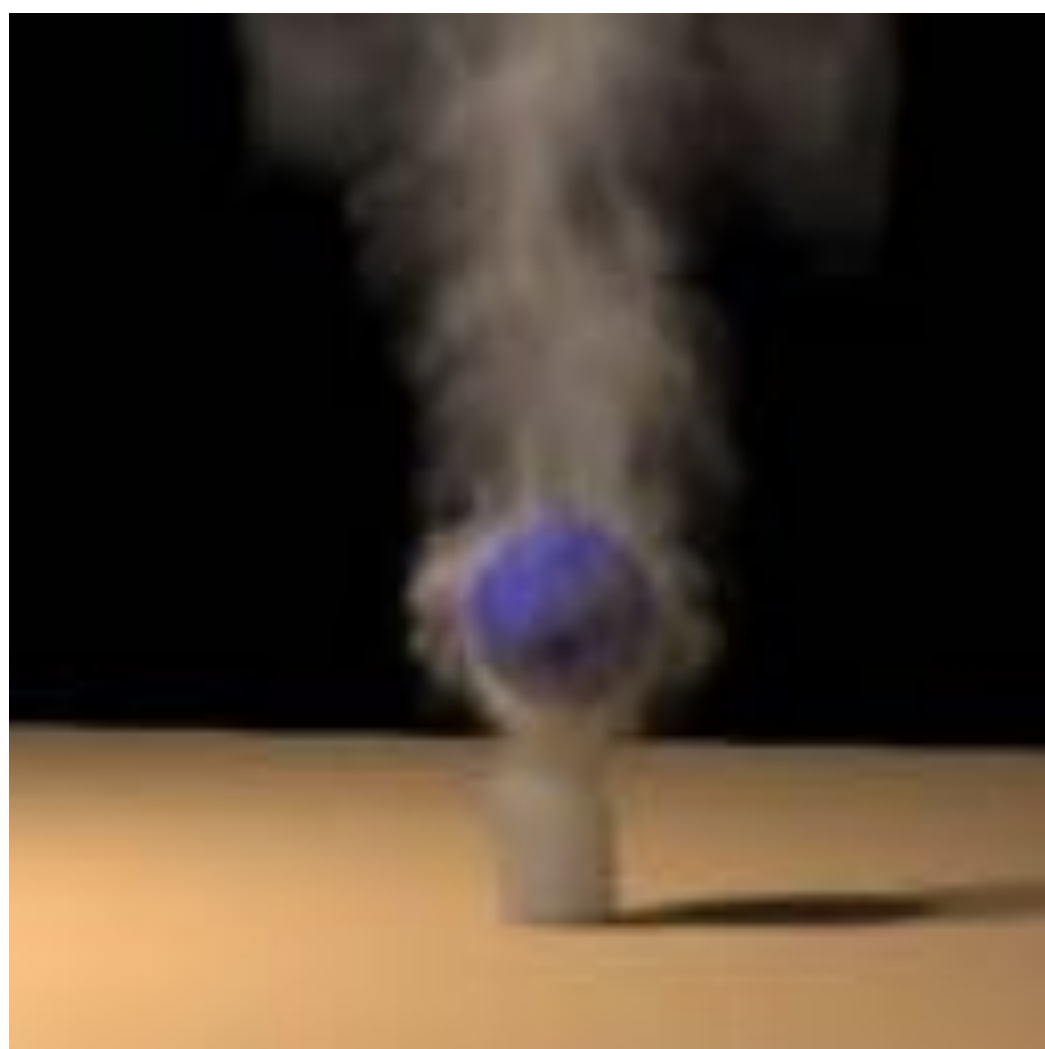
- Of course, no reason you have to choose just one!
- Many modern methods mix Lagrangian & Eulerian:
  - PIC/FLIP, particle level sets, mesh-based surface tracking, Voronoi-based, arbitrary Lagrangian-Eulerian (ALE), ...
- Pick the right tool for the job!

Maya Bifrost



# Aside: Which Quantity Do We Solve For?

- Many PDEs have mathematically equivalent formulations in terms of different quantities
- E.g., incompressible fluids:
  - velocity—how fast is each particle moving?
  - vorticity—how fast is fluid “spinning” at each point?
- Computationally, can make a big difference
- Pick the right tool for the job!





**Ok, but we're getting way ahead of ourselves.  
How do we solve easy PDEs?**

# Numerical PDEs—Basic Strategy

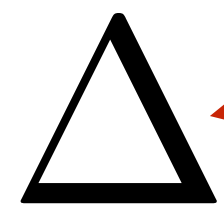
- **Pick PDE formulation**
  - Which quantity do we want to solve for?
  - E.g., velocity or vorticity?
- **Pick spatial discretization**
  - How do we approximate derivatives in space?
- **Pick time discretization**
  - How do we approximate derivatives in time?
  - When do we evaluate forces?
  - Forward Euler, backward Euler, symplectic Euler, ...
- **Finally, we have an update rule**
- **Repeatedly solve to generate an animation**



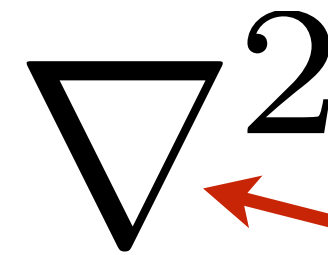
**Richard Courant**

# The Laplace Operator

- All of our model equations used the Laplace operator
- Different conventions for symbol:



← same symbol used for “change”



← same symbol used for Hessian!

- Unbelievably important object showing up everywhere across physics, geometry, signal processing, ...
- Ok, but what does it mean?
- Differential operator: eats a function, spits out its “2nd derivative”

- What does that mean for a function  $u: \mathbb{R}^n \rightarrow \mathbb{R}$ ?

$$\Delta u = \overset{\text{div}}{\nabla} \cdot \overset{\text{grad}}{\nabla} u$$

- divergence of gradient

- sum of second derivatives

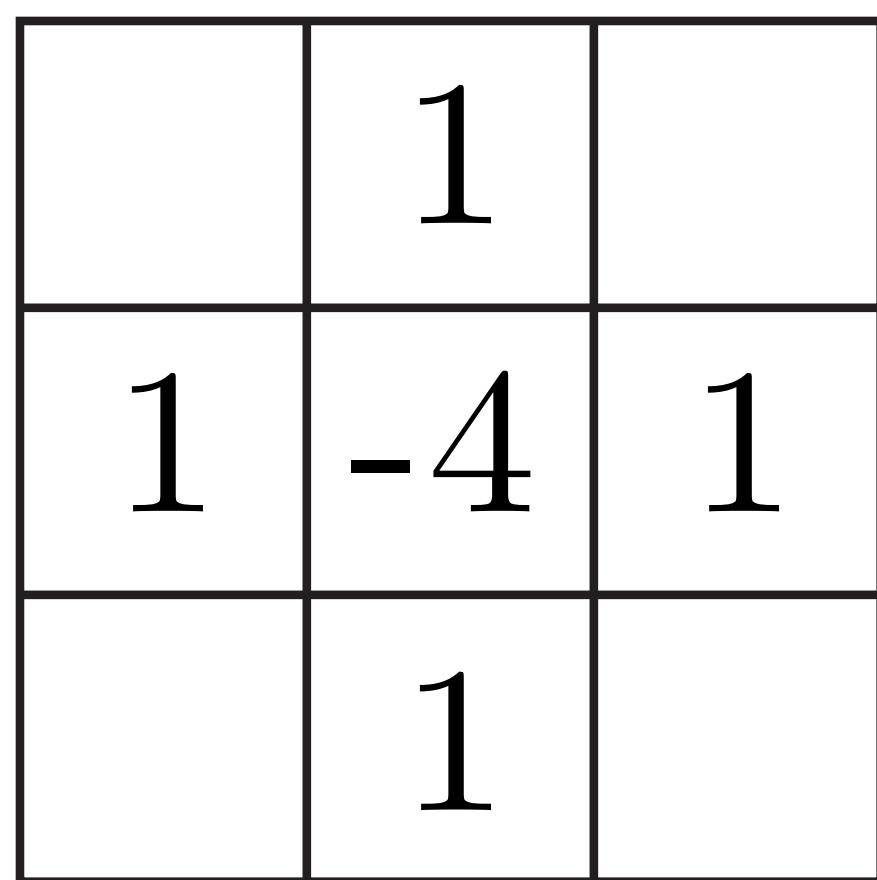
$$\Delta u = \frac{\partial^2 u}{\partial x_1^2} + \dots + \frac{\partial^2 u}{\partial x_n^2}$$



# Discretizing the Laplacian

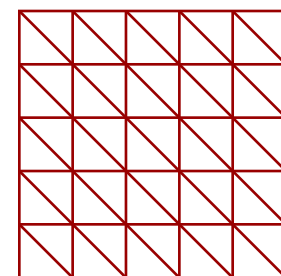
- How do we approximate the Laplacian?
- Depends on discretization (Eulerian, Lagrangian, grid, mesh, ...)
- Two extremely common ways in graphics:

GRID  $h$

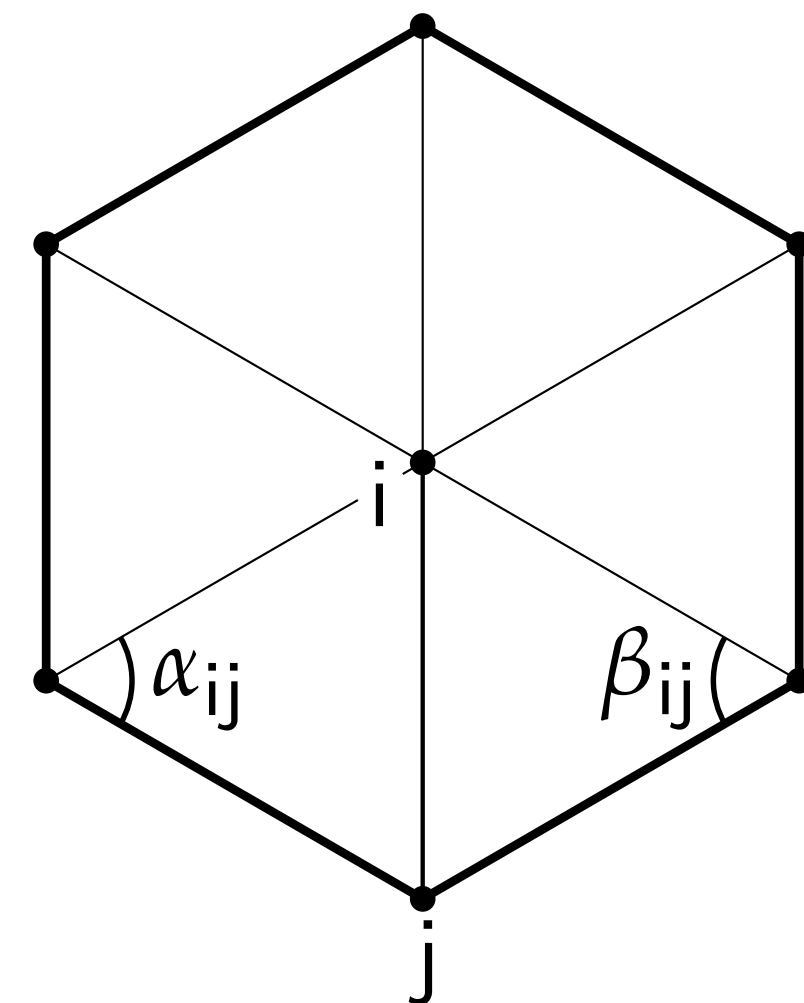


$$\frac{u_{i+1,j} + u_{i-1,j} + u_{i,j+1} + u_{i,j-1} - 4u_{ij}}{h^2}$$

(actually, this becomes that)



TRIANGLE MESH



$$\frac{1}{2} \sum_j (\cot \alpha_{ij} + \cot \beta_{ij})(u_j - u_i)$$

- Also not too hard on point clouds, polygon meshes, ...

# Numerically Solving the Laplace Equation

- Want to solve  $\Delta u = 0$
- Plug in one of our discretizations, e.g.,

	$c$	
$d$	$a$	$b$
	$e$	

$$\frac{b + c + d + e - 4a}{h^2} = 0$$

$$\iff a = \frac{1}{4}(b + c + d + e)$$

- Oh: if we have a solution, then each value must be the average of the neighboring values.
- How do we solve this?
- One idea: keep averaging with neighbors! (“Jacobi method”)
- Correct, but slow. Much better to use modern linear solver

# Solving the Heat Equation

- Back to our three model equations, want to solve heat eqn.

$$\dot{u} = \Delta u$$

- Just saw how to discretize Laplacian
- Also know how to do time (forward Euler, backward Euler, ...)
- E.g., forward Euler:

$$u^{k+1} = u^k + \Delta u^k$$

- Q: On a grid, what's our overall update now at  $u_{i,j}$ ?

$$u_{i,j}^{k+1} = u_{i,j}^k + \frac{\tau}{h^2} (u_{i+1,j}^k + u_{i-1,j}^k + u_{i,j+1}^k + u_{i,j-1}^k - 4u_{i,j}^k)$$

- Not hard to implement! Loop over grid, add up some neighbors.



# Solving the Wave Equation

- Finally, wave equation:

$$\ddot{u} = \Delta u$$

- Not much different; now have 2nd derivative in time

- By now we've learned two different techniques:

- Convert to two 1st order (in time) equations:

$$\dot{u} = v, \quad \dot{v} = \Delta u$$

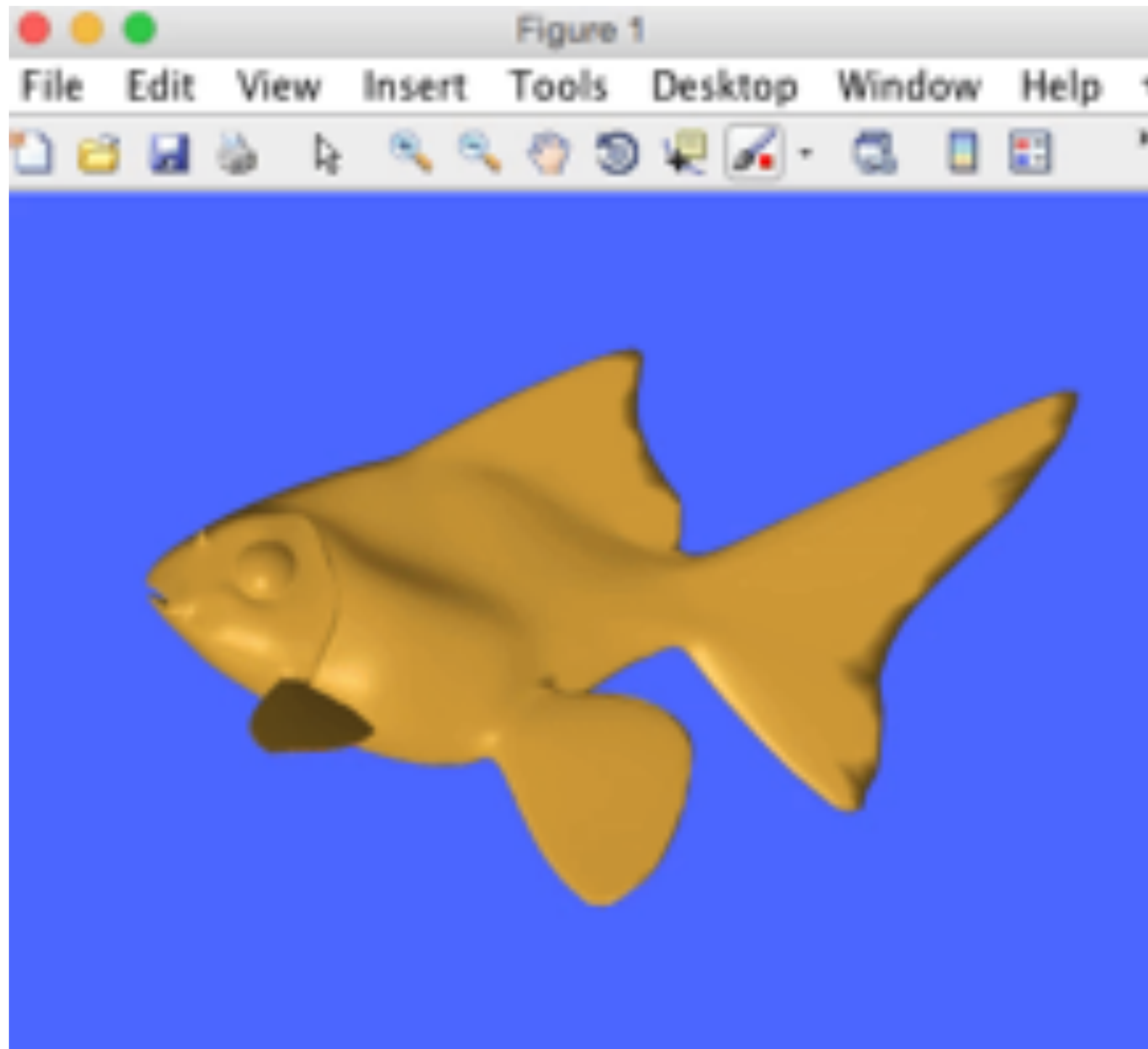
- Or, use centered difference (like Laplace) in time:

$$\frac{u^{k+1} - 2u^k + u^{k-1}}{\tau^2} = \Delta u^k$$

- Plus all our choices about how to discretize Laplacian.
- So many choices! And many, many (many) more we didn't

# Wave Equation on a Triangle Mesh

Credit: Alec Jacobson (<http://www.alecjacobson.com/weblog/?p=4363>)



Also: <http://www.adultswim.com/etcetera/elastic-man/>

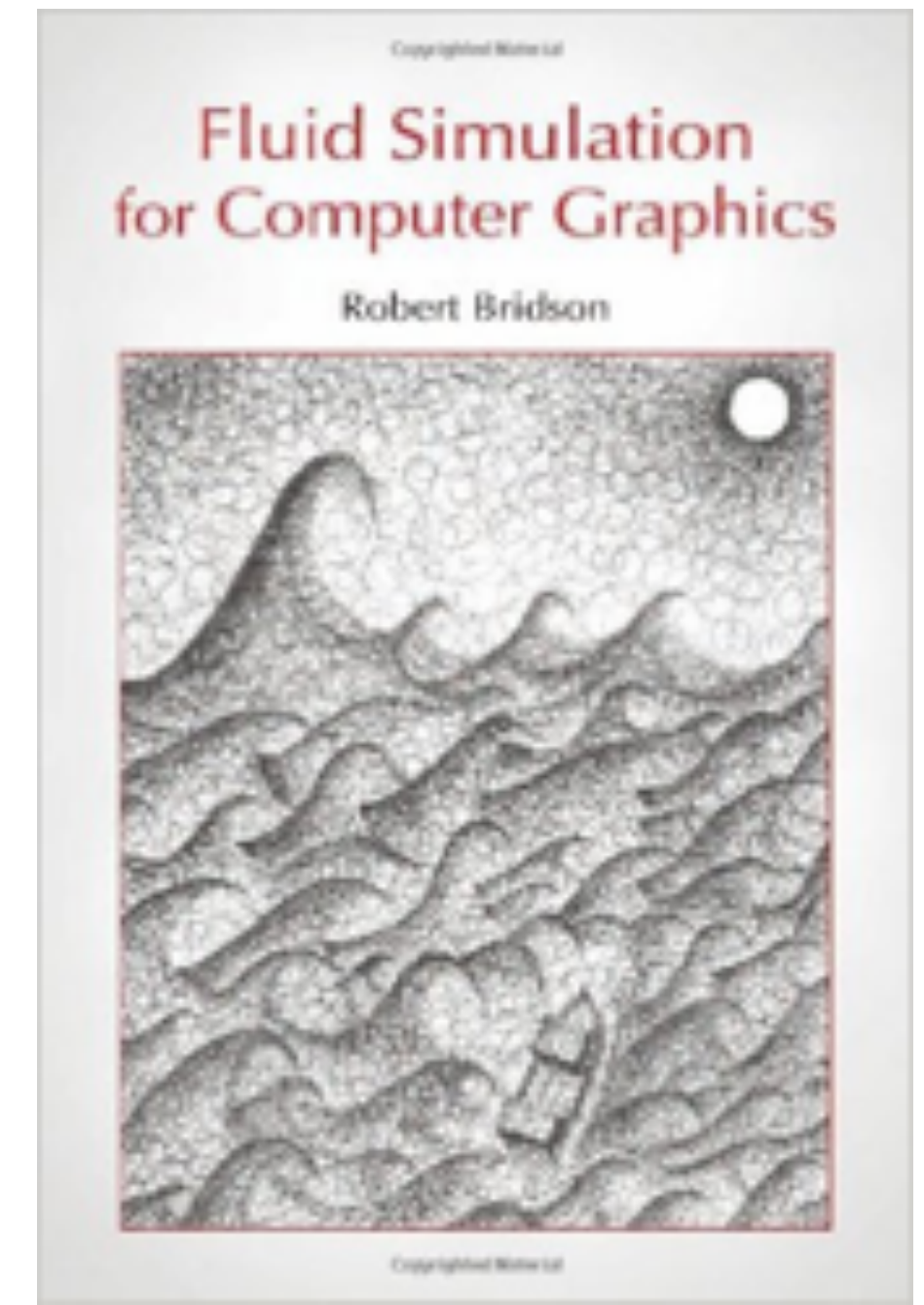
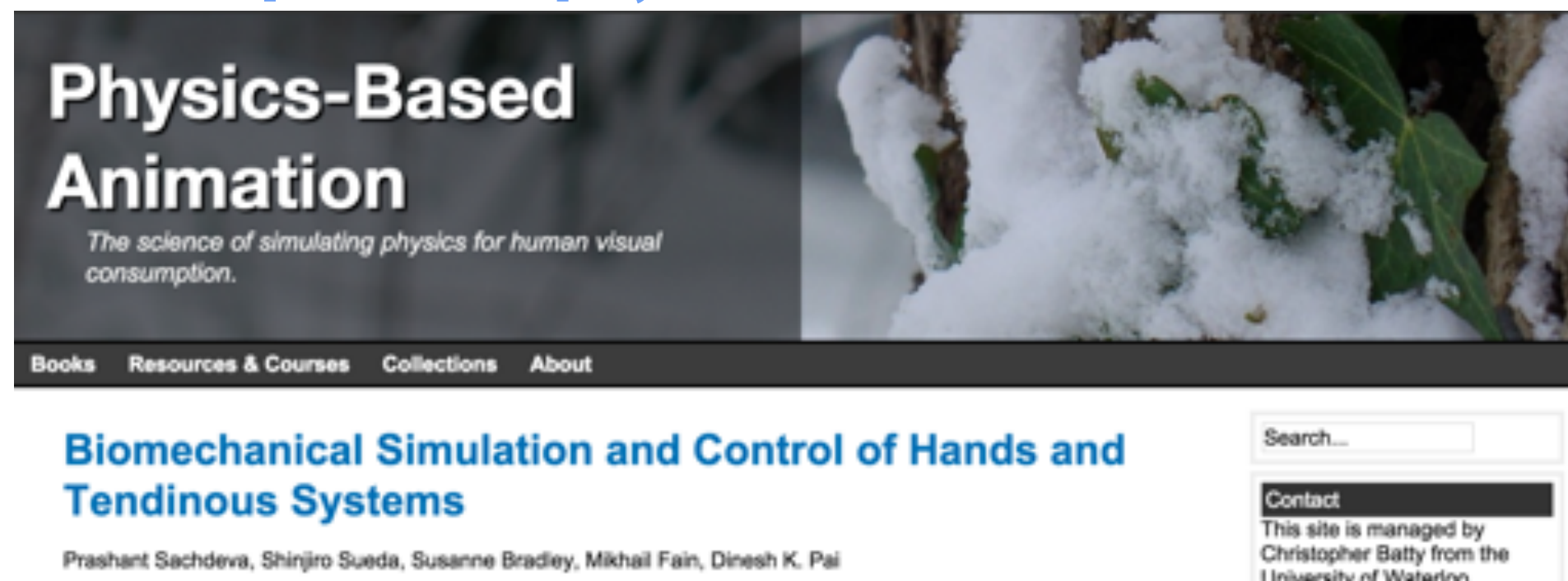
**Wait, what about all those  
cool fluids and stuff?**



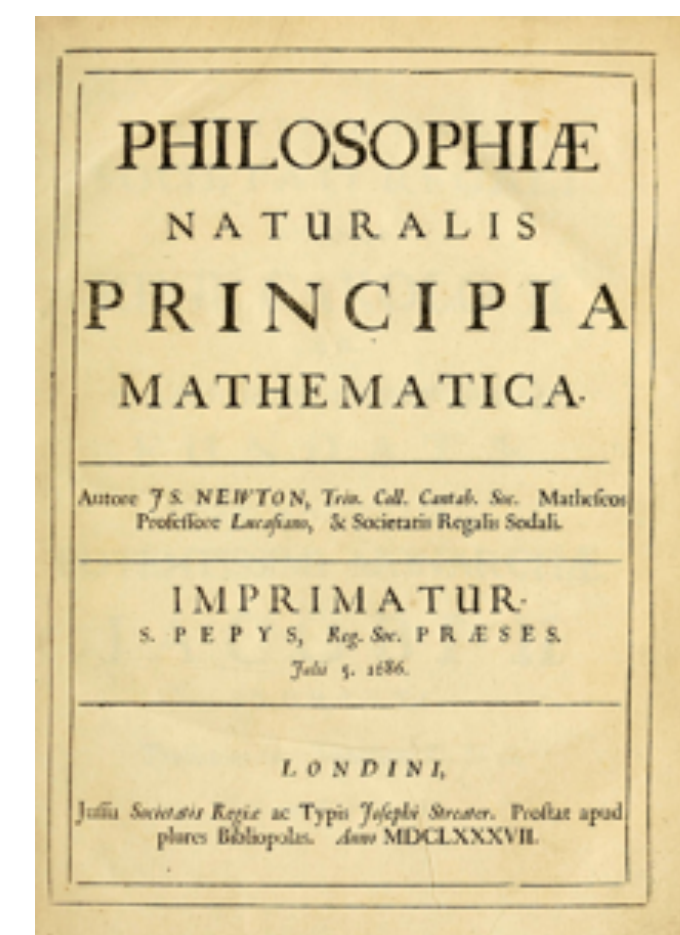
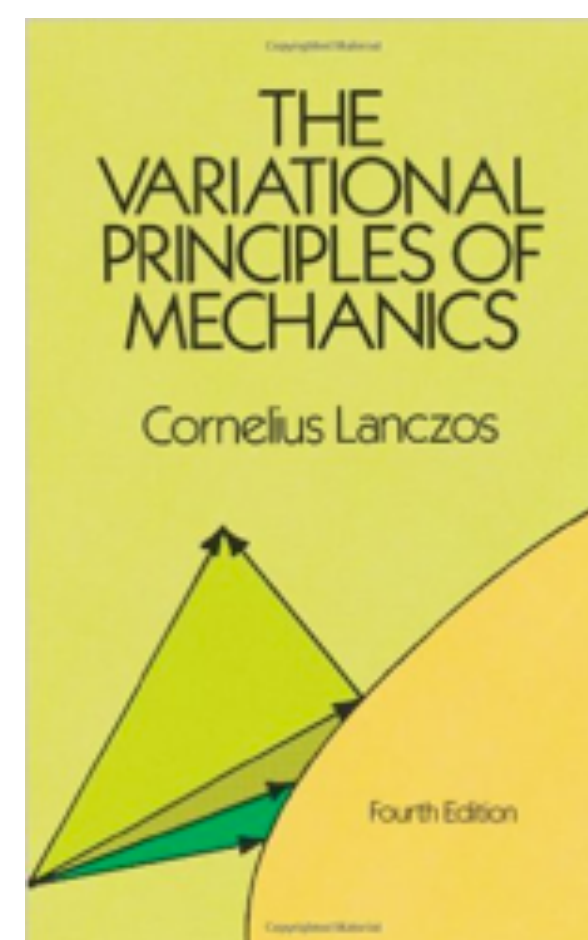
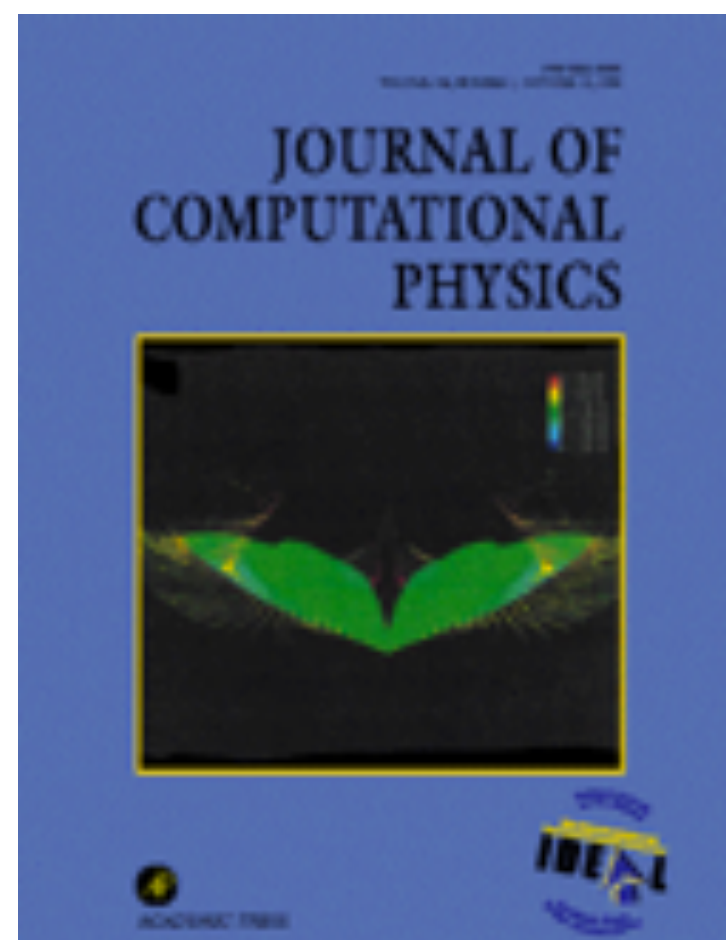
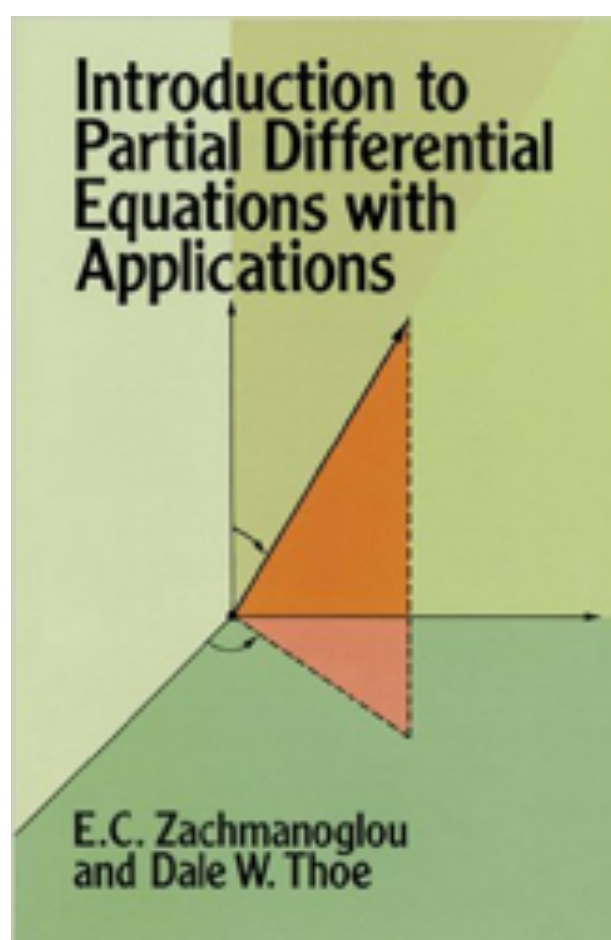
# Want to Know More?

- There are some good books:
- And papers:

<http://www.physicsbasedanimation.com/>



- Also, what did the folks who wrote these books & papers read?





# Also not covered: solving linear equations

