# Monte Carlo 

## Rendering

Computer Graphics<br>CMU 15-462/15-662

## TODAY: Monte Carlo Rendering

- How do we render a photorealistic image?
- Put together many of the ideas we've studied:
- color
- materials
- radiometry
- numerical integration
- geometric queries
- spatial data structures
- rendering equation

- Combine into final Monte Carlo ray tracing algorithm
- Alternative to rasterization, lets us generate much more realistic images (usually at much greater cost...)


## Photorealistic Rendering-Basic Goal What are the INPUTS and OUTPUTS?


("scene") image

## Ray Tracing vs. Rasterization—Order

- Both rasterization \& ray tracing will generate an image
- What's the difference?
- One basic difference: order in which we process samples

RASTERIZATION

for each primitive:
for each sample:
determine coverage evaluate color
(Use Z-buffer to determine which primitive is visible)

RAY TRACING

for each sample:
for each primitive: determine coverage evaluate color
(Use spatial data structure like BVH to determine which primitive is visible)

## Ray Tracing vs. Rasterization-Illumination

- More major difference: sophistication of illumination model
- [LOCAL] rasterizer processes one primitive at a time; hard* to determine things like "A is in the shadow of $B$ "
- [GLOBAL] ray tracer processes on ray at a time; ray knows about everything it intersects, easy to talk about shadows \& other "global" illumination effects

RASTERIZATION
RAY TRACING


Q: What illumination effects are missing from the image on the left?

## Monte Carlo Ray Tracing

- To develop a full-blown photorealistic ray tracer, will need to apply Monte Carlo integration to the rendering equation
- To determine color of each pixel, integrate incoming light
- What function are we integrating?
- illumination along different paths of light
- What does a "sample" mean in this context?
- each path we trace is a sample

$$
\begin{aligned}
L_{o}\left(\mathbf{p}, \omega_{0}\right)= & L_{e}\left(\mathbf{p}, \omega_{0}\right)+\quad \mathbb{L} \\
& \int_{\mathcal{H}^{2}} f_{r}\left(\mathbf{p}, \omega_{i} \rightarrow \omega_{0}\right) L_{i}\left(\mathbf{p}, \omega_{i}\right) \cos \theta d \omega_{i}
\end{aligned}
$$



## Monte Carlo Integration

- Started looking at Monte Carlo integration in our lecture on numerical integration
- Basic idea: take average of random samples
- Will need to flesh this idea out with some key concepts:
- EXPECTED VALUE — what value do we get on average?
- VARIANCE - what's the expected deviation from the average?
- IMPORTANCE SAMPLING - how do we (correctly) take more samples in more important regions?

$$
\lim _{N \rightarrow \infty} \frac{|\Omega|}{N} \sum_{i=1}^{N} f\left(X_{i}\right)=\int_{\Omega} f(x) d x
$$

## Expected Value

## Intuition: what value does a random variable take, on average?

- E.g., consider a fair coin where heads $=1$, tails $=0$
- Equal probability of heads $\&$ is tails ( $1 / 2$ for both)
- Expected value is then $(1 / 2) \cdot 1+(1 / 2) \cdot 0=1 / 2$

expected value of
random variable $Y$

$$
\begin{gathered}
\text { Properties of expectation: } \\
\begin{array}{c}
E\left[\sum_{i} Y_{i}\right]=\sum_{i} E\left[Y_{i}\right] \\
E[a Y]=a E[Y] \\
\text { (Can you show these are true?) }
\end{array} .
\end{gathered}
$$

## Variance

## Intuition: how far are our samples from the average, on average?

Definition

$$
V[Y]=E\left[(Y-E[Y])^{2}\right]
$$

## Q:Which of these has higher variance?



Properties of variance:

$$
\begin{gathered}
V[Y]=E\left[Y^{2}\right]-E[Y]^{2} \\
V\left[\sum_{i=1}^{N} Y_{i}\right]=\sum_{i=1}^{N} V\left[Y_{i}\right] \\
V[a Y]=a^{2} V[Y]
\end{gathered}
$$

(Can you show these are true?)

## Law of Large Numbers

- Important fact: for any random variable, the average value of N trials approaches the expected value as we increase N
- Decrease in variance is always linear in N :

$$
V\left[\frac{1}{N} \sum_{i=1}^{N} Y_{i}\right]=\frac{1}{N^{2}} \sum_{i=1}^{N} V\left[Y_{i}\right]=\frac{1}{N^{2}} N V[Y]=\frac{1}{N} V[Y]
$$

## Consider a coconut...

| nCoconuts | estimate of $\pi$ |
| :--- | :--- |
| 1 | 4.000000 |
| 10 | 3.200000 |
| 100 | 3.240000 |
| 1000 | 3.112000 |
| 10000 | 3.163600 |
| 100000 | 3.139520 |
| 1000000 | 3.141764 |



# Q: Why is the law of large numbers important for Monte Carlo ray tracing? A: No matter how hard the integrals are (crazy lighting, geometry, materials, etc.), can always* get the right image by taking more samples. 

## Biasing

- So far, we've picked samples uniformly from the domain (every point is equally likely)
- Suppose we pick samples from some other distribution (more samples in one place than another)

- Q: Can we still use samples $f(X i)$ to get a (correct) estimate of our integral?
- A: Sure! Just weight contribution of each sample by how likely we were to pick it
- Q: Are we correct to divide by $p$ ? Or... should we multiply instead?
- A: Think about a simple example where we sample RED region 8x as often as BLUE region
- average color over square should be purple

■ if we multiply, average will be TOO RED

- if we divide, average will be JUST RIGHT

$$
\int_{\Omega} f(x) d x \approx \frac{1}{N} \sum_{i=1}^{N} \frac{f\left(X_{i}\right)}{p\left(X_{i}\right)}
$$



## Importance sampling

Q: $0 k$, so then WHERE is the best place to take samples?

Think:
-What is the behavior of $f(x) / p_{1}(x) ? f(x) / p_{2}(x)$ ?

- How does this impact the variance of the estimator?


Idea: put more where integrand is large ("most useful samples"). E.g.:
(image-based lighting)


## Example: Direct Lighting



How bright is each point on the ground?

## Direct lighting—uniform sampling

Uniformly-sample hemisphere of directions with respect to solid angle
$p(\omega)=\frac{1}{2 \pi}$

$$
E(\mathrm{p})=\int L(\mathrm{p}, \omega) \cos \theta \mathrm{d} \omega
$$



## Estimator:

$$
\begin{aligned}
X_{i} & \sim p(\omega) \\
Y_{i} & =f\left(X_{i}\right) \\
Y_{i} & =L\left(\mathrm{p}, \omega_{i}\right) \cos \theta_{i} \\
F_{N} & =\frac{2 \pi}{N} \sum_{i=1}^{N} Y_{i}
\end{aligned}
$$

## Aside: Picking points on unit hemisphere

How do we uniformly sample directions from the hemisphere?
One way: use rejection sampling. (How?)
Another way: "warp" two values in $[0,1]$ via the inversion method:

$$
\left(\xi_{1}, \xi_{2}\right)=\left(\sqrt{1-\xi_{1}^{2}} \cos \left(2 \pi \xi_{2}\right), \sqrt{1-\xi_{1}^{2}} \sin \left(2 \pi \xi_{2}\right), \xi_{1}\right)
$$



Exercise: derive from the inversion method

## Direct lighting—uniform sampling (algorithm)

Uniformly-sample hemisphere of directions with respect to solid angle
$p(\omega)=\frac{1}{2 \pi}$

$$
E(\mathrm{p})=\int L(\mathrm{p}, \omega) \cos \theta \mathrm{d} \omega
$$

Given surface point $p$
A ray tracer evaluates radiance along a ray (see Raytracer::trace_ray() in raytracer.cpp)
For each of N samples:
Generate random direction: $\omega_{i}$
Compute incoming radiance arriving $L_{i}$ at $p$ from direction: $\omega_{i}$
Compute incident irradiance due to ray: $d E_{i}=L_{i} \cos \theta_{i}$
Accumulate $\frac{2 \pi}{N} d E_{i}$ into estimator

## Hemispherical solid angle sampling, 100 sample rays <br> (random directions drawn uniformly from hemisphere)

 (blocks light)
## Why is the image in the previous slide "noisy"?



## How can we reduce noise?

## One idea: just take more samples!

## Another idea:

-Don't need to integrate over entire hemisphere of directions (incoming radiance is 0 from most directions).
-Just integrate over the area of the light (directions where incoming radiance is non-zero)and weight appropriately

## Direct lighting: area integral

$E(\mathrm{p})=\int L(\mathrm{p}, \omega) \cos \theta \mathrm{d} \omega \longleftarrow$ Previously: just integrate over all directions
$E(\mathrm{p})=\int_{A^{\prime}} L_{o}\left(\mathrm{p}^{\prime}, \omega^{\prime}\right) V\left(\mathrm{p}, \mathrm{p}^{\prime}\right) \frac{\cos \theta \cos \theta^{\prime}}{\left|\mathrm{p}-\mathrm{p}^{\prime}\right|^{2}} \mathrm{~d} A^{\prime} \longleftarrow \substack{\text { Change of variables } \\ \text { to integrate over } \\ \text { area of light ** }}$


## Direct lighting: area integral

$$
E(\mathrm{p})=\int_{A^{\prime}} L_{o}\left(\mathrm{p}^{\prime}, \omega^{\prime}\right) V\left(\mathrm{p}, \mathrm{p}^{\prime}\right) \frac{\cos \theta \cos \theta^{\prime}}{\left|\mathrm{p}-\mathrm{p}^{\prime}\right|^{2}} \mathrm{~d} A^{\prime}
$$

Sample shape uniformly by area $A^{\prime}$


$$
\begin{aligned}
& \int_{A^{\prime}} p\left(\mathrm{p}^{\prime}\right) \mathrm{d} A^{\prime}=1 \\
& p\left(\mathrm{p}^{\prime}\right)=\frac{1}{A^{\prime}}
\end{aligned}
$$

## Direct lighting: area integral

$$
E(\mathrm{p})=\int_{A^{\prime}} L_{o}\left(\mathrm{p}^{\prime}, \omega^{\prime}\right) V\left(\mathrm{p}, \mathrm{p}^{\prime}\right) \frac{\cos \theta \cos \theta^{\prime}}{\left|\mathrm{p}-\mathrm{p}^{\prime}\right|^{2}} \mathrm{~d} A^{\prime}
$$

## Probability:



$$
p\left(\mathrm{p}^{\prime}\right)=\frac{1}{A^{\prime}}
$$

## Estimator

$$
\begin{gathered}
Y_{i}=L_{o}\left(\mathrm{p}_{i}^{\prime}, \omega_{i}^{\prime}\right) V\left(\mathrm{p}, \mathrm{p}_{i}^{\prime}\right) \frac{\cos \theta_{i} \cos \theta_{i}^{\prime}}{\left|\mathrm{p}-\mathrm{p}_{i}^{\prime}\right|^{2}} \\
F_{N}=\frac{A^{\prime}}{N} \sum_{i=1}^{N} Y_{i}
\end{gathered}
$$



If no ocdusion is present, all directions chosen in computing estimate "hit" the light source. (Choice of direction only matters if portion of light is ocduded from surface point $p_{0}$.)

# 1 area light sample <br> (high variance in irradiance estimate) 

16 area light samples
(lower variance in irradiance estimate)

## Comparing different techniques

- Variance in an estimator manifests as noise in rendered images
- Estimator efficiency measure:

$$
\text { Efficiency } \propto \frac{1}{\text { Variance } \times \text { Cost }}
$$

- If one integration technique has twice the variance of another, then it takes twice as many samples to achieve the same variance
- If one technique has twice the cost of another technique with the same variance, then it takes twice as much time to achieve the same variance


## Example—Cosine-Weighted Sampling

Consider uniform hemisphere sampling in irradiance estimate:

$$
\begin{array}{cc}
f(\omega)=L_{i}(\omega) \cos \theta & p(\omega)=\frac{1}{2 \pi} \\
\left(\xi_{1}, \xi_{2}\right)=\left(\sqrt{1-\xi_{1}^{2}} \cos \left(2 \pi \xi_{2}\right), \sqrt{1-\xi_{1}^{2}} \sin \left(2 \pi \xi_{2}\right), \xi_{1}\right) \\
\int_{\Omega} f(\omega) \mathrm{d} \omega \approx \frac{1}{N} \sum_{i}^{N} \frac{f(\omega)}{p(\omega)}=\frac{1}{N} \sum_{i}^{N} \frac{L_{i}(\omega) \cos \theta}{1 / 2 \pi}=\frac{2 \pi}{N} \sum_{i}^{N} L_{i}(\omega) \cos \theta
\end{array}
$$



## Example—Cosine-Weighted Sampling

Cosine-weighted hemisphere sampling in irradiance estimate:

$$
\begin{array}{cc}
f(\omega)=L_{i}(\omega) \cos \theta & p(\omega)=\frac{\cos \theta}{\pi} \\
\int_{\Omega} f(\omega) \mathrm{d} \omega \approx \frac{1}{N} \sum_{i}^{N} \frac{f(\omega)}{p(\omega)}=\frac{1}{N} \sum_{i}^{N} \frac{L_{i}(\omega) \cos \theta}{\cos \theta / \pi}=\frac{\pi}{N} \sum_{i}^{N} L_{i}(\omega)
\end{array}
$$

Idea: bias samples toward directions where $\cos \theta$ is large (if $L$ is constant, then these are the directions that contribute most)


# So far we've considered light coming directly from light sources, scattered once. 

How do we use Monte Carlo integration to get the final color values for each pixel?

## Monte Carlo + Rendering Equation



Need to know incident radiance.
So far, have only computed incoming radiance from scene light sources.

## Accounting for indirect illumination



Incoming light energy from direction $\omega_{i}$ may be due to light reflected off another surface in the scene (not an emitter)

## Path tracing: indirect illumination

$$
\int_{H^{2}} f_{r}\left(\omega_{i} \rightarrow \omega_{o}\right) L_{o, i}\left(\operatorname{tr}\left(\mathrm{p}, \omega_{i}\right),-\omega_{i}\right) \cos \theta_{i} \mathrm{~d} \omega_{i}
$$

- Sample incoming direction from some distribution (e.g. proportional to BRDF):

$$
\omega_{i} \sim p(\omega)
$$

- Recursively call path tracing function to compute incident indirect radiance








## Wait a minute... When do we stop?!

## Russian roulette

- Idea: want to avoid spending time evaluating function for samples that make a small contribution to the final result
- Consider a low-contribution sample of the form:

$$
L=\frac{f_{r}\left(\omega_{i} \rightarrow \omega_{o}\right) L_{i}\left(\omega_{i}\right) V\left(\mathrm{p}, \mathrm{p}^{\prime}\right) \cos \theta_{i}}{p\left(\omega_{i}\right)}
$$

## Russian roulette

$$
\begin{aligned}
& L=\frac{f_{r}\left(\omega_{i} \rightarrow \omega_{o}\right) L_{i}\left(\omega_{i}\right) V\left(\mathrm{p}, \mathrm{p}^{\prime}\right) \cos \theta_{i}}{p\left(\omega_{i}\right)} \\
& \downarrow \\
& L=\left[\frac{f_{r}\left(\omega_{i} \rightarrow \omega_{o}\right) L_{i}\left(\omega_{i}\right) \cos \theta_{i}}{p\left(\omega_{i}\right)}\right] V\left(\mathrm{p}, \mathrm{p}^{\prime}\right)
\end{aligned}
$$

■ If tentative contribution (in brackets) is small, total contribution to the image will be small regardless of $V\left(\mathrm{p}, \mathrm{p}^{\prime}\right)$

- Ignoring low-contribution samples introduces systematic error
- No longer converges to correct value!
- Instead, randomly discard low-contribution samples in a way that leaves estimator unbiased


## Russian roulette

- New estimator: evaluate original estimator with probability $p_{\text {rr }}$, reweight. Otherwise ignore.
- Same expected value as original estimator:

$$
p_{\mathrm{rr}} E\left[\frac{X}{p_{\mathrm{rr}}}\right]+E\left[\left(1-p_{\mathrm{rr}}\right) 0\right]=E[X]
$$



No Russian roulette: 6.4 seconds


Russian roulette: terminate 50\% of all contributions with luminance less than $\mathbf{0 . 2 5 : ~} \mathbf{5 . 1}$ seconds


Russian roulette: terminate $50 \%$ of all contributions with luminance less than $0.5: 4.9$ seconds


Russian roulette: terminate $90 \%$ of all contributions with luminance less than $0.125: 4.8$ seconds


Russian roulette: terminate $90 \%$ of all contributions with luminance less than 1:3.6 seconds

## Monte Carlo Rendering-Summary

- Light hitting a point (e.g., pixel) described by rendering equation
- Expressed as recursive integral
- Can use Monte Carlo to estimate this integral
- Need to be intelligent about how to sample!



## Next time:

- Variance reduction-how do we get the most out of our samples?


