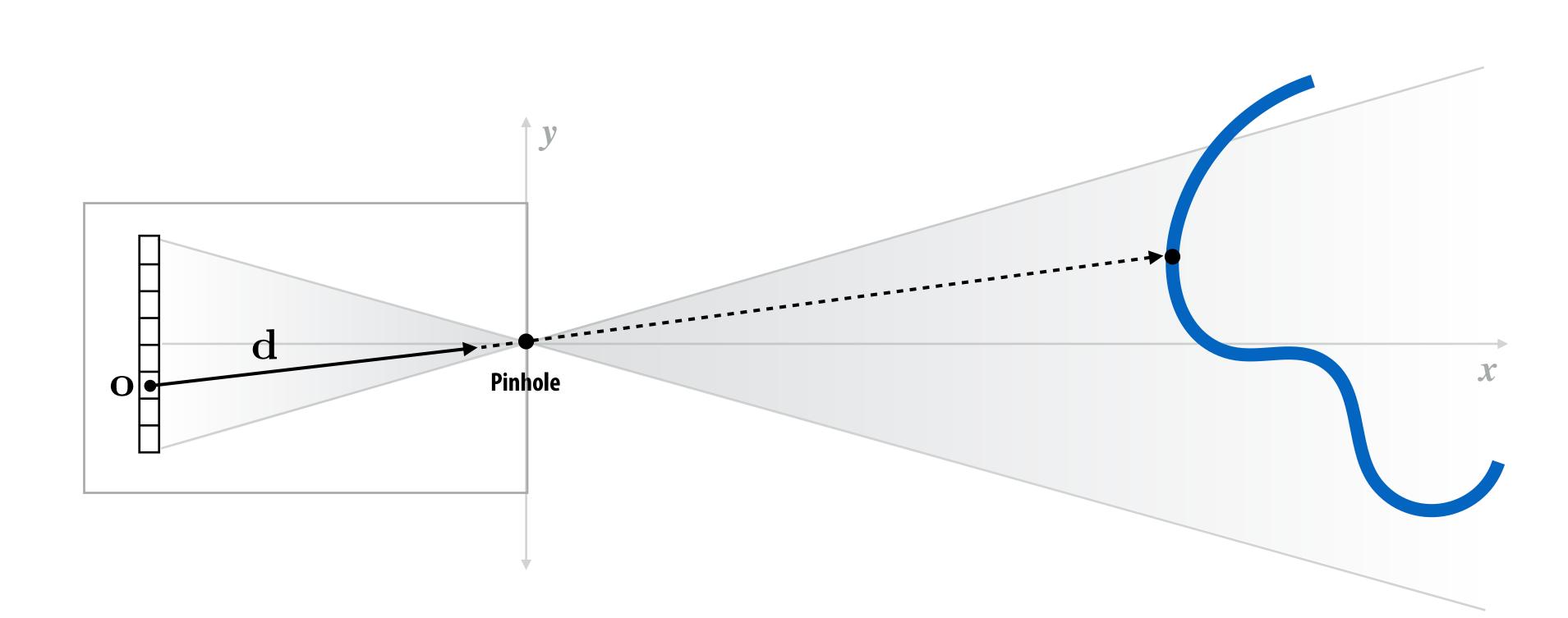
Lecture 13: Reflection

Computer Graphics CMU 15-462/15-662, Fall 2015

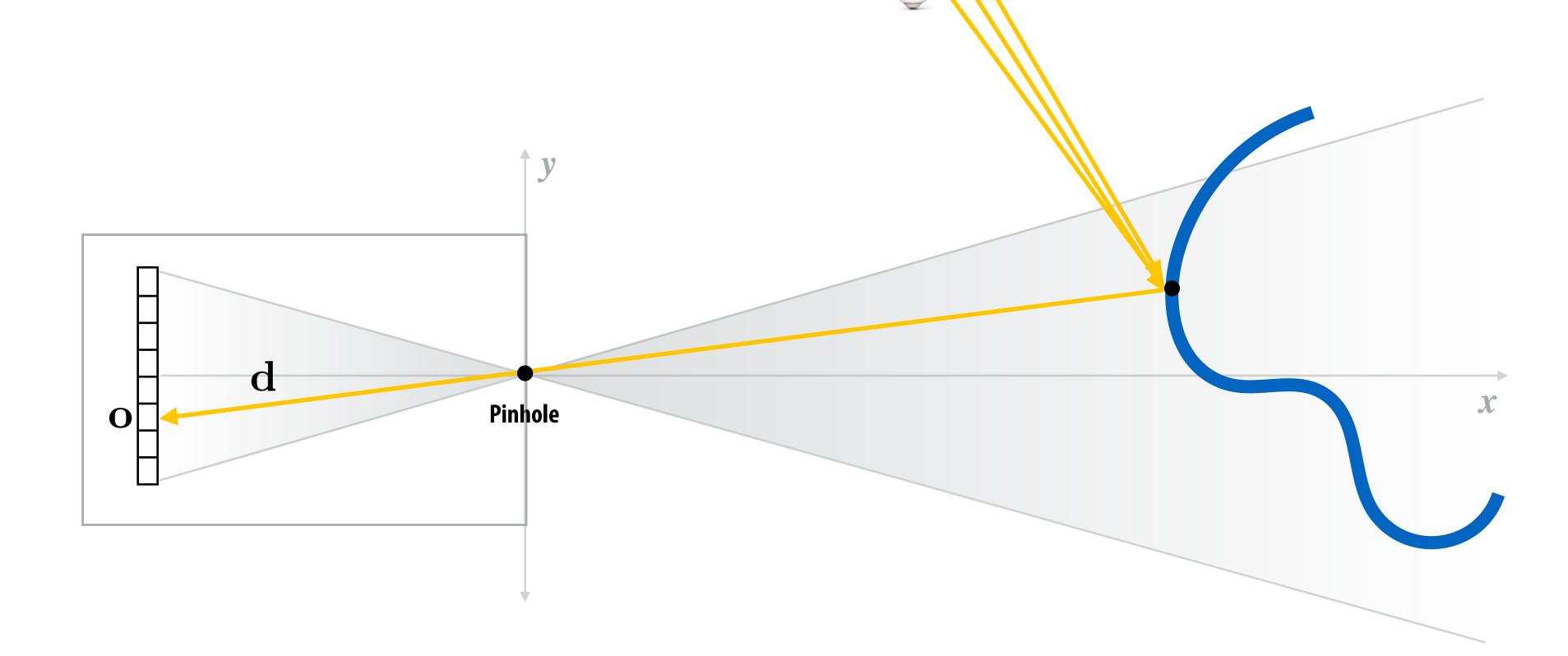
Slides credit: a majority of these slides were created by Matt Pharr and Pat Hanrahan

Ray tracer measures radiance along a ray



In the ray tracing algorithms we've discussed so far: want to measure radiance traveling in the direction opposite the ray direction.

Ray tracer measures radiance along a ray



Radiance entering camera in direction d = light from scene light sources that is reflected off surface in direction d.

Reflection models

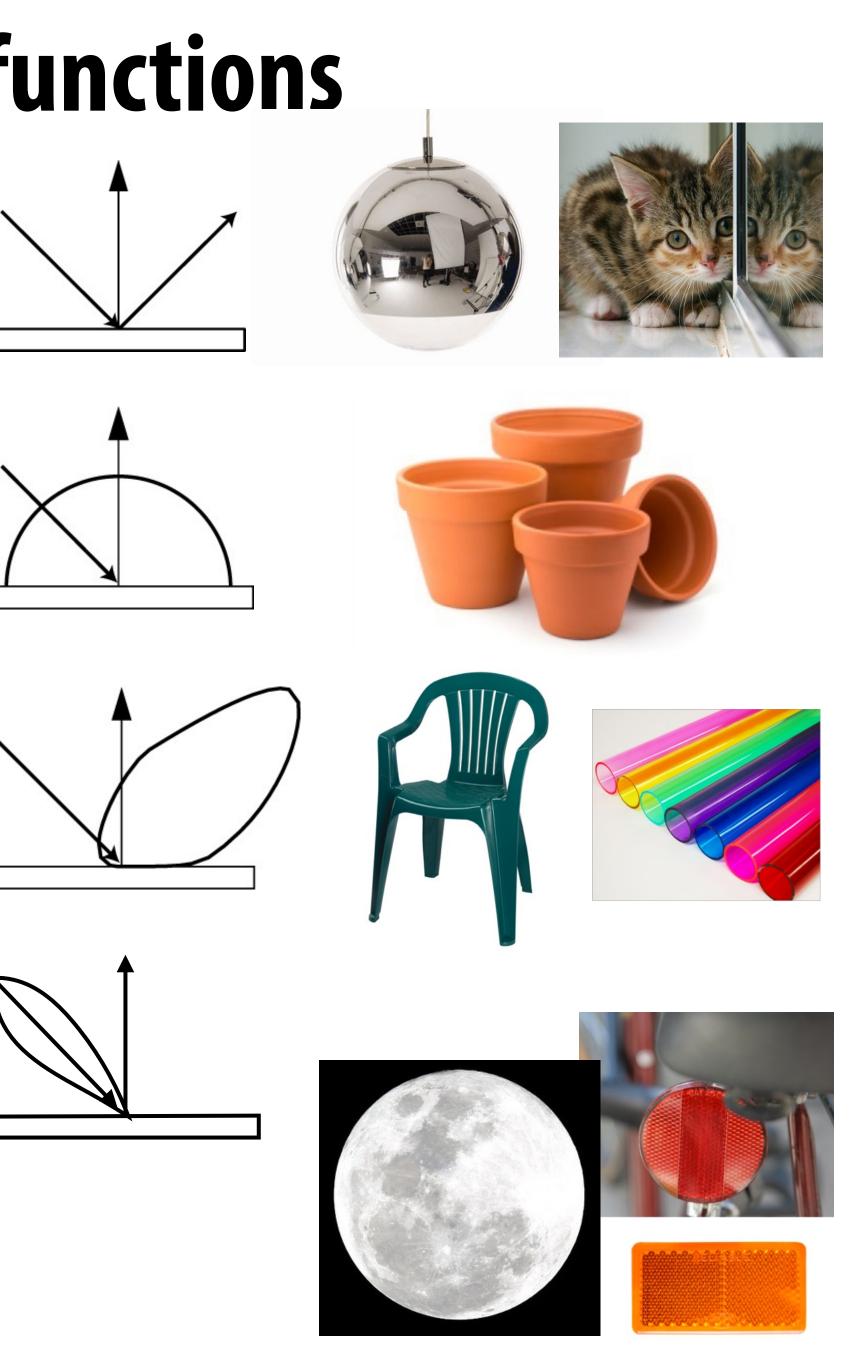
Definition: reflection is the process by which light incident on a surface interacts with the surface such that it leaves on the incident (same) side without change in frequency

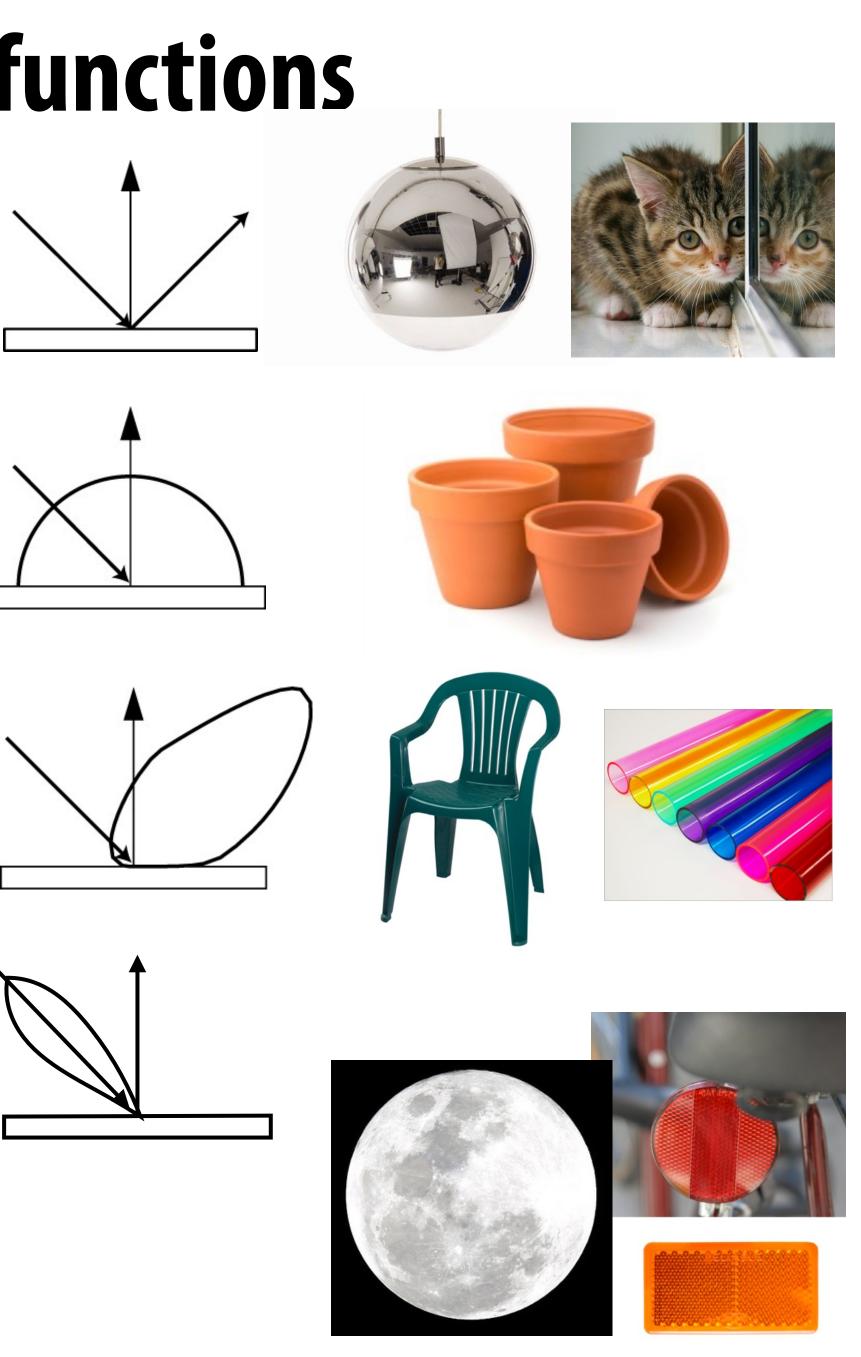
Categories of reflection functions

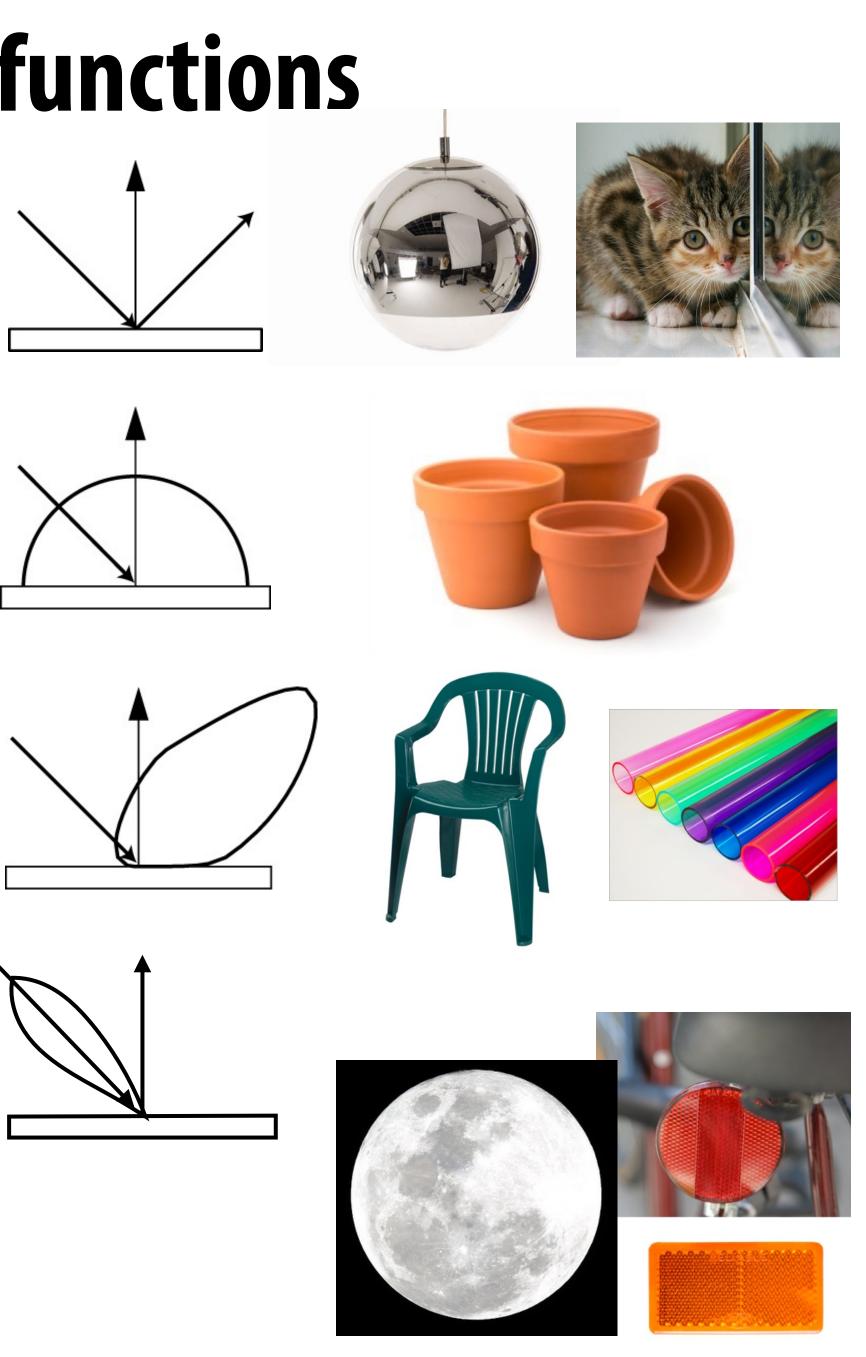
- **Ideal specular Perfect mirror**
- Ideal diffuse **Uniform reflection in all directions**
- **Glossy specular** Majority of light distributed in reflection direction
 - **Retro-reflective**

Reflects light back toward source

Diagrams illustrate how incoming light energy from given direction is reflected in various directions.









Materials: diffuse



Materials: plastic



Materials: red semi-gloss paint



Materials: Ford mystic lacquer paint



Materials: mirror



Materials: gold

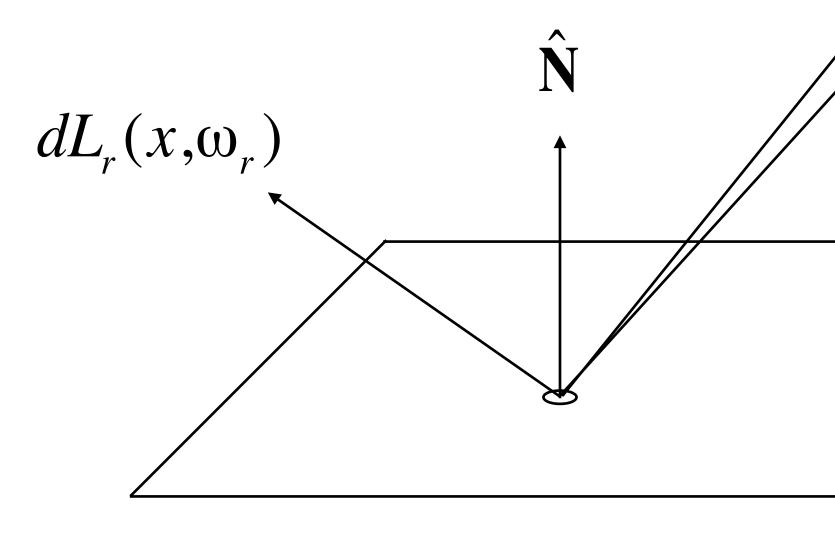


Materials





Bidirectional reflectance distribution function (BRDF)



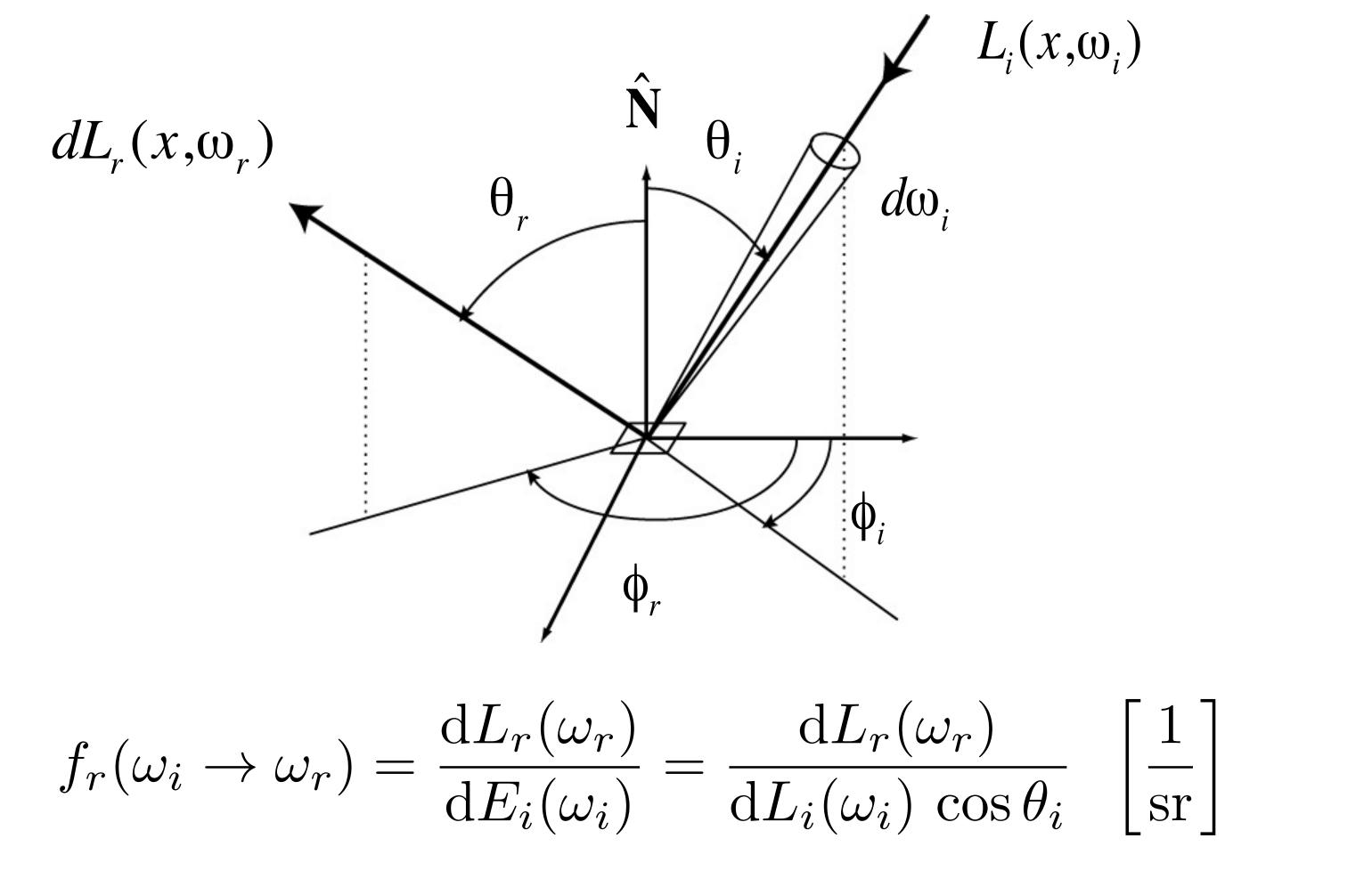
 $dL_r(\omega_r) \propto dE_i(\omega_i)$

Differential irradiance landing on surface from differential cone of directions ω_i $dE(\omega_i) = dL(\omega_i)\cos\theta_i$

Differential radiance reflected in direction ω_r (due to differential irradiance from ω_i) $dL_r(\omega_r)$

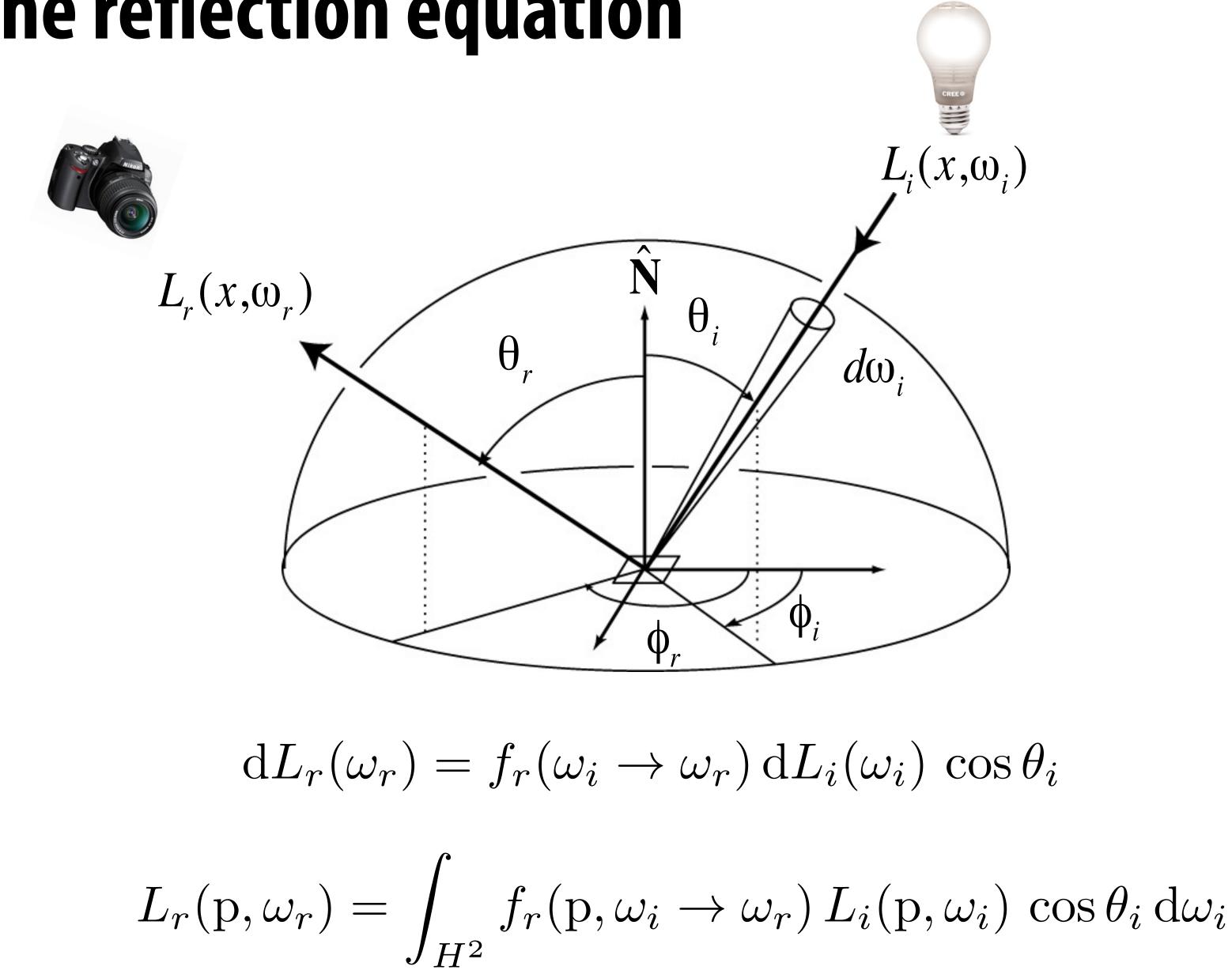
 $dE(\omega_i)$

Bidirectional reflectance distribution function (BRDF)



BRDF defines the fraction of energy arriving from ω_i that is reflected in the direction ω_r

The reflection equation



Solving the reflection equation

$$L_r(\mathbf{p}, \omega_r) = \int_{H^2} f_r(\mathbf{p}, \omega_i \to \omega_r) L_r$$

- **Basic Monte Carlo estimate:**
 - Generate directions ω_i sampled from some distribution $p(\omega)$
 - To reduce variance $p(\omega)$ should match BRDF or incident radiance function
 - Compute the estimator

$$\frac{1}{N} \sum_{j=1}^{N} \frac{f_r(\mathbf{p}, \omega_j \to \omega_r) L_i(\mathbf{p}, \omega_j)}{p(\omega_j)} L_i(\mathbf{p}, \omega_j) L_j(\mathbf{p}, \omega_$$



$u_i(\mathbf{p},\omega_i) \cos \theta_i \,\mathrm{d}\omega_i$

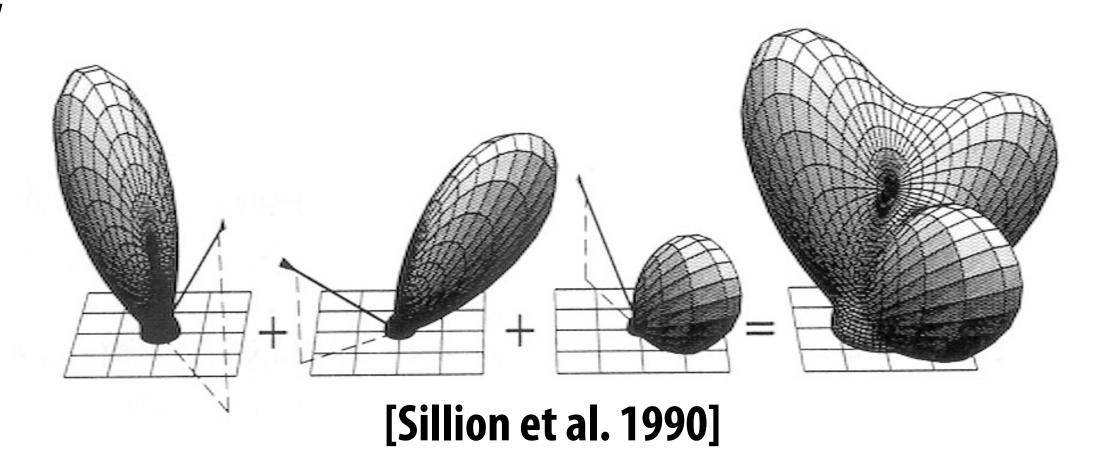
 ω_j) cos θ_j

Estimating reflected light

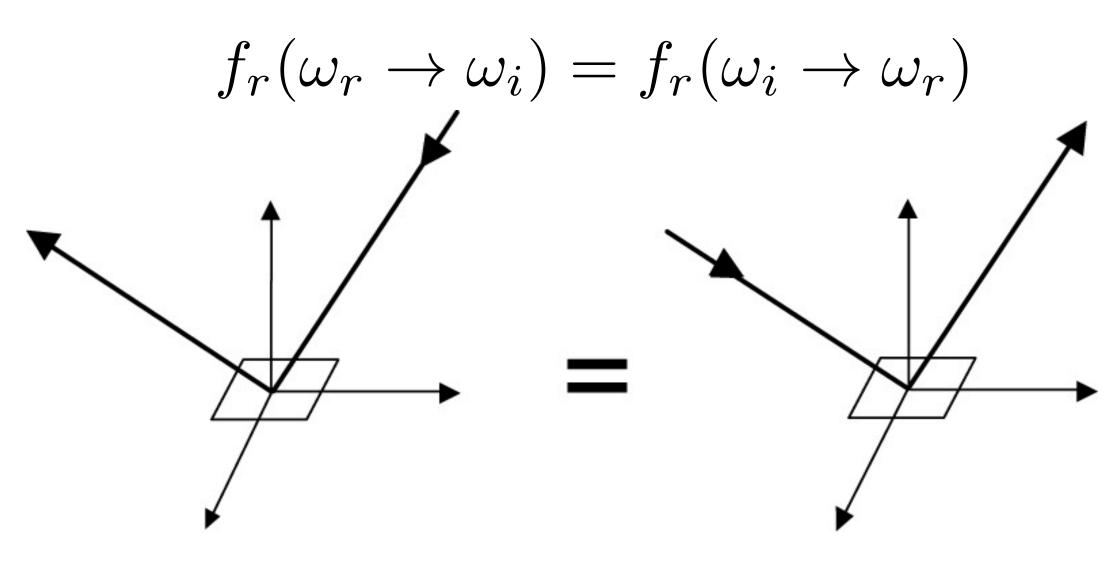
```
// Assume:
// Ray ray hits surface at point hit p
// Normal of surface at hit point is hit n
Vector3D wr = -ray.d; // outgoing direction
Spectrum Lr = 0.;
for (int i = 0; i < N; ++i) {
   Vector3D wi; // sample incident light from this direction
   float pdf; // p(wi)
   generate_sample(brdf, &wi, &pdf); // generate sample according to brdf
   Spectrum f = brdf->f(wr, wi);
   Spectrum Li = trace_ray(Ray(hit_p, wi)); // compute incoming Li
   Lr += f * Li * fabs(dot(wi, hit_n)) / pdf;
return Lr / N;
```

Properties of BRDFs

Linearity



Reciprocity principle



Properties of BRDFs

Isotropic vs. anisotropic

- If isotropic, $f_r(\theta_i, \phi_i; \theta_r, \phi_r) = f_r(\theta_i, \theta_r, \phi_r \phi_i)$
- Then, from reciprocity,

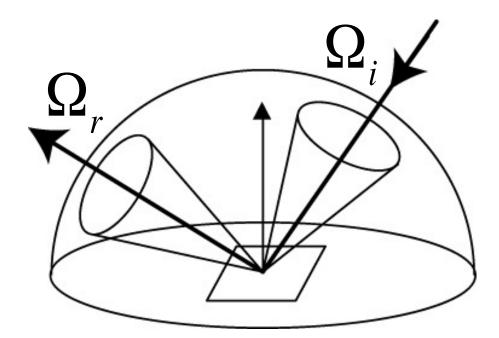
 $f_r(\theta_i, \theta_r, \phi_r - \phi_i) = f_r(\theta_r, \theta_i, \phi_i - \phi_r) = f_r(\theta_i, \theta_r, |\phi_r - \phi_i|)$

Energy conservation

$$f_r(\omega_i \to \omega_r) = \frac{\mathrm{d}L_r(\omega_i \to \omega_r)}{\mathrm{d}E_i} \quad \left[\frac{1}{\mathrm{sr}}\right]$$

Outgoing energy cannot exceed incoming energy (reflection does not create energy)

$$\frac{\mathrm{d}\Phi_r}{\mathrm{d}\Phi_i} = \frac{\int_{\Omega_r} L_r(\omega_r) \cos \theta_r \,\mathrm{d}\omega_r}{\int_{\Omega_i} L_i(\omega_i) \cos \theta_i \,\mathrm{d}\omega_i}$$
$$= \int_{\Omega_r} \int_{\Omega_i} \frac{f_r(\omega_i \to \omega_r) L_i(\omega_i) \cos \theta_i}{\int_{\Omega_i} L_i(\omega_i) \cos \theta_i}$$
$$\leq 1$$



$\frac{\theta_i \mathrm{d}\omega_i \cos \theta_r \,\mathrm{d}\omega_r}{\theta_i \,\mathrm{d}\omega_i}$

Energy conservation

Overall fraction of light reflected by surface (assuming constant incident light from all directions)

 $\rho = \frac{\int_{H^2} \int_{H^2} f_r(\omega_i \to \omega_r) C \cos \theta_i d\omega_i \cos \theta_r d\omega_r}{\int_{H^2} C \cos \theta_i d\omega_i}$ $= \frac{1}{\pi} \int_{\mathbf{H}^2} \int_{\mathbf{H}^2} f_r(\omega_i \to \omega_r) C \cos \theta_i \mathrm{d}\omega_i \cos \theta_r \,\mathrm{d}\omega_r$ < 1

Hemispherical incident radiance

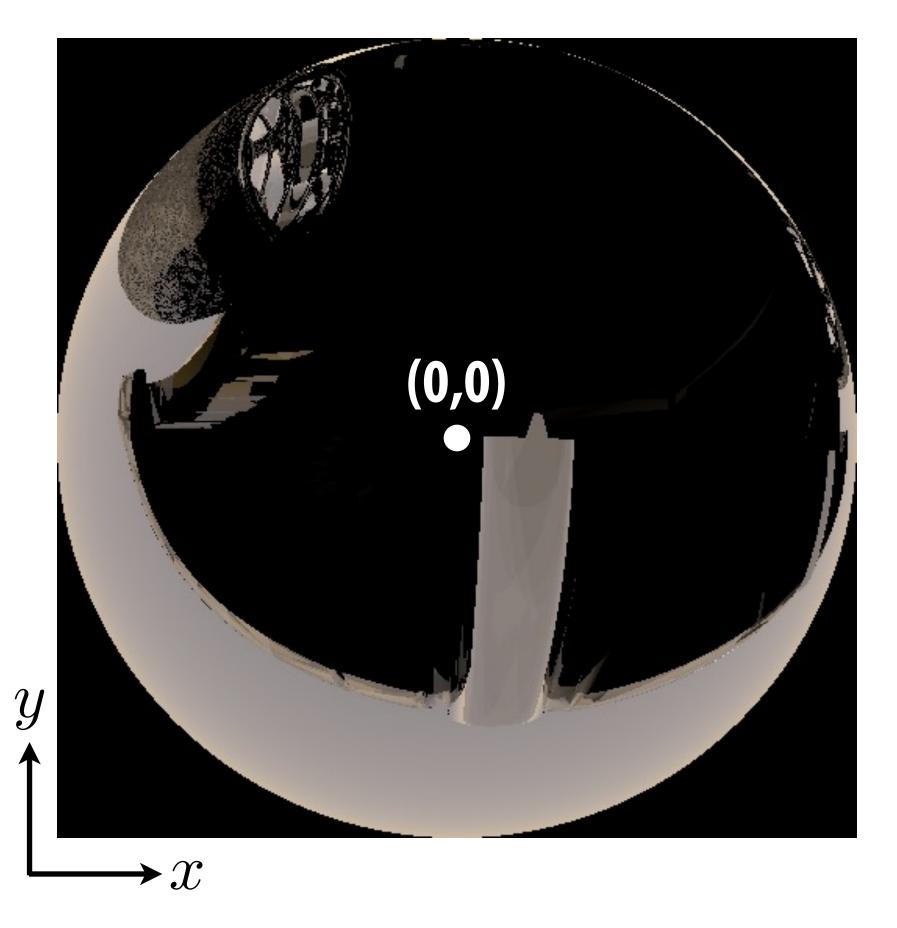
(1)

Consider view of hemisphere from this point



Hemispherical incident radiance

At any point on any surface in the scene, there's an incident radiance field that gives the directional distribution of illumination at the point





 $L_{i}(\omega) = L_{i}(x, y, \sqrt{1 - x^{2} - y^{2}})$

Ideal specular reflection



Incident radiance



Exitant radiance

Diffuse reflection



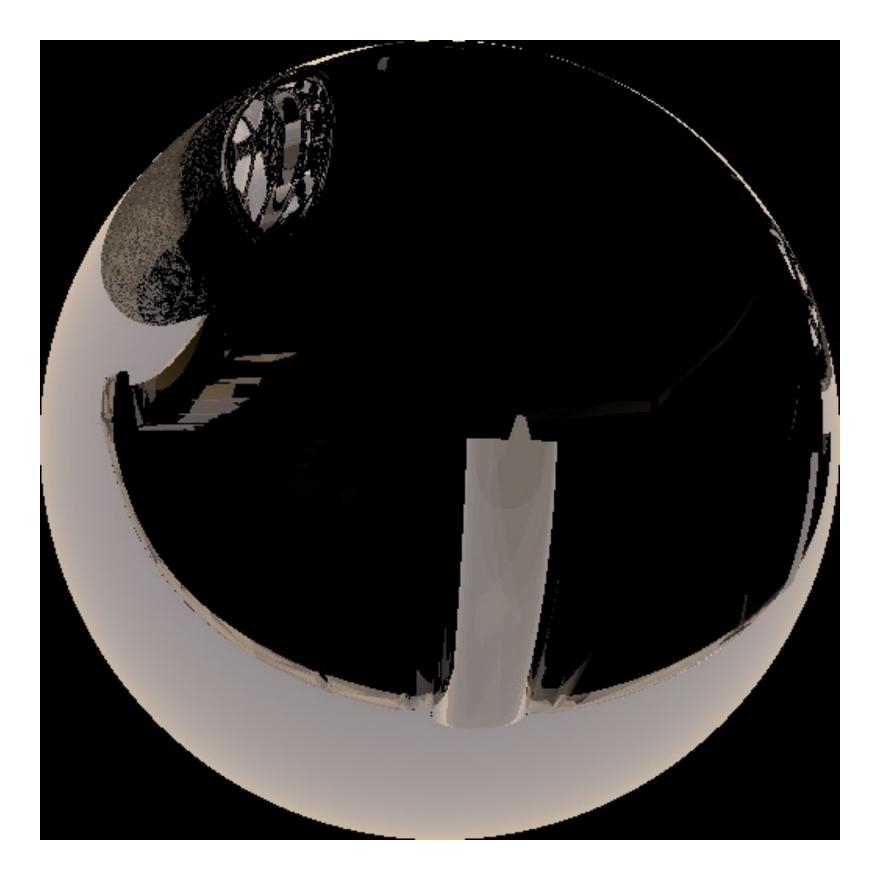
Incident radiance

Exitant radiance is the same in all directions



Exitant radiance

Plastic

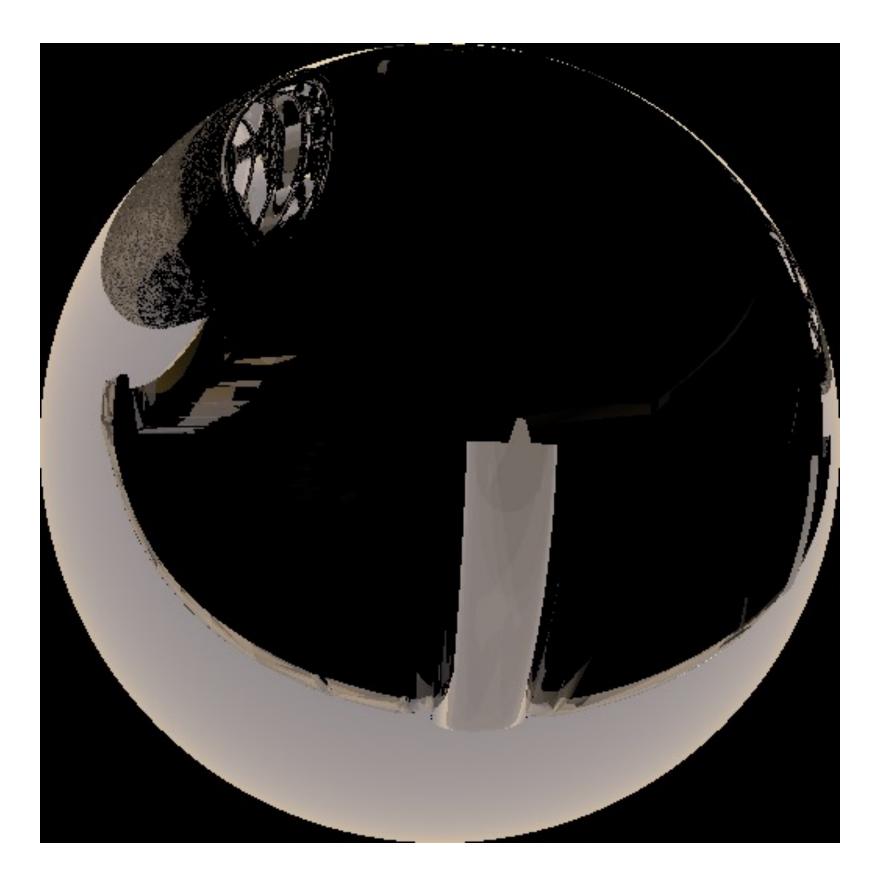






Exitant radiance

Copper

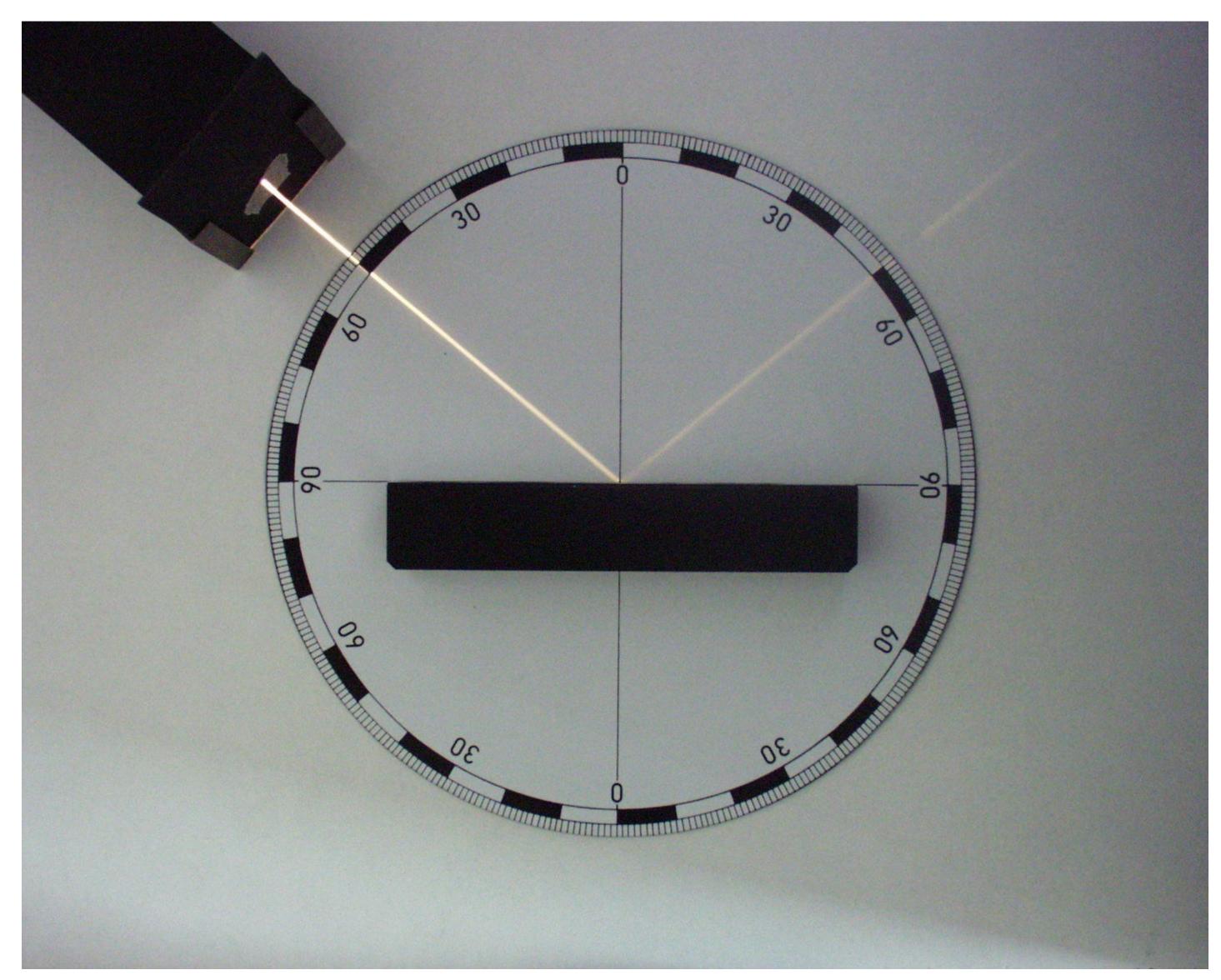


Incident radiance



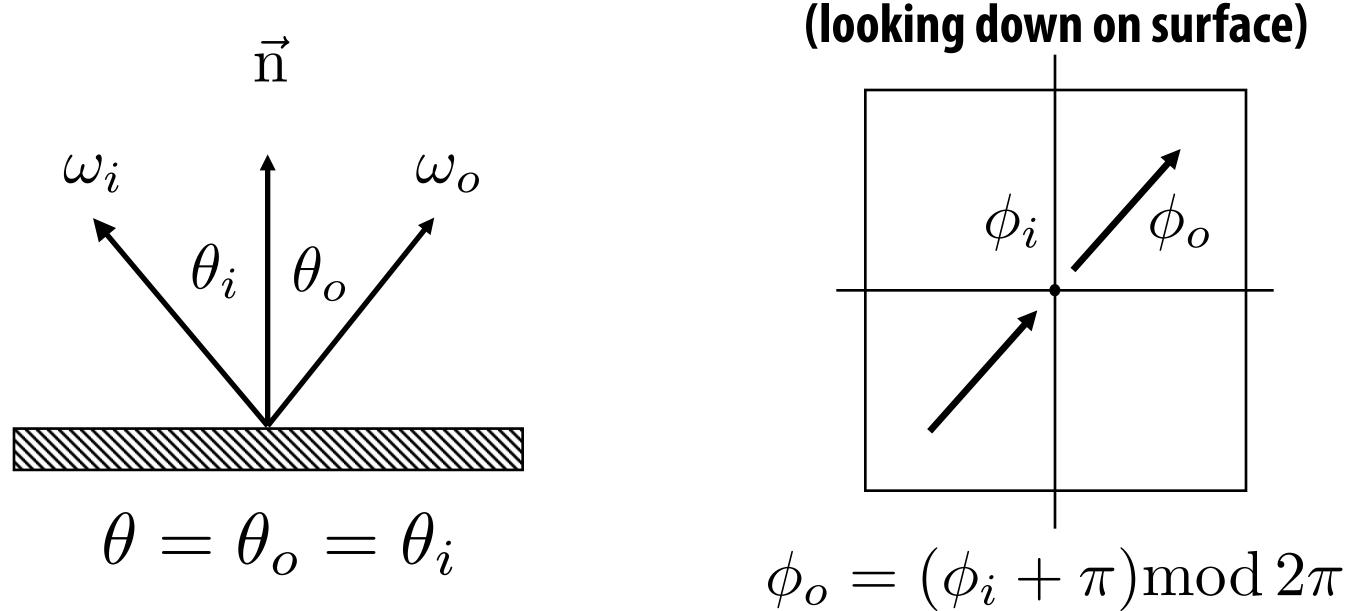
Exitant radiance

Perfect specular reflection



[Zátonyi Sándor]

Perfect specular reflection



 $\omega_o + \omega_i = 2\cos\theta \,\vec{\mathbf{n}} = 2(\omega_i \cdot \vec{\mathbf{n}})\vec{\mathbf{n}}$

 $\omega_o = -\omega_i + 2(\omega_i \cdot \vec{\mathbf{n}})\vec{\mathbf{n}}$

Top-down view ing down on surface)

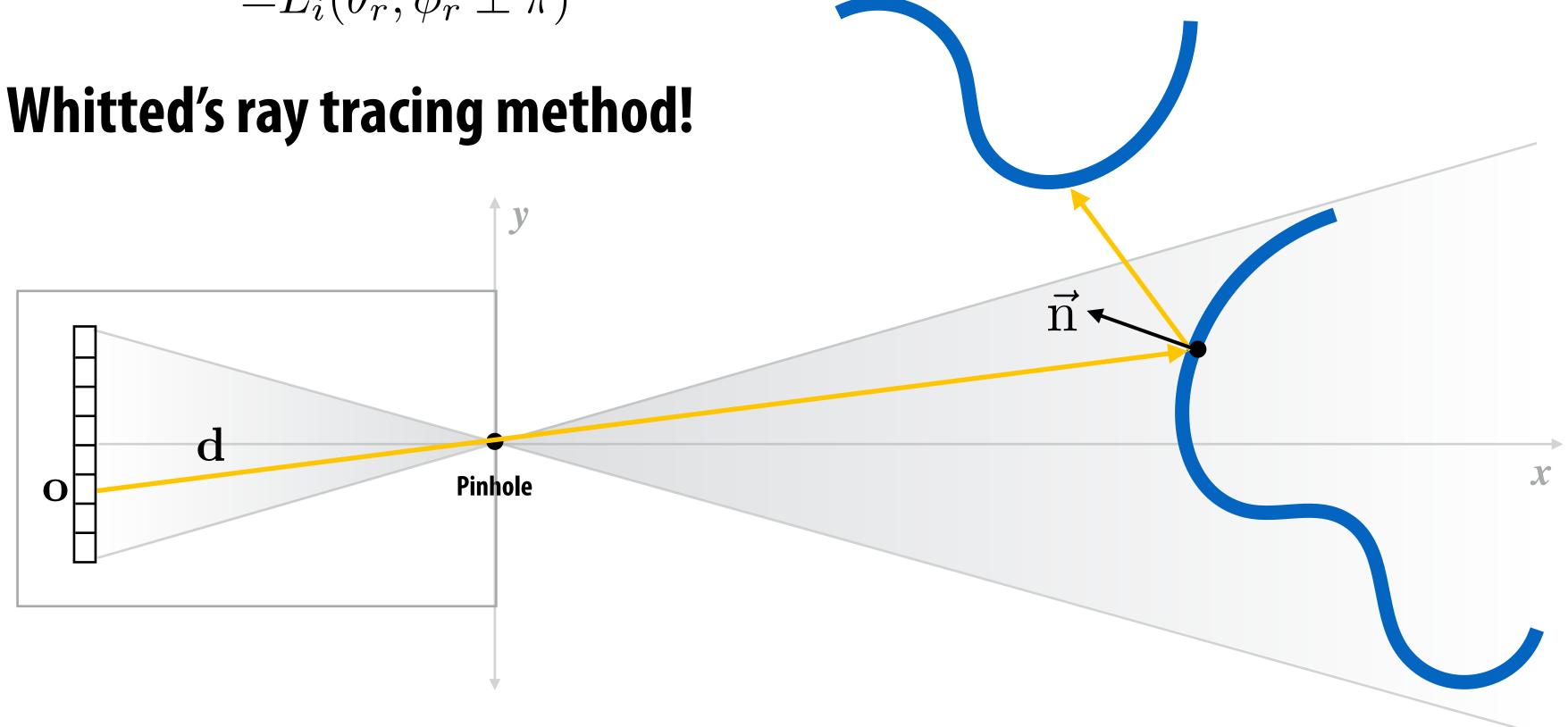
Specular reflection BRDF

 $L_{i}(\theta_{i},\phi_{i}) \qquad \qquad L_{o}(\theta_{o},\phi_{o}) \\ \theta_{i} \qquad \qquad \theta_{o} \qquad \qquad L_{o}(\theta_{o},\phi_{o}) = L_{i}(\theta_{o},\phi_{o}\pm\pi)$

 $f_r(\theta_i, \phi_i; \theta_o, \phi_o) = \frac{\delta(\cos \theta_i - \cos \theta_o)}{\cos \theta_i} \delta(\phi_i - \phi_o \pm \pi)$

Specular reflection and the reflection equation

$$L_o(\theta_o, \phi_o) = \int f_r(\theta_i, \phi_i; \theta_o, \phi_o) L_i(\theta_i, \phi_i) \cos \theta_i$$
$$= \int \frac{\delta(\cos \theta_i - \cos \theta_o)}{\cos \theta_i} \delta(\phi_i - \phi_o \pm \pi)$$
$$= L_i(\theta_r, \phi_r \pm \pi)$$



 $\theta_i \mathrm{d}\cos\theta_i \mathrm{d}\phi_i$

-) $L_i(\theta_i, \phi_i) \cos \theta_i d \cos \theta_i d\phi_i$

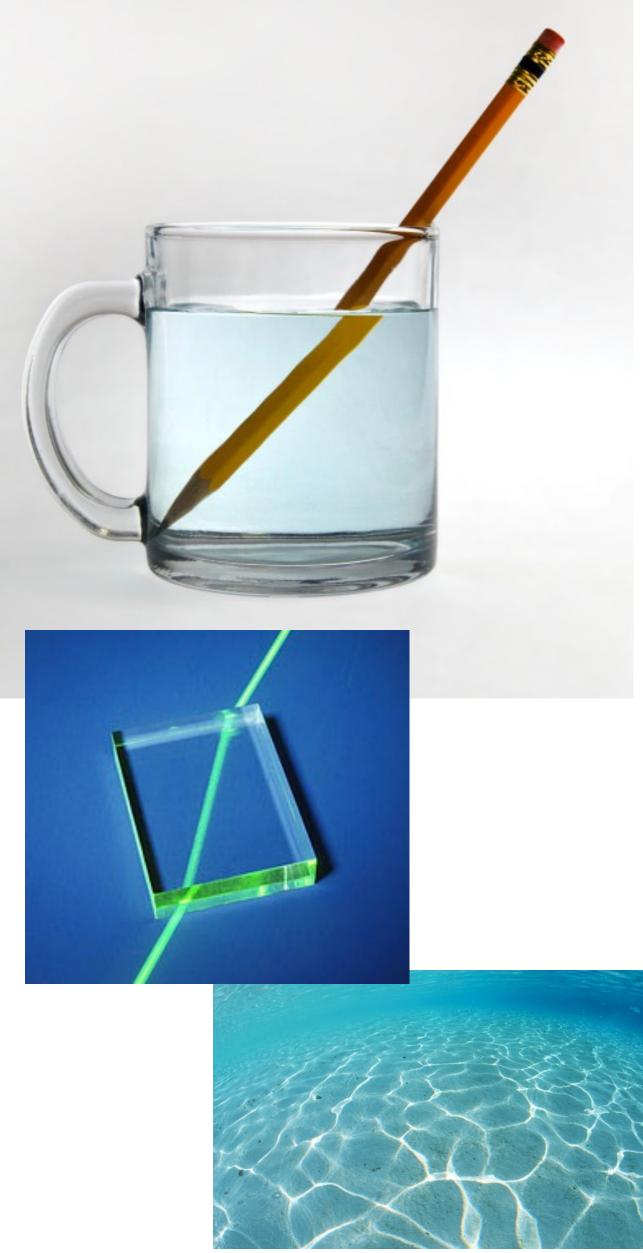
CMU 15-462/662, Fall 2015

Transmission

In addition to reflecting off surface, light may be transmitted through surface.

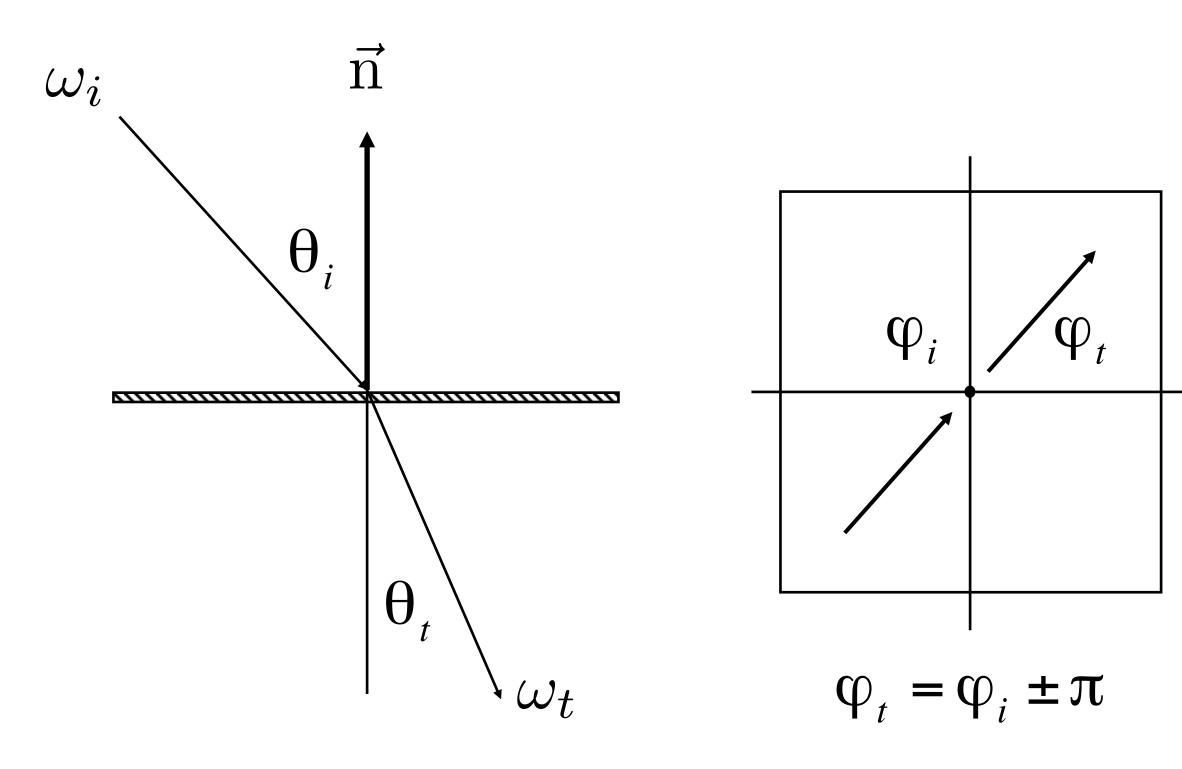
Light refracts when it enters a new medium.





Snell's Law

Transmitted angle depends on index of refraction of medium incident ray is in and index of refraction of medium light is entering.

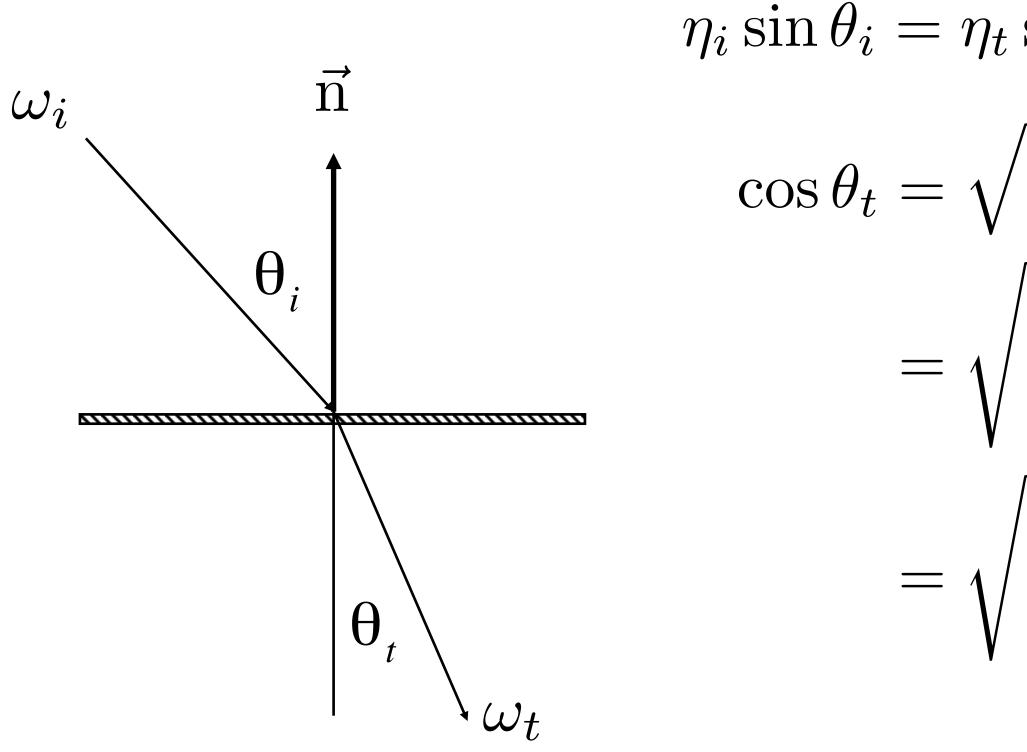


 $\eta_i \sin \theta_i = \eta_t \sin \theta_t$

Medium	η *
Vacuum	1.0
Air (sea level)	1.00029
Water (20°C)	1.333
Glass	1.5-1.6
Diamond	2.42

* index of refraction is wavelength dependent (these are averages)

Law of refraction



Total internal reflection:

When light is moving from a more optically dense medium to a less optically dense medium: $\frac{\eta_i}{-}>1$

Light incident on boundary from large enough angle will not exit medium.

$$\sin \theta_t$$

$$\overline{1 - \sin^2 \theta_t}$$

$$\overline{1 - \left(\frac{\eta_i}{\eta_t}\right)^2 \sin^2 \theta_i}$$

$$\overline{1 - \left(\frac{\eta_i}{\eta_t}\right)^2 (1 - \cos^2 \theta_i)}$$

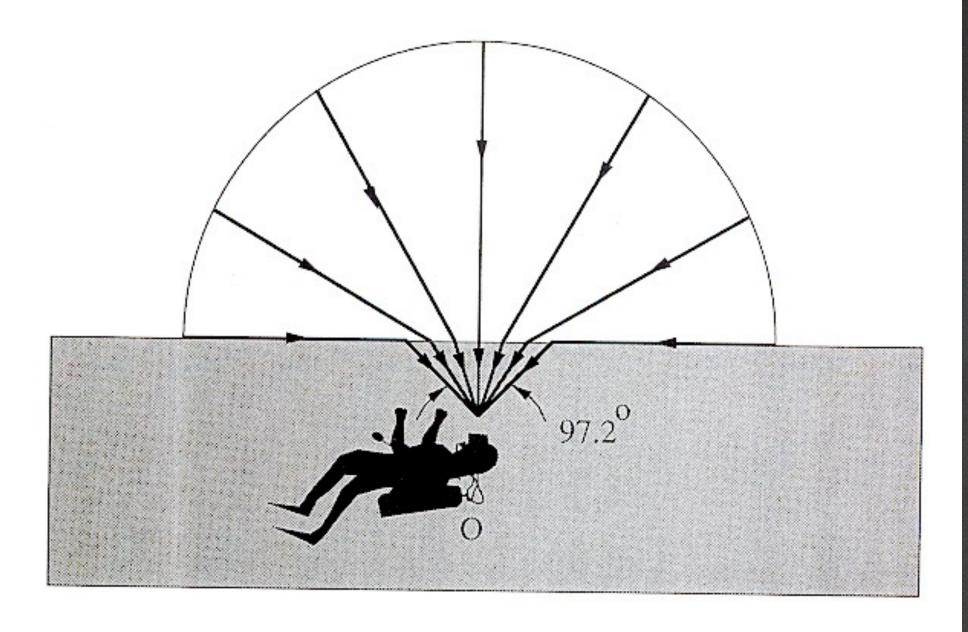
$$\left(\frac{\eta_i}{\eta_t}\right)^2 \left(1 - \cos^2 \theta_i\right) < 0$$

1 —

 η_t

Optical manhole

Total internal reflection





[Livingston and Lynch]

Fresnel reflection

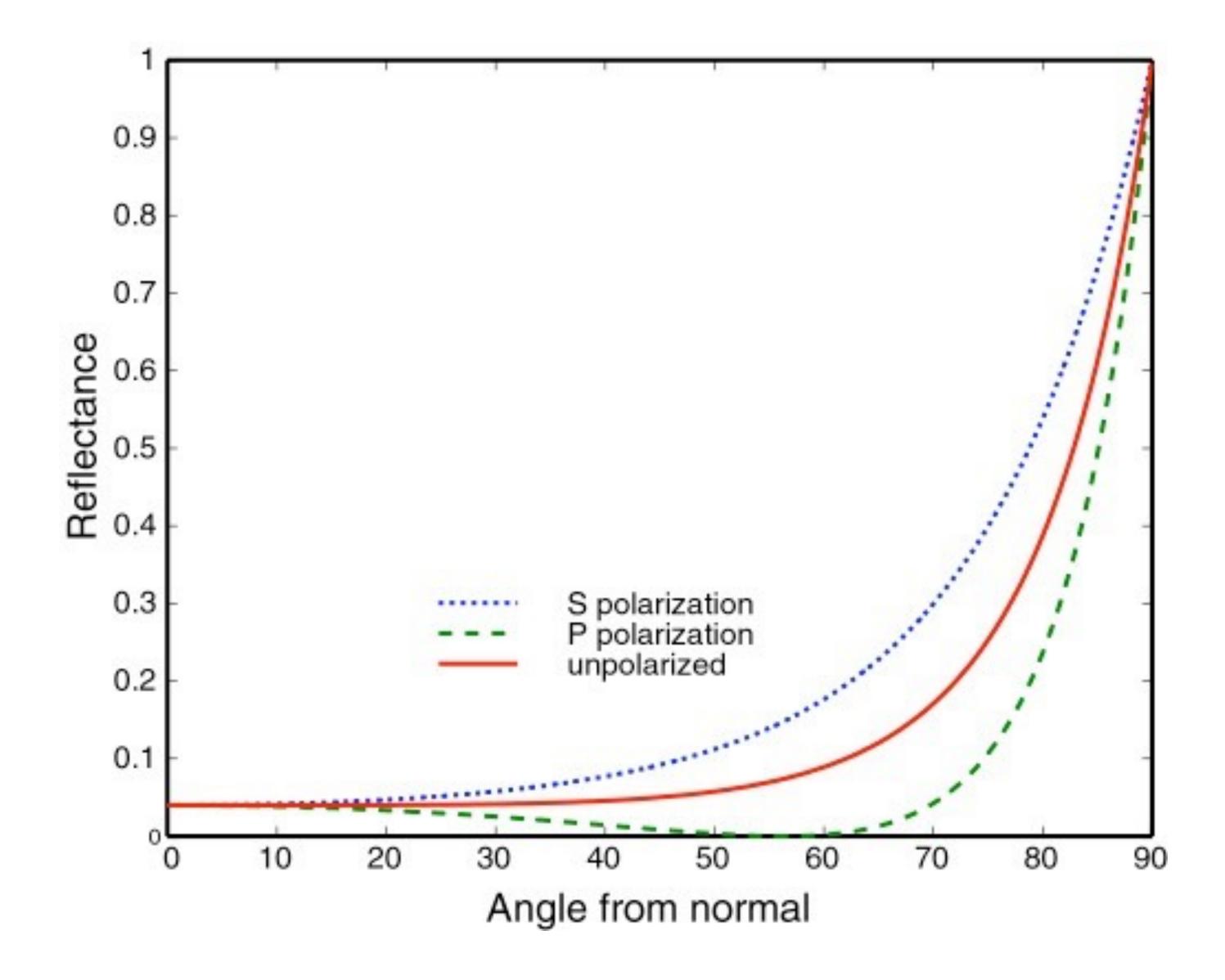
Reflectance depends on angle of incidence and polarization of light



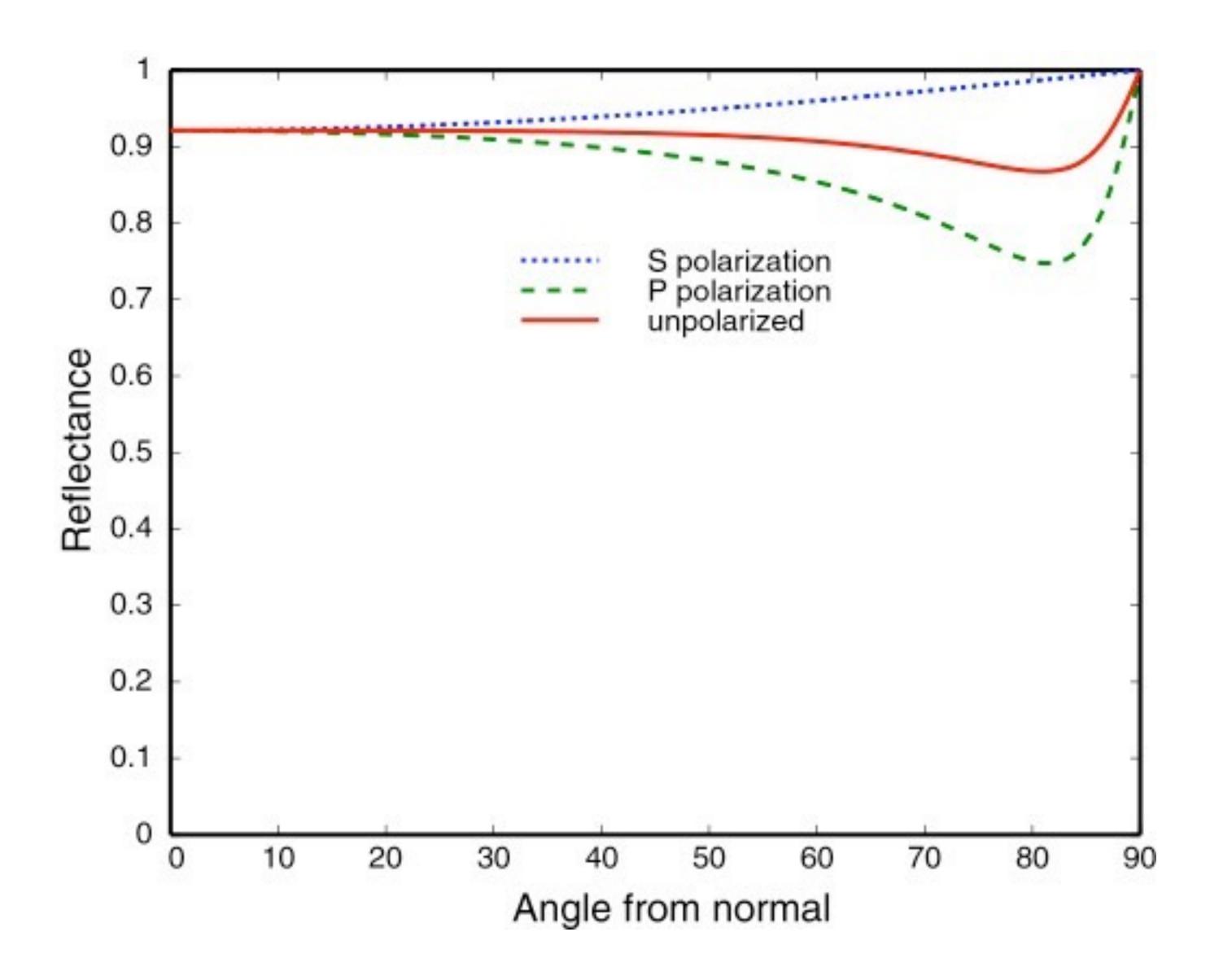
This example: reflectance increases with grazing angle

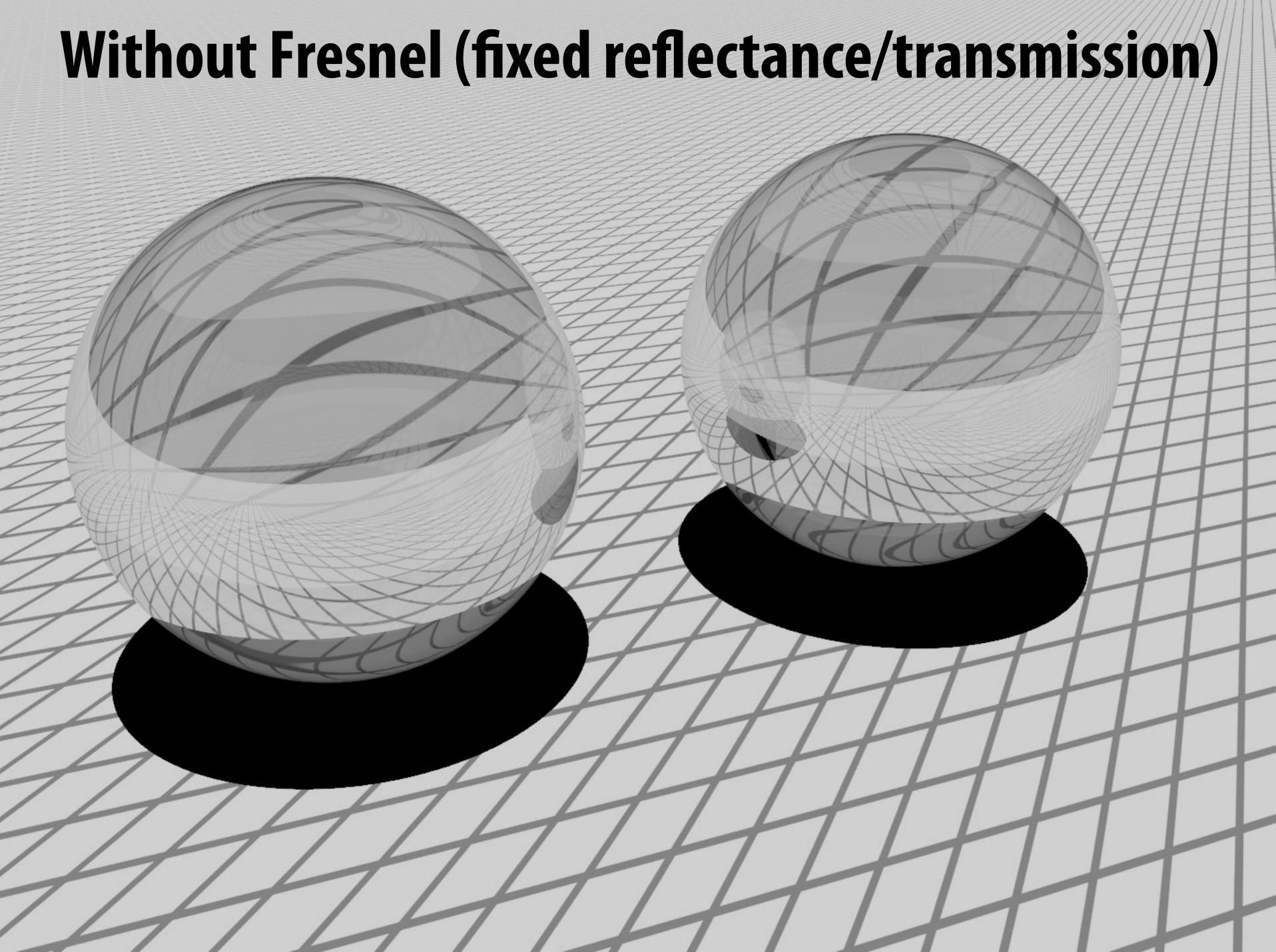
[Lafortune et al. 1997]

Fresnel reflection (dielectric, $\eta = 1.5$)



Fresnel reflectance (conductor)

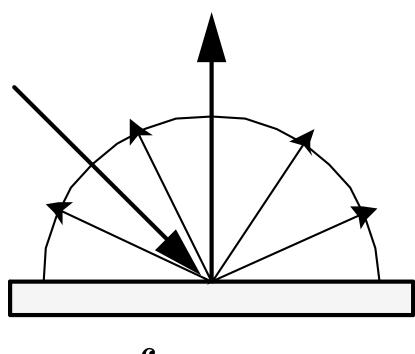




Glass with Fresnel reflection/transmission

Lambertian reflection

Assume light is equally likely to be reflected in each output direction



 $f_r = c$

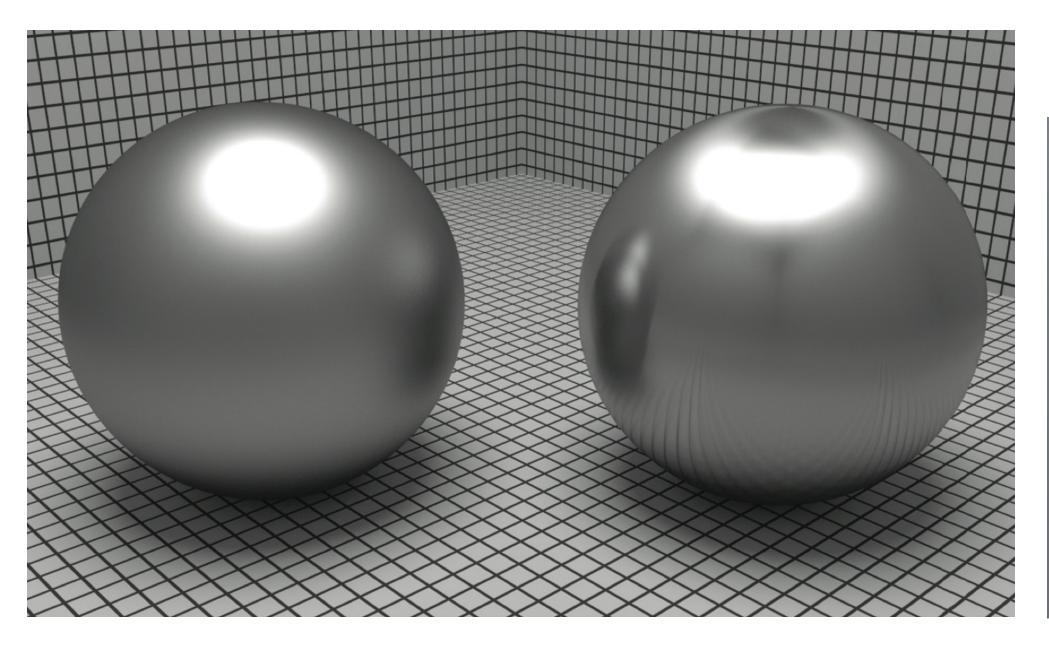
 $L_o(\omega_o) = \int_{H^2} f_r L_i(\omega_i) \cos \theta_i \,\mathrm{d}\omega_i$ $= f_r \int_{H^2} L_i(\omega_i) \, \cos \theta_i \, \mathrm{d}\omega_i$ $=f_r E$

 $f_r = -\frac{\rho}{r}$

Anisotropic reflection

Reflection depends on azimuthal angle ϕ

Results from oriented microstructure of surface e.g., brushed metal







Stanford CS348b, Spring 2014

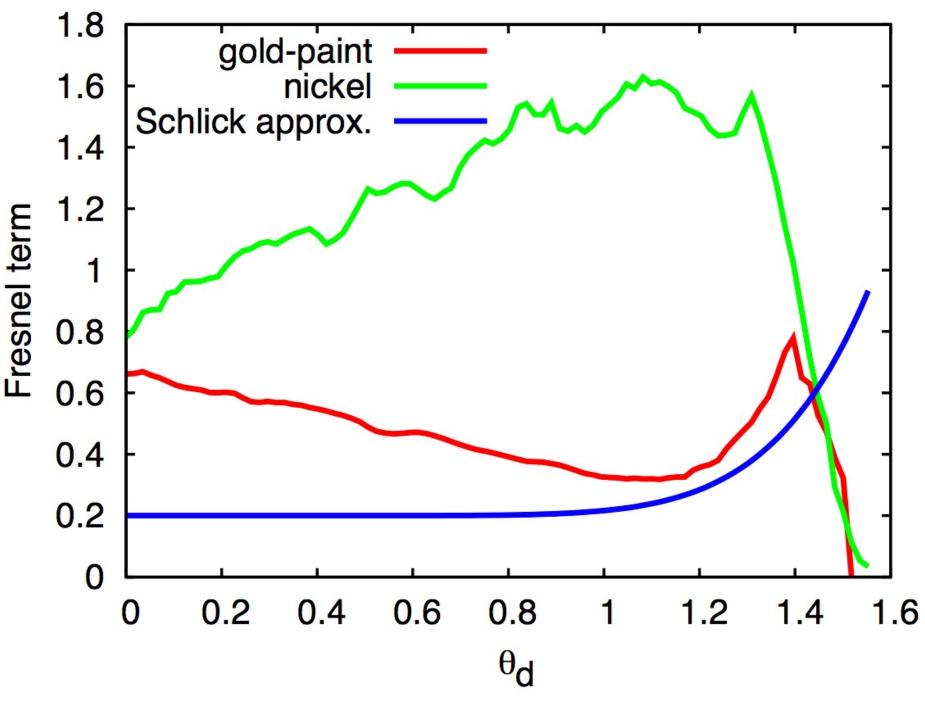
Measuring BRDFs

Stanford CS348b, Spring 2014

Measuring BRDFs: motivation

- Avoid need to develop / derive models
 - Automatically includes all of the scattering effects present
- Can accurately render with real-world materials
 - Useful for product design, special effects, ...
- **Theory vs. practice:**





Measuring BRDFs

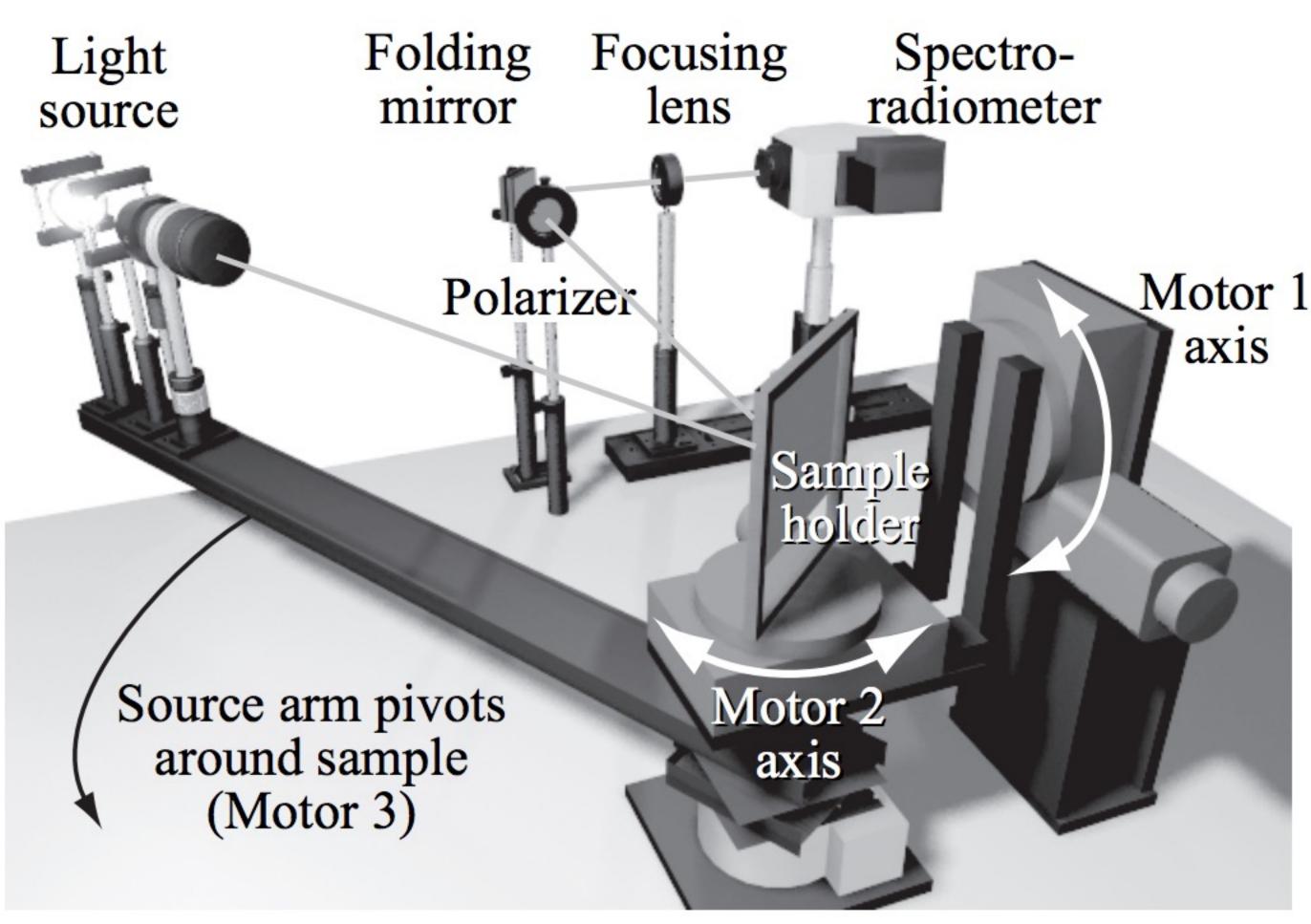
General approach:

foreach outgoing direction wo
move light to illuminate surface with a thin beam from wo
for each incoming direction wi
move sensor to be at direction wi from surface
measure incident radiance

- Improving efficiency:
 - Isotropic surfaces reduce dimensionality from 4D to 3D
 - Reciprocity reduces # of measurements by half
 - Clever optical systems...

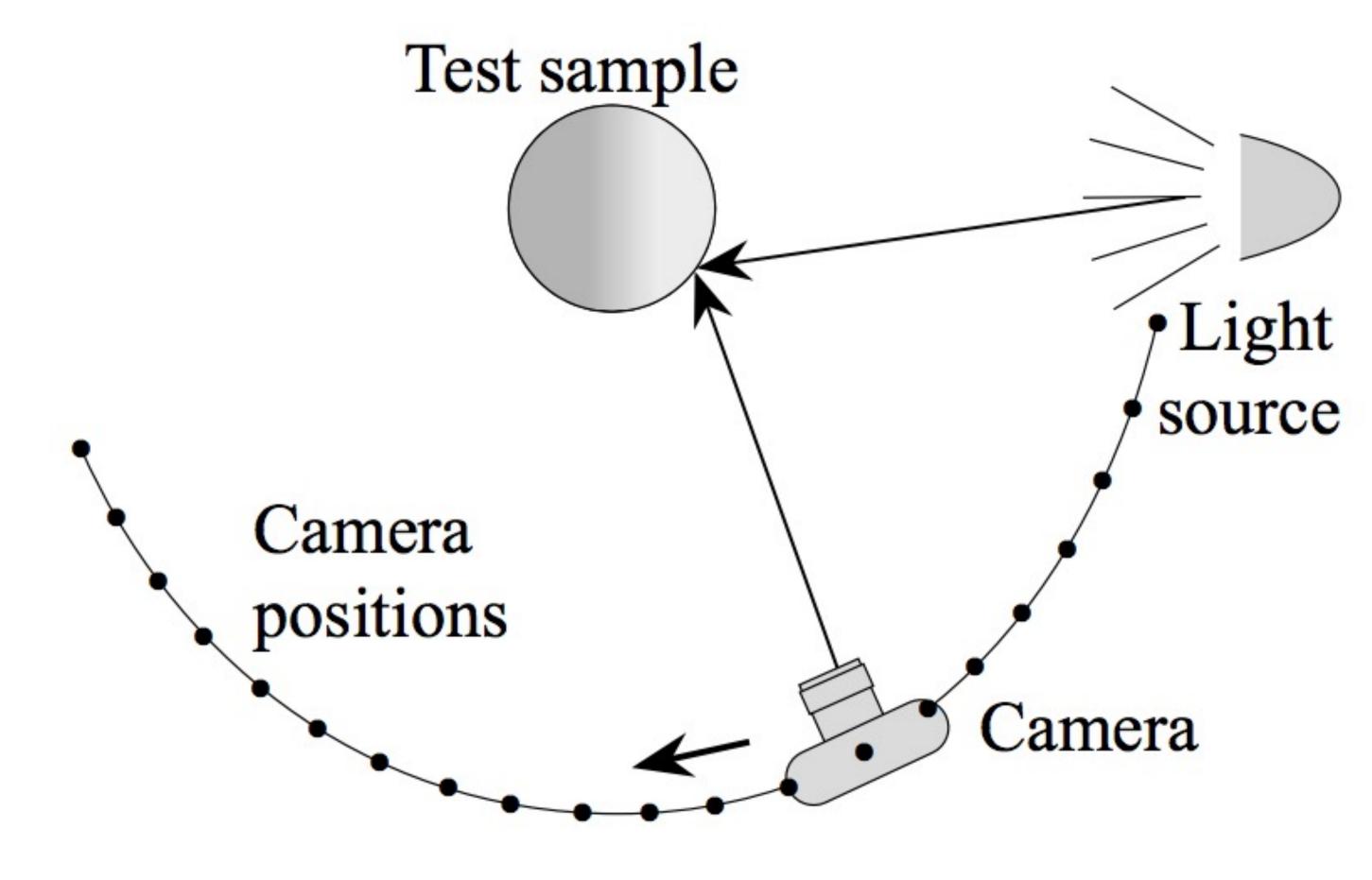
lity from 4D to 3D ts by half

Measuring BRDFs: gonioreflectometer



[Li et al. 2005]

Image-based BRDF measurement



[Marschner et al. 1999]

Challenges in measuring BRDFs

- Accurate measurements at grazing angles
 - Important due to Fresnel effects
- Measuring with dense enough sampling to capture high frequency specularities
- Retro-reflection
- Spatially-varying reflectance, ...

Representing measured BRDFs

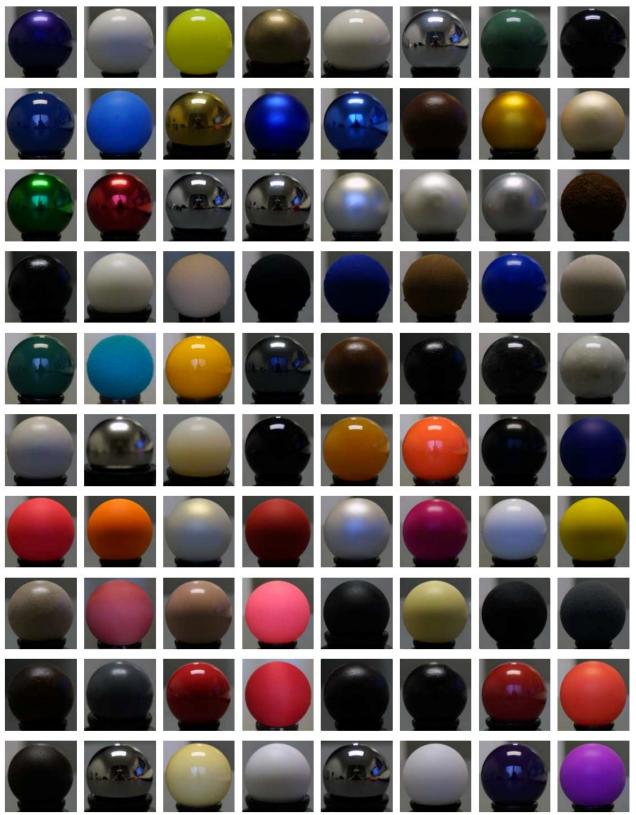
- **Desirable qualities**
 - Compact representation
 - Accurate representation of measured data
 - Efficient evaluation for arbitrary pairs of directions
 - Good distributions available for importance sampling



Tabular representation

- Store regularly-spaced samples in $(\theta_i, \theta_o, |\phi_i - \phi_o|)$
 - Better: reparameterize
 angles to better match
 specularities
- Generally need to resample measured values to table
- Very high storage requirements





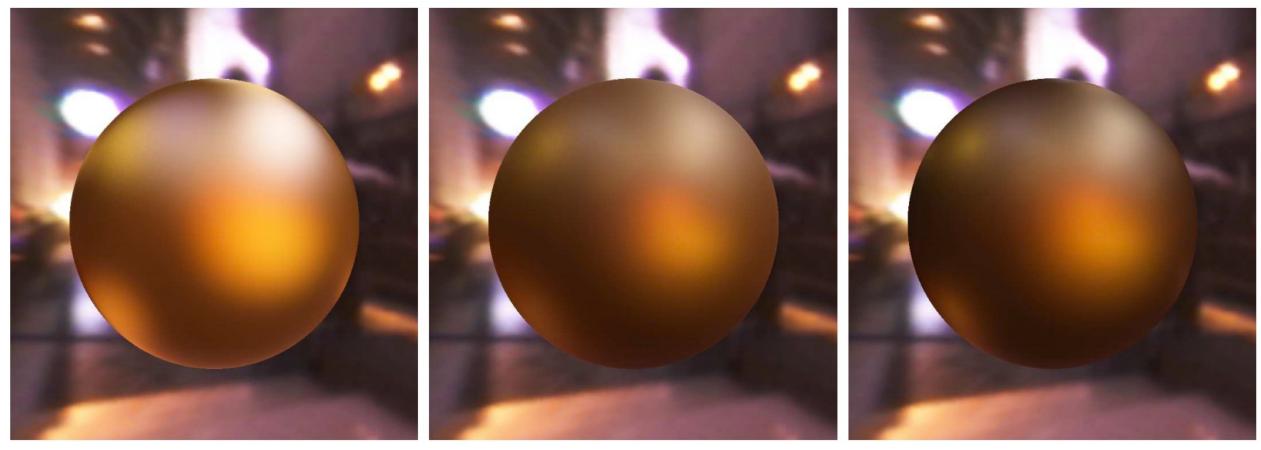
MERL BRDF Database [Matusik et al. 2004] 90*90*180 measurements

Basis functions

Can fit existing models, e.g. Cook-Torrance, 3 parameters per wavelength, k_d, k_s, k_e

 $f_r(\omega_i \to \omega_o) = k_d + k_s (\vec{\mathbf{h}} \cdot \vec{\mathbf{n}})^{k_e}$

More sophisticated, e.g. [Bagher et al. 2012] 11 parameter model:



(b) Beckmann distribution

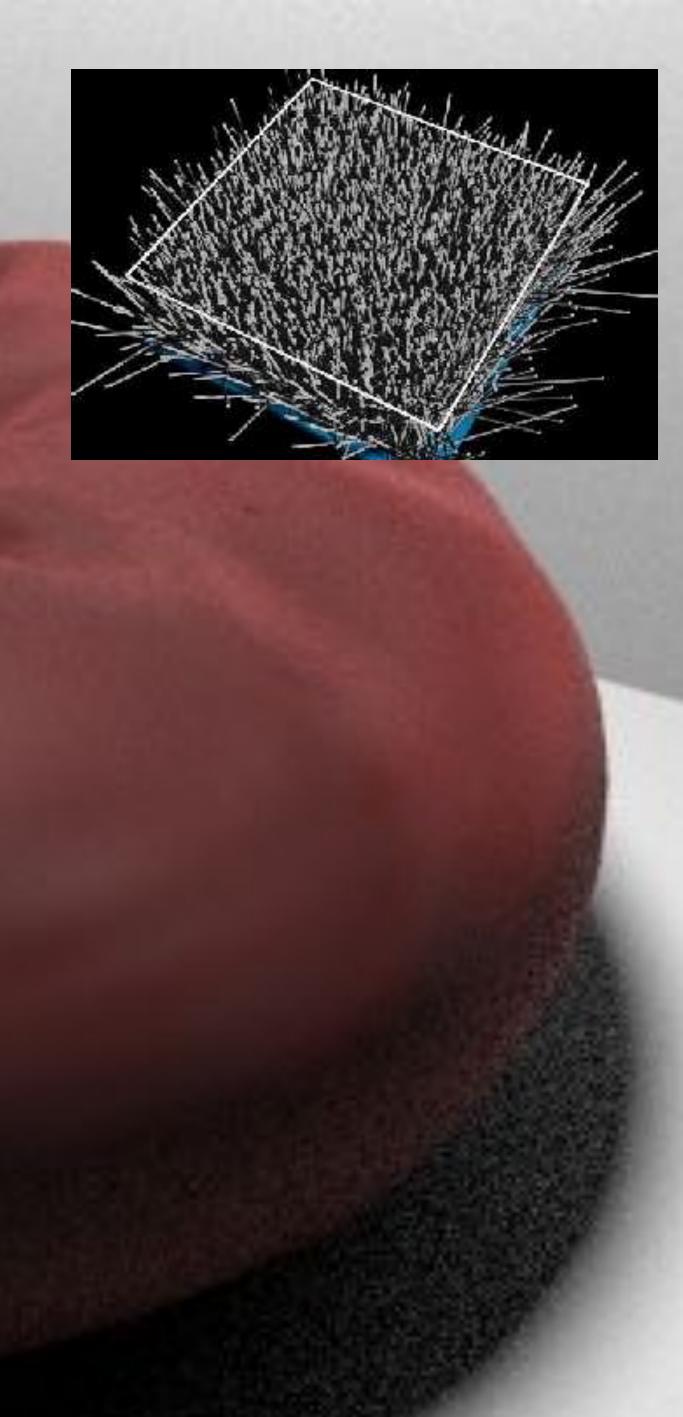
(c) Ground truth

$$\vec{\mathbf{h}} = \widehat{\omega_i + \omega_c}$$

(d) SGD distribution (ours)

Simulation: velvet

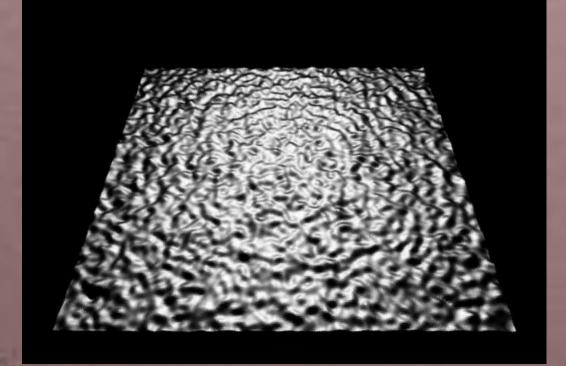
[Westin et al. 1992]



Simulation: brushed aluminum

[Westin et al. 1992]





Simulation: nylon

[Westin et al. 1992]



Translucent materials: Jade



Translucent materials: skin



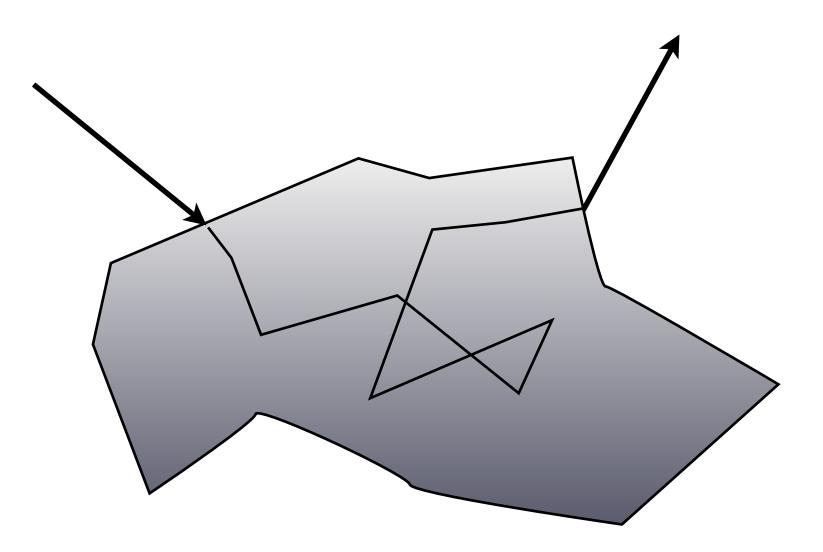
Translucent materials: leaves

S



Subsurface scattering

- Visual characteristics of many surfaces caused by light entering at different points than it exits
 - Violates a fundamental assumption of the BRDF





[Jensen et al 2001]



[Donner et al 2008]

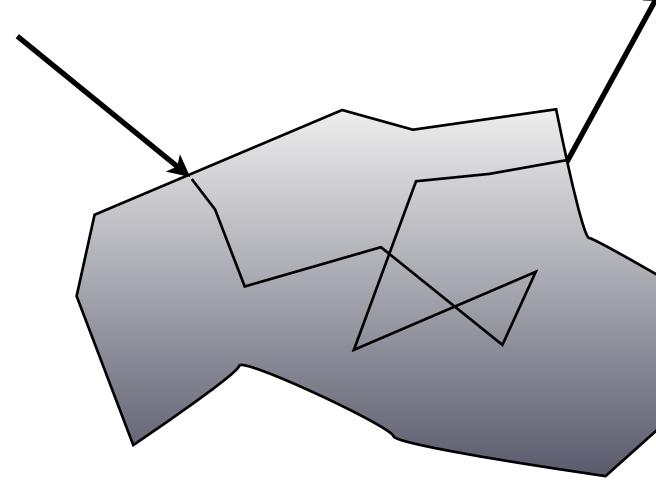
Scattering functions

Generalization of BRDF; describes exitant radiance at one point due to incident differential irradiance at another point:

$$S(x_i, \omega_i, x_o, \omega_o)$$

Generalization of reflection equation integrates over all points on the surface and all directions(!)

$$L(x_o, \omega_o) = \int_A \int_{H^2} S(x_i, \omega_i, x_o, \omega_o) L_a$$



 $(x_i, \omega_i) \cos \theta_i \, \mathrm{d}\omega_i \, \mathrm{d}A$

BRDF





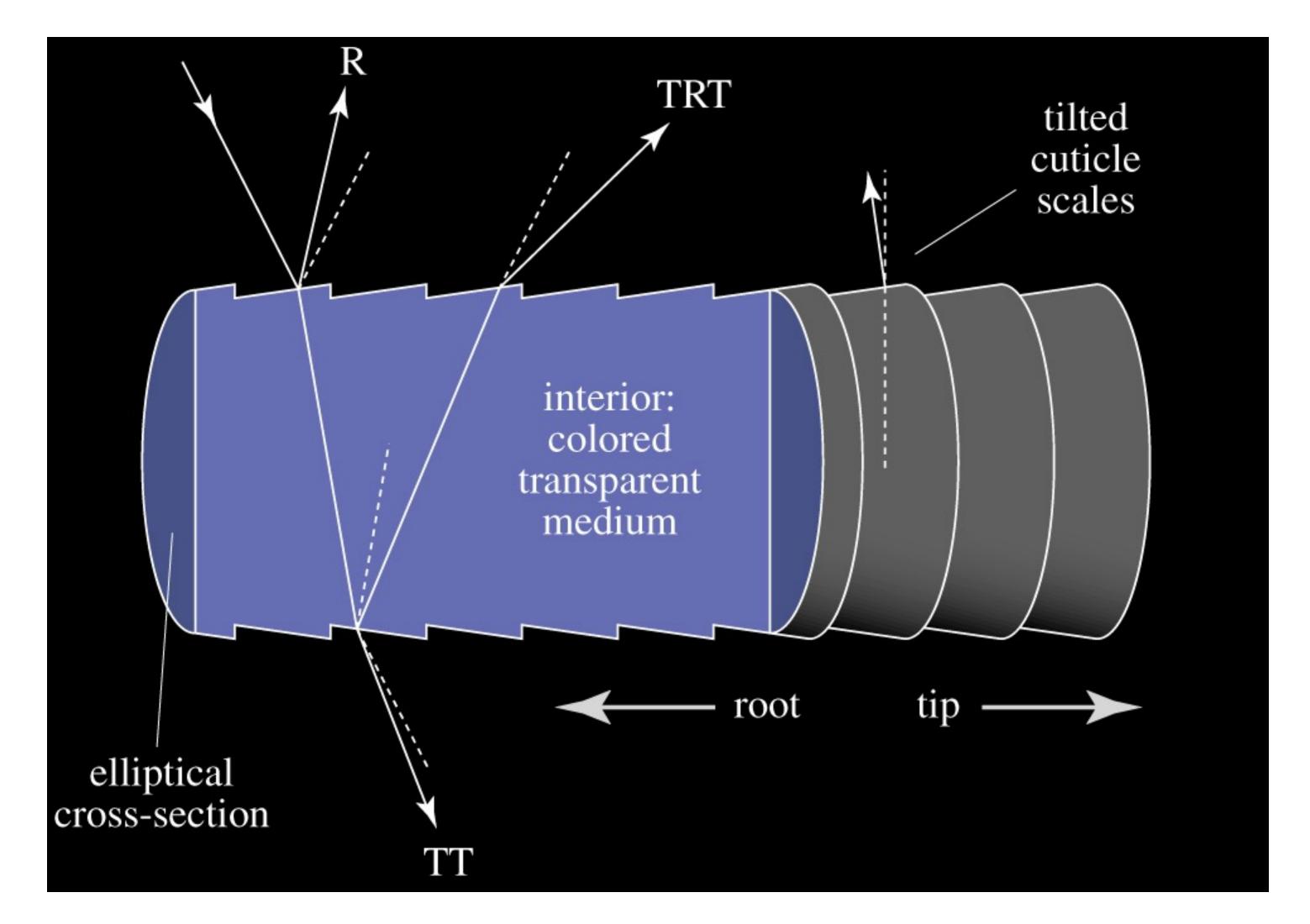
BSSRDF







Fiber model



[Marschner et al. 2003]

Hair appearance













Summary

- **BRDF describes how light reflects off a surface**
- **BRDF** defines the fraction of energy incident on surface from direction ω_i that is reflected in the direction ω_r

Light is also transmitted through surfaces

- Snell's Law gives angle of transmitted ray
- Amount of light reflected/transmitted is computed via Fresnel equations
- Can think of BTDF (bidirectional transmission distribution function) describing directional distribution of transmission

Subsurface scattering

Light exits surface at different point than it entered (e.g., skin)