Monte Carlo Ray Tracing

Computer Graphics
CMU 15-462/15-662
TODAY: Monte Carlo Ray Tracing

- How do we render a photorealistic image?
- Put together many of the ideas we’ve studied:
  - color
  - materials
  - radiometry
  - numerical integration
  - geometric queries
  - spatial data structures
  - rendering equation
- Combine into final Monte Carlo ray tracing algorithm
- Alternative to rasterization, lets us generate much more realistic images (usually at much greater cost...)

[Image of a modern kitchen setting]
Photorealistic Ray Tracing—Basic Goal

What are the INPUTS and OUTPUTS?

camera

geometry

materials

lights

("scene")

Ray Tracer

image
Ray Tracing vs. Rasterization—Order

- Both rasterization & ray tracing will generate an image
- What’s the difference?
- One basic difference: order in which we process samples

**Rasterization**

- for each **primitive**: for each **sample**:
  - determine coverage
  - evaluate color
  
  *(Use Z-buffer to determine which primitive is visible)*

**Ray Tracing**

- for each **sample**: for each **primitive**:
  - determine coverage
  - evaluate color
  
  *(Use spatial data structure like BVH to determine which primitive is visible)*
Ray Tracing vs. Rasterization—Illumination

More major difference: sophistication of illumination model

- [LOCAL] rasterizer processes one primitive at a time; hard* to determine things like “A is in the shadow of B”
- [GLOBAL] ray tracer processes on ray at a time; ray knows about everything it intersects, easy to talk about shadows & other “global” illumination effects

Q: What illumination effects are missing from the image on the left?

*But not impossible to do some things with rasterization (e.g., shadow maps)… just results in more complexity
Monte Carlo Ray Tracing

- To develop a full-blown photorealistic ray tracer, will need to apply Monte Carlo integration to the rendering equation.
- To determine color of each pixel, integrate incoming light.
- What function are we integrating?
  - illumination along different paths of light.
- What does a “sample” mean in this context?
  - each path we trace is a sample.

\[
L_o(p, \omega_o) = L_e(p, \omega_o) + \int_{H^2} f_r(p, \omega_i \rightarrow \omega_o) L_i(p, \omega_i) \cos \theta \, d\omega_i
\]
Monte Carlo Integration

- Started looking at Monte Carlo integration in our lecture on numerical integration
- Basic idea: take average of random samples
- Will need to flesh this idea out with some key concepts:
  - EXPECTED VALUE — what value do we get on average?
  - VARIANCE — what’s the expected deviation from the average?
  - IMPORTANCE SAMPLING — how do we (correctly) take more samples in more important regions?

\[
\lim_{N \to \infty} \frac{|\Omega|}{N} \sum_{i=1}^{N} f(X_i) = \int_{\Omega} f(x) \, dx
\]
Expected Value

Intuition: what value does a random variable take, on average?

- E.g., consider a fair coin where heads = 1, tails = 0
- Equal probability of heads & tails (1/2 for both)
- Expected value is then \((1/2)\cdot 1 + (1/2)\cdot 0 = 1/2\)

Properties of expectation:

- \(E[\sum_i Y_i] = \sum_i E[Y_i]\)
- \(E[aY] = aE[Y]\)

(Can you show these are true?)
Variance

Intuition: how far are our samples from the average, on average?

Definition

\[ V[Y] = E[(Y - E[Y])^2] \]

Q: Which of these has higher variance?

Properties of variance:

\[ V[Y] = E[Y^2] - E[Y]^2 \]

\[ V\left[\sum_{i=1}^{N} Y_i\right] = \sum_{i=1}^{N} V[Y_i] \]

\[ V[aY] = a^2 V[Y] \]

(Can you show these are true?)
Law of Large Numbers

- Important fact: for any random variable, the average value of $N$ trials approaches the expected value as we increase $N$
- Decrease in variance is always linear in $N$:

$$V \left[ \frac{1}{N} \sum_{i=1}^{N} Y_i \right] = \frac{1}{N^2} \sum_{i=1}^{N} V[Y_i] = \frac{1}{N^2} N V[Y] = \frac{1}{N} V[Y]$$

**Consider a coconut...**

<table>
<thead>
<tr>
<th>nCoconuts</th>
<th>estimate of $\pi$</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
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</tr>
<tr>
<td>10</td>
<td>3.200000</td>
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<tr>
<td>100</td>
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<tr>
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<tr>
<td>10000</td>
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<td>3.139520</td>
</tr>
<tr>
<td>1000000</td>
<td>3.141764</td>
</tr>
</tbody>
</table>
Q: Why is the law of large numbers important for Monte Carlo ray tracing?

A: No matter how hard the integrals are (crazy lighting, geometry, materials, etc.), can always* get the right image by taking more samples.

*As long as we make sure to sample all possible kinds of light paths…
Biasing

- So far, we’ve picked samples uniformly from the domain (every point is equally likely)
- Suppose we pick samples from some other distribution (more samples in one place than another)
- Q: Can we still use samples $f(X_i)$ to get a (correct) estimate of our integral?
- A: Sure! Just weight contribution of each sample by how likely we were to pick it
- Q: Are we correct to divide by $p$? Or… should we multiply instead?
- A: Think about a simple example where we sample RED region 8x as often as BLUE region
  - average color over square should be purple
  - if we multiply, average will be TOO RED
  - if we divide, average will be JUST RIGHT

$$\int_{\Omega} f(x) \, dx \approx \frac{1}{N} \sum_{i=1}^{N} \frac{f(X_i)}{p(X_i)}$$
Importance sampling

Q: Ok, so then WHERE is the best place to take samples?

Think:
- What is the behavior of $f(x)/p_1(x)$? $f(x)/p_2(x)$?
- How does this impact the variance of the estimator?

Idea: put more where integrand is large ("most useful samples"). E.g.:

(BRDF)  
(image-based lighting)
Example: Direct Lighting

How bright is each point on the ground?

Visibility function:

\[ V(p, p') = \begin{cases} 
1, & p \text{ "sees" } p' \\
0, & \text{otherwise} 
\end{cases} \]
Direct lighting—uniform sampling

Uniformly-sample hemisphere of directions with respect to solid angle

\[ p(\omega) = \frac{1}{2\pi} \]

\[ E(p) = \int L(p, \omega) \cos \theta \, d\omega \]

**Estimator:**

\[ X_i \sim p(\omega) \]

\[ Y_i = f(X_i) \]

\[ Y_i = L(p, \omega_i) \cos \theta_i \]

\[ F_N = \frac{2\pi}{N} \sum_{i=1}^{N} Y_i \]
Aside: Picking points on unit hemisphere

How do we uniformly sample directions from the hemisphere?

One way: use rejection sampling. (How?)

Another way: “warp” two values in [0,1] via the inversion method:

\[ (\xi_1, \xi_2) = (\sqrt{1 - \xi_1^2} \cos(2\pi \xi_2), \sqrt{1 - \xi_1^2} \sin(2\pi \xi_2), \xi_1) \]

Exercise: derive from the inversion method
Direct lighting—uniform sampling (algorithm)

Uniformly-sample hemisphere of directions with respect to solid angle

\[ p(\omega) = \frac{1}{2\pi} \]

\[ E(p) = \int L(p, \omega) \cos \theta \, d\omega \]

Given surface point \( p \)

For each of \( N \) samples:

Generate random direction: \( \omega_i \)

Compute incoming radiance arriving \( L_i \) at \( p \) from direction: \( \omega_i \)

Compute incident irradiance due to ray: \( dE_i = L_i \cos \theta_i \)

Accumulate \( \frac{2\pi}{N} dE_i \) into estimator

A ray tracer evaluates radiance along a ray (see `Raytracer::trace_ray()` in `raytracer.cpp`)
Hemispherical solid angle sampling, 100 sample rays (random directions drawn uniformly from hemisphere)

Light source

Occluder (blocks light)
Why is the image in the previous slide “noisy”?
Incident lighting estimator uses different random directions in each pixel. Some of those directions point towards the light, others do not.

(Estimator is a random variable)
How can we reduce noise?
One idea: just take more samples!

Another idea:
• Don’t need to integrate over entire hemisphere of directions (incoming radiance is 0 from most directions).
• Just integrate over the area of the light (directions where incoming radiance is non-zero) and weight appropriately
Direct lighting: area integral

\[ E(p) = \int L(p, \omega) \cos \theta \, d\omega \]

Previously: just integrate over all directions

\[ E(p) = \int_{A'} L_o(p', \omega') V(p, p') \frac{\cos \theta \cos \theta'}{|p - p'|^2} \, dA' \]

Change of variables to integrate over area of light *

\[ dw = \frac{dA}{|p' - p|^2} = \frac{dA' \cos \theta}{|p' - p|^2} \]

Binary visibility function:
1 if \( p' \) is visible from \( p \), 0 otherwise (accounts for light occlusion)

Outgoing radiance from light point \( p \), in direction \( w' \) towards \( p \)
Direct lighting: area integral

\[ E(p) = \int_{A'} L_o(p', \omega') V(p, p') \frac{\cos \theta \cos \theta'}{|p - p'|^2} \, dA' \]

Sample shape uniformly by area \( A' \)

\[ \int_{A'} p(p') \, dA' = 1 \]
\[ p(p') = \frac{1}{A'} \]
Direct lighting: area integral

\[ E(p) = \int_{A'} L_o(p', \omega') V(p, p') \frac{\cos \theta \cos \theta'}{|p - p'|^2} \, dA' \]

**Probability:**

\[ p(p') = \frac{1}{A'} \]

**Estimator**

\[ Y_i = L_o(p_i', \omega_i') V(p, p_i') \frac{\cos \theta_i \cos \theta_i'}{|p - p_i'|^2} \]

\[ F_N = \frac{A'}{N} \sum_{i=1}^{N} Y_i \]
If no occlusion is present, all directions chosen in computing estimate “hit” the light source. (Choice of direction only matters if portion of light is occluded from surface point p.)
1 area light sample
(high variance in irradiance estimate)
16 area light samples
(lower variance in irradiance estimate)
Comparing different techniques

- Variance in an estimator manifests as noise in rendered images
- Estimator efficiency measure:

\[ \text{Efficiency} \propto \frac{1}{\text{Variance} \times \text{Cost}} \]

- If one integration technique has twice the variance of another, then it takes twice as many samples to achieve the same variance
- If one technique has twice the cost of another technique with the same variance, then it takes twice as much time to achieve the same variance
Example—Cosine-Weighted Sampling

Consider uniform hemisphere sampling in irradiance estimate:

\[ f(\omega) = L_i(\omega) \cos \theta \quad \quad p(\omega) = \frac{1}{2\pi} \]

\[ (\xi_1, \xi_2) = (\sqrt{1 - \xi_1^2} \cos(2\pi \xi_2), \sqrt{1 - \xi_1^2} \sin(2\pi \xi_2), \xi_1) \]

\[ \int_{\Omega} f(\omega) \, d\omega \approx \frac{1}{N} \sum_{i=1}^{N} \frac{f(\omega)}{p(\omega)} = \frac{1}{N} \sum_{i=1}^{N} \frac{L_i(\omega) \cos \theta}{1/2\pi} = \frac{2\pi}{N} \sum_{i=1}^{N} L_i(\omega) \cos \theta \]
Example—Cosine-Weighted Sampling

Cosine-weighted hemisphere sampling in irradiance estimate:

\[ f(\omega) = L_i(\omega) \cos \theta \]

\[ p(\omega) = \frac{\cos \theta}{\pi} \]

\[ \int_{\Omega} f(\omega) \, d\omega \approx \frac{1}{N} \sum_{i}^{N} \frac{f(\omega)}{p(\omega)} = \frac{1}{N} \sum_{i}^{N} \frac{L_i(\omega) \cos \theta}{\cos \theta / \pi} = \frac{\pi}{N} \sum_{i}^{N} L_i(\omega) \]

Idea: bias samples toward directions where \( \cos \theta \) is large
(if \( L \) is constant, then these are the directions that contribute most)
So far we’ve considered light coming directly from light sources, scattered once.

How do we use Monte Carlo integration to get the final color values for each pixel?
Monte Carlo + Rendering Equation

Need to know incident radiance.
So far, have only computed incoming radiance from scene light sources.
Accounting for indirect illumination

\[ L_o(p, \omega_o) = L_e(p, \omega_o) + \int_{H^2} f_r(p, \omega_i \rightarrow \omega_o) L_i(p, \omega_i) \cos \theta_i \, d\omega_i \]

Incoming light energy from direction \( \omega_i \) may be due to light reflected off another surface in the scene (not an emitter)
Path tracing: indirect illumination

\[
\int_{H^2} f_r(\omega_i \to \omega_o) L_o,i(tr(p, \omega_i), -\omega_i) \cos \theta_i \, d\omega_i
\]

- Sample incoming direction from some distribution (e.g. proportional to BRDF):
  \[\omega_i \sim p(\omega)\]

- Recursively call path tracing function to compute incident indirect radiance
Direct illumination
One-bounce global illumination
Two-bounce global illumination
Four-bounce global illumination
Eight-bounce global illumination
Wait a minute…
When do we stop?!
Russian roulette

- Idea: want to avoid spending time evaluating function for samples that make a **small contribution** to the final result
- Consider a low-contribution sample of the form:

\[
L = \frac{f_r(\omega_i \rightarrow \omega_o) L_i(\omega_i) V(p, p') \cos \theta_i}{p(\omega_i)}
\]
Russian roulette

\[ L = \frac{f_r(\omega_i \rightarrow \omega_o) L_i(\omega_i) V(p, p') \cos \theta_i}{p(\omega_i)} \]

\[ L = \left[ \frac{f_r(\omega_i \rightarrow \omega_o) L_i(\omega_i) \cos \theta_i}{p(\omega_i)} \right] V(p, p') \]

- If tentative contribution (in brackets) is small, total contribution to the image will be small regardless of \( V(p, p') \).
- Ignoring low-contribution samples introduces systematic error.
  - No longer converges to correct value!
- Instead, randomly discard low-contribution samples in a way that leaves estimator unbiased.
Russian roulette

- New estimator: evaluate original estimator with probability \( p_{rr} \), reweight. Otherwise ignore.
- Same expected value as original estimator:

\[
p_{rr} E \left[ \frac{X}{p_{rr}} \right] + E[(1 - p_{rr})0] = E[X]
\]
No Russian roulette: 6.4 seconds
Russian roulette: terminate 50% of all contributions with luminance less than 0.25: 5.1 seconds
Russian roulette: terminate 50% of all contributions with luminance less than 0.5: 4.9 seconds
Russian roulette: terminate 90% of all contributions with luminance less than 0.125: 4.8 seconds
Russian roulette: terminate 90% of all contributions with luminance less than 1: 3.6 seconds
Monte Carlo Ray Tracing—Summary

- Light hitting a point (e.g., pixel) described by rendering equation
  - Expressed as recursive integral
  - Can use Monte Carlo to estimate this integral
  - Need to be intelligent about how to sample!

\[
L_o(p, \omega_o) = L_e(p, \omega_o) + \int_{\mathcal{H}_2} f_r(p, \omega_i \rightarrow \omega_o)L_i(p, \omega_i) \cos \theta \, d\omega_i
\]
Next time:

- Variance reduction—how do we get the most out of our samples?